GROUND STATE MASS CONCENTRATION IN THE
L^2-CRITICAL NONLINEAR SCHRÖDINGER EQUATION
BELOW H^1

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Abstract. We consider finite time blowup solutions of the L^2-critical cubic focusing nonlinear Schrödinger equation on R^2. Such functions, when in H^1, are known to concentrate a fixed L^2-mass (the mass of the ground state) at the point of blowup. Blowup solutions from initial data that is only in L^2 are known to concentrate at least a small amount of mass. In this paper we consider the intermediate case of blowup solutions from initial data in H^s, with 1 > s > s_Q, where s_Q = \frac{1}{5} + \frac{1}{5} \sqrt{11}. Our main result is that such solutions, when radially symmetric, concentrate at least the mass of the ground state at the origin at blowup time.

1. Introduction

Special interest has recently been devoted to the existence and long-time behavior of solutions with low regularity to nonlinear Schrödinger equations. These questions were mainly investigated for defocusing\(^1\) equations with a global-in-time a priori H^1 upper bound [1] [6] [22] [7]. In this article, we are interested in a detailed description of rough solutions, with regularity below the H^1 energy threshold, which blow up in a finite time.

We consider the initial value problem for the two-dimensional, cubic, focusing nonlinear Schrödinger (NLS) equation:

\begin{equation}
\begin{cases}
  iu_t + \Delta u + |u|^2 u = 0, \\
  u(0, x) = u_0(x), \\
  x \in \mathbb{R}^2,
\end{cases}
\end{equation}

which is L^2-critical. This refers to the property that both the equation and the L^2-norm of the solution are invariant under the scaling transformation u(t, x) \rightarrow u_\lambda(t, x) = \lambda u(\lambda^2 t, \lambda x). This problem is locally well-posed\(^2\) for initial data in H^s

\(^{1}\)Low regularity global well-posedness results have also been obtained for other Hamiltonian evolution equations. Orbital instability properties of solitons subject to rough perturbations for focusing NLS equations have been studied as well [8], [9].

\(^{2}\)For s = 0, the size of the interval of existence depends upon the initial profile u_0 [3]; for s > 0, the H^s norm of the data determines the size of the existence interval.
with \( s \geq 0 \) \[4\]. We recall that the following quantities, if finite, are conserved:

\[
\text{Mass} = M[u(t)] = \|u(t)\|_{L^2}^2, \\
\text{Energy} = E[u(t)] = \frac{1}{2}\|\nabla u(t)\|_{L^2}^2 - \frac{1}{4}\|u(t)\|_{L^4}^4.
\]

We will frequently refer to \(\frac{1}{2}\|\nabla u(t)\|_{L^2}^2\) as the kinetic energy of the solution, and \(E[u(t)]\) as the total energy.

It is known that there exist explicit finite time blowup solutions to (1.1); for sufficiently smooth and decaying initial data, the virial identity provides a sufficient condition guaranteeing that finite time blowup occurs. For a solution which blows up in finite time, let \([0, T^*)\) be the maximal (forward) time interval of existence.

A specific property of critical collapse is the phenomenon of mass concentration, often referred to in the physical literature as strong collapse \[25\] (see also \[18\] for a review): \(H^1\)-solutions concentrate a finite amount of mass in a neighborhood of the focus of width slightly larger than \((T^* - t)^{1/2}\). Heuristic arguments suggest that this phenomenon does not occur in supercritical nonlinear Schrödinger blowup. For \(H^1\)-solutions of (1.1), there is a precise lower bound on the amount of concentrated mass, namely the mass of the ground state \(Q\) \[21\], \[16\], where \(Q\) is the unique positive solution (up to translations) of

\[
\Delta w - w + |w|^2w = 0.
\]

In addition to the scaling properties of the NLS equation, the main ingredients in the proof that \(H^1\) blowup solutions concentrate at least the mass of the ground state are: (i) the conservation of the energy, (ii) a precise Gagliardo-Nirenberg inequality \[23\] which implies that nonzero \(H^1\)-functions of non-positive energy have at least ground state mass.

The purpose of this work is to address the phenomenon of mass concentration in the spaces \(H^s, s < 1\), where the conservation of energy cannot be used. In the setting of merely \(L^2\) initial data, if global well-posedness fails to hold for (1.1) \((i.e. T^* < \infty)\), then a nontrivial parabolic concentration of \(L^2\)-mass occurs \[1\] as \(t \uparrow T^*\):

\[
\limsup_{t \uparrow T^*} \sup_{\text{cubes } I \subset \mathbb{R}^2} \left( \frac{1}{\text{side}(I)} \int_I |u(t, x)|^2 dx \right)^\frac{1}{2} \geq \eta(\|u_0\|_{L^2}) > 0.
\]

Unlike the \(H^1\)-case, there is no explicit quantification on the lower bound.

A natural question\(^3\), highlighted in \[15\], is to determine whether tiny \(L^2\)-mass concentrations can occur when \(u_0 \in L^2\). The conjectured answer is no. Solutions of (1.1) with a finite maximal (forward) existence interval are expected to concentrate at least the \(L^2\)-mass of the ground state. Our main result corroborates this expectation, at least for \(H^s\)-solutions with \(s\) just below 1.

\(^3\)The fact that the lower bound in (1.3) may be taken to be a fixed constant \(\delta_0\) independent of the initial size in \(L^2\) has recently been announced \[13\].
Theorem 1.1. There exists \( s_Q = \frac{1}{5} + \frac{1}{5} \sqrt{11} \) such that the following is true for any \( s > s_Q \). Suppose \( H^s \ni u_0 \mapsto u(t) \) solves (1.1) on the maximal (forward) time interval \([0, T^*)\), with \( T^* < \infty \). Moreover, assume that \( u_0 \) is radially symmetric. Then for any positive \( \gamma(z) \uparrow \infty \) arbitrarily slowly as \( z \downarrow 0 \) we have

\[
\limsup_{t \uparrow T^*} \|u\|_{L^2}^2 \geq \|Q\|_{L^2}^2.
\]

(1.4)

The proof consists of an imitation of the \( H^1 \) argument (as presented in [2]) with the energy, which is infinite in the \( H^s \)-setting, replaced by a modified energy introduced in [6]. The idea is to apply to the \( H^s \)-solution a smoothing operator to make it \( H^1 \) and define the usual energy of this new object. The crucial point here is to prove that the modified total energy grows more slowly than the modified kinetic energy. In Section 2, we prove Theorem 1.1 assuming Proposition 2.1 and Corollary 3.6 stated below. Proposition 2.1 contains a key upper bound for the modified energy in terms of the \( H^s \)-norm of the solution. Its proof, which relies upon the local-in-time theory developed in Section 3, is postponed to Section 4.

Remark 1.2. As mentioned above, the expectation is that parabolic concentration of at least the ground state mass holds true even for \( L^2 \) initial data. However, the analysis showing that the modified total energy grows more slowly than the modified kinetic energy (quantified by the statement that \( p(s) < 2 \) in Proposition 2.1), requires taking \( s \) close to 1. Also, note that the concentration width \((T^* - t)^{s/2+}\) obtained in (1.4) is much larger than \((T^* - t)^{1/2+}\) within which ground state mass concentration is expected to occur.

Remark 1.3. The two-dimensional nature of the analysis only appears directly in the use of the Sobolev inequality in the proof of Lemma 3.9. In higher dimensions the power of the nonlinearity of the \( L^2 \)-critical problem is non-integer, which would make the multilinear analysis of the modified energy more technical.

Remark 1.4. Our methods only enable us to control the modified energy at time \( t \) by the supremum up to time \( t \) of the modified kinetic energy. This is the source of the lim sup in Theorem 1.1, which does not appear in the \( H^1 \) result in [21]. Because there is no known upper bound for the rate of blowup of the \( H^s \) norm, we are unable to control the relationship between times at which the blowup is occurring maximally and those where it is occurring minimally. Any such result would, in addition to its inherent interest, allow us to strengthen our result to one with a \( \lim \inf \). For further discussion of the monotonicity of the blowup, but in the context of the critical generalized KdV equation, see pp. 621–623 of [14].

Remark 1.5. We use \( C \) to denote constants which do not depend on the crucial parameters and variables. Such constants will not depend on the high-frequency cut-off parameter (denoted \( N \)) or the time \( t \), but may depend on \( s, T^* \), or \( \|u_0\|_{H^s} \).

\(^4\)The non-radial case is amenable to treatment by employing the methods of compensated compactness as used in [24], [17] (see also [2]).
In the proof of Theorem 1.1, nowhere do we make the hypothesis that \( \|u_0\|_{L^2} \geq \|Q\|_{L^2} \). Thus, since solutions conserve mass and the concentration is shown to be in excess of the ground state mass, we prove the following corollary about the global well-posedness of (1.1).

**Corollary 1.6.** There exists \( s_Q \leq \frac{1}{5} + \frac{1}{5}\sqrt{11} \) such that, if \( u_0 \in H^s \), \( s > s_Q \) is radially symmetric and \( \|u_0\|_{L^2} < \|Q\|_{L^2} \) then the initial value problem (1.1) is globally well-posed.

**Remark 1.7.** A statement stronger than Corollary 1.6 may be inferred from earlier work. The analysis in [6] of the defocusing analog of (1.1) relies upon the local well-posedness theory and two other inputs: the almost conservation of the modified energy (Proposition 3.1 of [6]) and the obvious fact that, in the defocusing case, the modified total energy controls the modified kinetic energy. The almost conservation property depends upon the local-in-time space-time boundedness properties of the solution and also holds in the focusing case. Since the smoothing operator \( I_N \) (see (2.1) below) shrinks the \( L^2 \) size of functions, it can be shown that the modified total energy does indeed control the modified kinetic energy provided that the initial data satisfies the smallness condition \( \|u_0\|_{L^2} < \|Q\|_{L^2} \). Thus, Corollary 1.6 actually holds without the radial symmetry restriction and for \( s > \frac{4}{7} \).

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2. Mass Concentration

We wish to find a replacement for energy conservation. To do so, we define, for \( s < 1 \), the smoothing operators \( I_N : H^s \rightarrow H^1 \) used in [6]:

\[
I_N u(\xi) = m(\xi) \hat{u}(\xi)
\]

where

\[
m(\xi) = \begin{cases} 
1, & |\xi| \leq N \\
\left(\frac{|\xi|}{N}\right)^{s-1}, & |\xi| > 3N
\end{cases}
\]

with \( m(\xi) \) smooth, radial, and monotone in \( |\xi| \). For \( s \geq 1 \), we will take \( m(\xi) = 1 \). Note that we will sometimes drop the subscript \( N \) when that will not lead to confusion. The following properties of \( I_N \) are easily verified:

\[
\|I_N u\|_{L^2} \leq \|u\|_{L^2} \\
\|u\|_{H^s} \leq \|I_N \langle D \rangle u\|_{L^2} \leq N^{1-s} \|u\|_{H^s},
\]

where \( \langle D \rangle \) is the multiplier operator with symbol \( (1 + |\xi|^2)^{1/2} \). We define the **blowup parameters** associated to the \( H^s \)-norm of the solution

\[
\lambda(t) = \|u(t)\|_{H^s}
\]
and
\[ \Lambda(t) = \sup_{0 \leq \tau \leq t} \lambda(\tau). \]

We also define the modified blowup parameters
\[ \sigma(t) = \| I_N(D)u(t) \|_{L^2} \]
and
\[ \Sigma(t) = \sup_{0 \leq \tau \leq t} \sigma(\tau). \]

For finite time blowup solutions \( u \), the blowup parameters \( \sigma(t) \) and \( \lambda(t) \) tend to \( \infty \) as \( t \to T^* \), and can be compared using (2.3).

We will exploit the freedom to choose \( N \) very large. Indeed, for fixed \( T < T^* \), we will show that \( N = N(T) \) may be chosen so large that the modified energy \( E[I_Nu(T)] \) is much smaller than the modified kinetic energy \( \| I_N\nabla u(T) \|_{L^2}^2 \).

**Proposition 2.1.** There exists \( s_Q \leq \frac{1}{5} + \frac{1}{5} \sqrt{11} \) such that for all \( s > s_Q \) there exists \( p(s) < 2 \) with the following holding true: If \( H^s \ni u_0 \mapsto u(t) \) solves (1.1) on a maximal (forward) finite existence interval \( [0, T^*) \) then for all \( T < T^* \) there exists \( N = N(T) \) such that
\[ |E[I_{N(T)}u(T)]| \leq C_0(\Lambda(T))^{p(s)} \]
with \( C_0 = C_0(s, T^*, \| u_0 \|_{H^s}) \). Moreover, \( N(T) = C(\Lambda(T))^{\frac{p(s)}{2(1-s)}} \).

**Remark 2.2.** For \( s \geq 1 \) we may set \( p = 0 \) since \( I_N \) is then taken to be the identity operator. In this case, Proposition 2.1 is reduced to the statement that the energy remains bounded, which is true since it is conserved. Note also that we have chosen \( N = N(\Lambda) \) so the time dependence of \( N \) only enters through that of the blowup parameter \( \Lambda = \Lambda(t) \).

Proposition 2.1 gives a control on the growth of the modified energy as \( t \) approaches \( T^* \). During the finite time blowup evolution, the modified kinetic energy explodes to infinity. The above Proposition shows that the total modified energy grows more slowly than its kinetic component. It is the key element in the proof of Theorem 1.1, requiring somewhat delicate harmonic analysis estimates to prove an almost conservation property of the modified energy \( E[I_Nu] \) in terms of space-time control given by local existence theory. For the sake of a clear presentation, we start by proving Theorem 1.1 assuming Proposition 2.1 and a lower bound on the rate of blowup of \( \| I_N(D)u \|_{L^2} \) expressed in Corollary 3.6.

**Proof of Theorem 1.1.** It is carried out in four steps.

a. **Rescaling and weak convergence.**

Let \( \{ t_n \}_{n=1}^{\infty} \) be a sequence such that \( t_n \uparrow T^* \) and for each \( t_n \)
\[ \| u(t_n) \|_{H^s} = \Lambda(t_n). \]

We call such a sequence maximizing and denote \( u_n = u(t_n) \). Define
\[ I_Nu_n = I_{N(t_n)}u(t_n) \]
with $N(t_n)$ taken\(^6\) as in the Proposition 2.1. We rescale these as follows:

\begin{equation}
\tag{2.9}
v_n(y) = \frac{1}{\sigma_n} I_N^{} u_n\left(\frac{y}{\sigma_n}\right)
\end{equation}

where

\[\sigma_n = \|I_N(D)u_n\|_{L^2} = \sigma(t_n).\]

We have, from (2.3), that

\begin{equation}
\tag{2.10}
\Lambda(t_n) \leq \sigma_n
\end{equation}

along a maximizing sequence so $\sigma_n \to \infty$ as $n \to \infty$. The lower bound of $\sigma_n$ by $\Lambda(t_n)$ does not necessarily hold for arbitrary sequences, but does so along maximizing sequences.

The rescaling (2.9) leaves $L^2$-norms unchanged. Since $\|I_N \cdot\|_{L^2} \leq \|\cdot\|_{L^2}$ for all $N$ and since mass is conserved, we have $\|v_n\|_{L^2} \leq \|u_0\|_{L^2}$ uniformly in $n$. By our choice of $\sigma_n$, we have $\|\nabla v_n\|_{L^2} \leq 1$ for all $n$. In fact, by construction, we have

\begin{equation}
\tag{2.11}
\lim_{n \to \infty} \|\nabla v_n\|_{L^2} = 1.
\end{equation}

Thus, $\{v_n\}$ is a bounded sequence in $H^1$ and has a weakly convergent subsequence, which we also call $\{v_n\}$. There exists an asymptotic object $v \in H^1$ such that

\[v_n \rightharpoonup v\]

in $H^1$.

**b. Compactness and energy of the rescaled asymptotic object.**

Since $u$ is assumed to be radially symmetric, so are the $v_n$, and we can apply the following Lemma from [19].

**Lemma 2.3. (Radial compactness lemma)** If $\{f_n\} \subset H^1(\mathbb{R}^2)$ is a bounded sequence of radially symmetric functions, then there exists a subsequence (also denoted $\{f_n\}$) and a function $f \in H^1(\mathbb{R}^2)$ such that for all $2 < q < \infty$,

\[f_n \to f\]

in $L^q$.

Thus,

\[v_n \rightharpoonup v\]

in $L^4$. This strong $L^4$-convergence is important due to the appearance of the $L^4$ norm in the energy, which we now examine. The only usage of the radial symmetry assumption in the argument is to obtain compactness of $\{v_n\}$ in $L^4$.

We have, from Proposition 2.1 and (2.10),

\[|E[v_n]| = \sigma_n^{-2}|E[I_N^{} u_n]| \leq C \sigma_n^{-2} \Lambda^{p(s)}(t_n) \leq CA^{p(s)-2}(t_n).
\]

\(^6\)The reason for this choice is made clear at equation (4.2).
Since \( s > s_Q \), we have \( p(s) < 2 \), so
\[
|E[v_n]| \to 0
\]
as \( n \to \infty \).

The fact that the energy of the functions \( v_n \) goes to zero is useful in two important ways. First, by (2.11) and the strong \( L^4 \)-convergence,
\[
0 = \lim_{n \to \infty} |E[v_n]|
\]
\[
= \lim_{n \to \infty} \left( \frac{1}{2} \| \nabla v_n \|^2_{L^2} - \frac{1}{4} \| v_n \|^4_{L^4} \right)
\]
This ensures that \( v \neq 0 \). Second, the \( L^2 \) norm is a lower semi-continuous function for weakly convergent sequences, so
\[
0 = \lim_{n \to \infty} E[v_n] \geq E[v].
\]

**c. Non-positive energy implies at least ground state mass.**

The fact that nonzero functions of nonpositive energy have at least the mass of the ground state is a consequence of the Gagliardo–Nirenberg inequality:

\[
\| w \|_{L^4}^4 \leq C_{\text{opt}} \| w \|_{L^2}^2 \| \nabla w \|_{L^2}^2.
\]

The optimal constant, obtained by minimizing the functional

\[
J(f) = \frac{\| \nabla f \|_{L^2}^2 \| f \|_{L^2}^2}{\| f \|_{L^4}^4}
\]

among all functions \( f \in H^1(\mathbb{R}^2) \), is found to be \( C_{\text{opt}} = 2/\| Q \|_{L^2}^2 \) [23].

Thus, the asymptotic object \( v \) satisfies
\[
\| v \|_{L^2} \geq \| Q \|_{L^2}.
\]

**d. Scaling back to the original variables.**

Now we complete the proof. To prove (1.4), it suffices to show for any \( \epsilon > 0 \) that
\[
\lim_{n \to \infty} \| u(t_n) \|_{L^2_{\{ |x| < (T^* - t_n)^{s/2} \gamma(T^* - t_n) \}}} > \| Q \|_{L^2} - \epsilon.
\]

Fix \( \epsilon > 0 \). Since \( N(t_n) \) goes to \( \infty \), we have
\[
\lim_{n \to \infty} \| u(t_n) \|_{L^2_{\{ |x| < (T^* - t_n)^{s/2} \gamma(T^* - t_n) \}}} = \lim_{n \to \infty} \| I_N(t_n) u(t_n) \|_{L^2_{\{ |x| < (T^* - t_n)^{s/2} \gamma(T^* - t_n) \}}}.
\]

Recalling the definition of the functions \( v_n \), we have for all \( n \)
\[
\| I_N(t_n) u(t_n) \|_{L^2_{\{ |x| < (T^* - t_n)^{s/2} \gamma(T^* - t_n) \}}} = \| v_n \|_{L^2_{\{ |y| < (T^* - t_n)^{s/2} \gamma(T^* - t_n) \sigma_n \}}}.
\]

By (2.15) we know there exists \( \rho > 0 \) such that
\[
\| v \|_{L^2_{\{ |y| < \rho \}}} > \| Q \|_{L^2} - \epsilon.
\]
Since, by Corollary 3.6, the $\sigma_n$ go to $\infty$ at least as fast as $(T^*-t_n)^{-s/2}$, eventually $\rho < (T^*-t_n)^{s/2} \gamma(T^*-t_n) \sigma_n$, where $\gamma(z)$ is a positive function satisfying $\gamma(z) \uparrow \infty$ as $z \downarrow 0$. Thus,
\[
\lim_{n \to \infty} \|u(t_n)\|_{L^2} \left\{ |x| < (T^*-t_n)^{s/2} \gamma(T^*-t_n) \sigma_n \right\} = \lim_{n \to \infty} \|v_n\|_{L^2} \left\{ |y| < (T^*-t_n)^{s/2} \gamma(T^*-t_n) \sigma_n \right\} \\
\geq \lim_{n \to \infty} \|v_n\|_{L^2} \left\{ |y| < \rho \right\} \\
\geq \|v\|_{L^2} \left\{ |y| < \rho \right\} \\
> \|Q\|_{L^2} - \epsilon.
\]
This concludes the proof of Theorem 1.1 under the assumptions that Proposition 2.1 and Corollary 3.6 hold true.

\section{3. local-in-time theory}

In this section, we adapt the arguments in [6] to prove an almost conservation property for $E[I_N u]$ which plays a central role in the proof of Proposition 2.1. We begin by revisiting the Strichartz estimates and the classical proof [4] of local well-posedness of (1.1) for $u_0 \in H^s$, $s > 0$. We then explain a modification of the $H^s$ local well-posedness result in which the $H^s$-norm of $u_0$ is replaced by $\|I_N(D)u_0\|_{L^2}$. The modified local well-posedness result provides the space-time control used to prove the almost conservation of the modified energy $E[I_N u]$.

\subsection{3.1. Strichartz estimates}

We recall the classical Strichartz estimates [11] for the Schrödinger group $e^{it\Delta}$ on $\mathbb{R}_t \times \mathbb{R}^2_\xi$ (see also [12] for a unified presentation).

The ordered exponent pairs $(q,r)$ are \emph{admissible} if $\frac{s}{q} + \frac{s}{r} = 1$, $2 < q$. Note that $(3,6)$ and $(\infty,2)$ are admissible. We define the \emph{Strichartz norm} of functions $u : [0,T] \times \mathbb{R}^2 \to \mathbb{C}$,
\[
\|u\|_{S_T^q} = \sup_{(q,r) \text{ admissible}} \|u\|_{L^q_t \in [0,T] L^r_x \in \mathbb{R}^2}. \tag{3.1}
\]
We will use the shorthand notation $L^q_T$ to denote $L^q_t \in [0,T]$ and $L^p_x$ for $L^p_x \in \mathbb{R}^2$. The Hölder dual exponent of $q$ is denoted $q'$, so $\frac{1}{q} + \frac{1}{q'} = 1$. The Strichartz estimates may be expressed as follows:
\[
\|u\|_{S_T^q} \leq \|u(0)\|_{L^2} + \|(i\partial_t + \Delta)u\|_{L^q_T L^{q'}_x} \tag{3.2}
\]
where $(q,r)$ is any admissible exponent pair.

The smoothing properties underlying our proof of the almost conservation of $E[I_N u]$ given below requires a careful control of the interaction between high and low frequency parts of the solution. Linear Strichartz estimates are not sufficient for this purpose. They are complimented by bilinear Strichartz estimates that were introduced in [1] and revisited in [10]. Let $D^\alpha$ denote the operator defined by $\hat{D^\alpha}u(\xi) = |\xi|^\alpha \hat{u}(\xi)$. Similarly, $(D)^\alpha$ denotes the operator defined via $(\hat{D})^\alpha u(\xi) = (1 + |\xi|^2)^{\frac{\alpha}{2}} \hat{u}(\xi)$. We recall the following \emph{a priori bilinear}
Strichartz estimate [1] as expressed in Lemma 3.4 of [10]: For all \( \delta > 0 \) and any \( u, v : [0, T] \times \mathbb{R}^2 \rightarrow \mathbb{C} \)
\[
\|uv\|_{L^\infty_T L^2_x} \leq C(\delta) \left( \|D^{\frac{1}{2}} + \delta u(0)\|_{L^2_x} + \|D^{\frac{1}{2}} + \delta (i\partial_t + \Delta)u\|_{L^1_T L^2_x} \right) \times \left( \|D^{\frac{1}{2}} - \delta v(0)\|_{L^2_x} + \|D^{\frac{1}{2}} - \delta (i\partial_t + \Delta)v\|_{L^1_T L^2_x} \right).
\]
Note that, in the inequality (3.3), a different amount of regularity is required for \( u \) and \( v \). In the following analysis, we will use it with \( u, v \) being the projection of an \( H^s \) solution of (1.1) onto different frequency regimes.

3.2. Standard \( H^s \) Local well-posedness. We revisit the proof of local well-posedness of (1.1) for initial data in \( H^s \), \( s > 0 \), extracting the features of the local-in-time theory required in the proof of the almost conservation property underlying our proof of Theorem 1.1 and Proposition 2.1.

Proposition 3.1 (\( H^s \)-LWP [4]). For \( u_0 \in H^s(\mathbb{R}^2) \), \( s > 0 \), the evolution \( u_0 \mapsto u(t) \) is well-posed on the time interval \( [0, T_{lwp}] \) with
\[
T_{lwp} = c_0\|\langle D\rangle^s u_0\|_{L^2_x}^2,
\]
for a constant \( c_0 \) and
\[
\|\langle D\rangle^s u\|_{S^s_{lwp}} \leq 2\|\langle D\rangle^s u_0\|_{L^2_x}.
\]

Proof. The initial value problem (1.1) is equivalent, by Duhamel’s formula, to solving the integral equation
\[
\frac{\partial u}{\partial t} = \Delta u + i\langle D\rangle^s u_0 + i\int_0^t e^{i(t-t')\Delta}\langle |u|^2 u(t')\rangle dt'.
\]
For a given function \( u \), denote the right-hand side of (3.6) by \( \Phi_{u_0}[u] \). We prove that \( \Phi_{u_0}[\cdot] \) is a contraction mapping on the ball
\[
B_{L^\infty_T L^6_x}(\rho) = \{ u : [0, T] \times \mathbb{R}^2 \rightarrow \mathbb{C} \mid \|u\|_{L^\infty_T L^6_x} < \rho \},
\]
for sufficiently small \( \rho \). In fact, we will show that \( \|\Phi_{u_0}[u] - \Phi_{u_0}[v]\|_{S^s_{lwp}} < \frac{1}{2}\|u - v\|_{L^\infty_T L^6_x} \) provided \( T \) is chosen small enough in terms of the \( H^s \) size of the initial data. We write \( \Phi_{u_0}[u] - \Phi_{u_0}[v] \), observe the cancellation of the linear pieces, apply the \( S^s_{lwp} \) norm, and use (3.2) to obtain
\[
\|\Phi_{u_0}[u] - \Phi_{u_0}[v]\|_{S^s_{lwp}} \leq C\|u\|_{L^\infty_T L^6_x}^2 - \|v\|_{L^\infty_T L^6_x}^2.
\]
(We have made the choice \( q' = 1 \) and \( r' = 2 \) in (3.2) to simplify the analysis below which emerges from the appearance of this norm in (3.3). This choice makes it convenient to perform the fixed point argument in \( L^2_T L^6_x \).)

By Hölder’s inequality and simple algebra,
\[
\|u\|_{L^\infty_T L^6_x}^2 - \|v\|_{L^\infty_T L^6_x}^2 \leq C(\|u\|_{L^\infty_T L^6_x}^2 + \|v\|_{L^\infty_T L^6_x}^2)\|u - v\|_{L^\infty_T L^6_x} \leq C\rho^2\|u - v\|_{L^\infty_T L^6_x}.
\]
This proves \( \Phi_{u_0}[\cdot] \) is indeed a contraction mapping on \( B(\rho) \) if \( \rho < \rho_0 \), where \( \rho_0 \) is an explicit constant.
Thus, the sequence of Duhamel iterates \( \{ u^j \} \), defined by the recursion
\[
\begin{align*}
    u^0(t, x) & = e^{it\Delta} u_0(x) \\
    u^{j+1}(t) & = e^{it\Delta} u_0 + i \int_0^t e^{i(t-t')\Delta} (|u^j|^2 u^j(t')) dt',
\end{align*}
\]
converges geometrically to the solution \( u \) provided that
\[
\|e^{it\Delta} u_0\|_{L^2_t L^6_x} < \rho_0.
\]
By Hölder’s inequality in time and Sobolev’s inequality in space,
\[
\|u\|_{L^3_t L^6_x} \leq C T^{3/2 - \frac{2}{q}} \|\langle D\rangle^s u\|_{L^q_t L^r_x}
\]
with \( q > 3 \) and \( \frac{2}{r} = \frac{2}{6} + s \). We choose \( q \) so that \((q, r)\) is admissible, i.e. \( \frac{2}{q} + \frac{2}{r} = 1 \). This gives \( \frac{1}{3} - \frac{1}{q} = \frac{s}{2} \). Applying (3.11) and then (3.2), we have
\[
\|e^{it\Delta} u_0\|_{L^2_t L^6_x} \leq T^{\frac{s}{2}} \|\langle D\rangle^s u_0\|_{L^2_t L^6_x} \leq T^{\frac{s}{2}} \|\langle D\rangle^s u_0\|_{L^2}.
\]
We choose \( T = T_{lwp} \) so that the right-hand side of (3.12) is less than \( \rho_0 \), namely so that (3.4) holds. The Strichartz estimate implies that the zeroth iterate satisfies
\[
\|u^0\|_{S^0_{T_{lwp}}} \leq C \|u_0\|_{H^s}.
\]
By the geometric convergence of the iterates, we have that
\[
\|u\|_{S^0_{T_{lwp}}} \leq C \|u_0\|_{H^s}
\]
and
\[
\|u\|_{L^3_{T_{lwp}} L^6_x} \leq C \rho_0.
\]
A posteriori, we can revisit the estimate for the solution of (3.6) and use the Leibnitz rule for fractional derivatives to prove the persistence of regularity property
\[
\|\langle D\rangle^s u\|_{S^0_T} \leq 2 \|\langle D\rangle^s u_0\|_{L^2}.
\]
This follows from the Strichartz estimate on the linear term in (3.6) and the estimate
\[
\|\langle D\rangle^s(|u|^2 u)\|_{L^1_t L^2_x} \leq C \|u\|_{L^3_t L^6_x}^2 \|\langle D\rangle^s u\|_{L^2_t L^6_x} \leq C \rho_0^2 \|\langle D\rangle^s u\|_{S^0_T}
\]
where, in the last step, we used (3.14). The first inequality in (3.16) follows, for example, from Proposition 1.1 on page 105 of [20].

\[\blacksquare\]

**Corollary 3.2** ([4]). If \( H^s \ni u_0 \mapsto u(t) \) with \( s > 0 \) solves (1.1) for all \( t \) near enough to \( T^* \) in the maximal finite interval of existence \([0, T^*)\) then
\[
C(T^* - t)^{-\frac{s}{2}} \leq \|\langle D\rangle^s u(t)\|_{L^2}.
\]
Note that the estimate (3.16) implies that, when we restrict attention to solutions of (1.1) with \( t \in [0, T_{lwp}] \), we can essentially ignore the contributions involving the inhomogeneous terms appearing on the right side of (3.3) since these terms are controlled by the corresponding homogeneous terms. As a consequence of this and the bilinear Strichartz estimate, we prove the following lemma. We define \( \mathbb{P}_{N_j} \) to be the Littlewood-Paley projection operator to frequencies of size \( N_j \in 2^\mathbb{N} \), i.e. \( \hat{\mathbb{P}_{N_j}} f(\xi) = \chi_{\{\frac{1}{2}N_j < \xi < 2N_j\}} \hat{f}(\xi) \).

**Lemma 3.3.** Suppose \( u \) solves (1.1) on the time interval \([0, T_{lwp}]\). Let \( u_j = \mathbb{P}_{N_j} u \), for \( j = 1, 2 \) with \( N_1 > N_2 \). Then

\[
\|u_1 u_2\|_{L^2_{T_{lwp}} L^2_x} \leq C \left( \frac{N_2}{N_1} \right)^{1/2} \|u\|_{S^0_{T_{lwp}}}^2,
\]

The estimate (3.18) is also valid if \( u_j \) is replaced by \( \overline{u_j} \).

This bilinear smoothing property of solutions of (1.1) is the key device underpinning the proof of the almost conservation of the modified energy in Proposition 3.7.

### 3.3. Modified \( H^s \) Local Well-posedness.

**Proposition 3.4** (Modified \( H^s \)-LWP). For \( u_0 \in H^s \), \( s > 0 \), the (1.1) evolution \( u_0 \mapsto u(t) \) is well-posed on the time interval \([0, \tilde{T}_{lwp}]\) with

\[
\tilde{T}_{lwp} = c_0 \left\| I_N \nabla u_0 \right\|_{L^2_x}^{-2}.
\]

\[
\|I_N \langle D \rangle u\|_{S^0_{T_{lwp}}} \leq 2 \|I_N \langle D \rangle u_0\|_{L^2_x}.
\]

**Proof.** The proof is a modification of the arguments used to prove Proposition 3.1. Note first that the estimates (3.12) and (2.3) may be combined to give

\[
\|e^{it\Delta} u_0\|_{L^2_x L^6_\tau} \leq CT^{5/6} \|I_N \langle D \rangle u_0\|_{L^2}.
\]

Thus, the previous analysis produces a solution \( u \) of (1.1) satisfying (3.14) and

\[
\|u\|_{S^0_{T_{lwp}}} \leq C \|I_N \langle D \rangle u_0\|_{L^2}
\]

provided that we choose \( \tilde{T}_{lwp} \) as in (3.19).

Next, we turn our attention toward the space-time regularity estimate (3.20). Since \( e^{it\Delta} \) does not affect the magnitude of Fourier coefficients, (3.20) is clearly valid for the linear term in (3.6). Since the spaces appearing on both sides of the trilinear estimate (3.16) are translation invariant and (the first inequality in) (3.16) is valid, the modified estimate (3.20) follows directly from the interpolation lemma (Lemma 12.1 on page 108) in [5].
Remark 3.5. A modification of (3.18) follows using the spacetime control given in (3.20): For \( N_1 \geq N_2 \) and for solutions \( u \) of (1.1),

\[
(3.23) \quad \| I(D) u_{N_1} I(D) u_{N_2} \|_{L^2_T L^2_x} \leq C \left( \frac{N_2}{N_1} \right)^{\frac{1}{2}} \| I(D) u \|_{S_0 T}^2.
\]

Corollary 3.6. If \( H^s \ni u_0 \mapsto u(t) \) with \( s > 0 \) solves (1.1) for all \( t \) near enough to \( T^* \) in the maximal finite time interval of existence \( [0, T^*) \)

\[
(3.24) \quad C(T^* - t)^{- \frac{s}{2}} \leq \| I_N(D) u(t) \|_{L^2_x}.
\]

Since we are studying here finite time blowup solutions, we will sometimes implicitly assume that \( \| I_N \nabla u(t) \|_{L^2} > 1 \).

3.4. Almost conservation law for the modified energy.

Proposition 3.7. If \( H^s \ni u_0 \mapsto u(t) \) with \( s > 0 \) solves (1.1) for all \( t \in [0, T_{lwp}] \) then

\[
(3.25) \quad \sup_{t \in [0, T_{lwp}]} \| E[I_N u(t)] \| \leq |E[I_N u(0)]| + C N^{-\alpha_4} \| I_N(D) u(0) \|_{S_0 T}^4 + C N^{-\alpha_6} \| I_N(D) u(0) \|_{S_0 T}^6,
\]

with \( \alpha_4 = \frac{3}{2} - \) and \( \alpha_6 = 2 - \).

Proof. We adapt arguments from [6] in which a similar result is proved using local well-posedness theory in the weighted \( X_{s,b} \) spaces. We recall that the parameter \( N \) refers to the operator \( I_N \) defined in (2.2). In light of (3.20), it suffices to control the energy increment \( |E[I_N u(t)] - E[I_N u(0)]| \) for \( t \in [0, T_{lwp}] \) in terms of \( \| I_N(D) u \|_{S_0 T_{lwp}} \). We define the set \( \ast_n = \{ (\xi_1, \ldots , \xi_n) : \Sigma \xi_i = 0 \} \). An explicit calculation of \( \partial_t E[I_N u] \) (carried out in detail in Section 3 of [6]) reveals that \( |E[I_N u(t)] - E[I_N u(0)]| \) is controlled by the sum of the two space-time integrals:

\[
(3.26) \quad E_1 = \left| \int_0^t \int_{s*} \left[ 1 - \frac{m(\xi_1)}{m(\xi_2) m(\xi_3) m(\xi_4)} \Delta \tilde{u}(\xi_1) \tilde{u}(\xi_2) \tilde{u}(\xi_3) \tilde{u}(\xi_4) \right] \right|,
\]

and

\[
(3.27) \quad E_2 = \left| \int_0^t \int \left[ 1 - \frac{m(\xi_1)}{m(\xi_2) m(\xi_3) m(\xi_4)} \right] I(\tilde{u}^2 \tilde{u})(\xi_1) \tilde{u}(\xi_2) \tilde{u}(\xi_3) \tilde{u}(\xi_4) \right|.
\]

We estimate the 4-linear expression (3.26) first. Let \( u_{N_j} \) denote \( P_{N_j} u \). When \( \xi_j \) is dyadically localized to \( \{ |\xi| \sim N_j \} \) we will write \( m_j \) to denote \( m(\xi_j) \).
Lemma 3.8. If \( H^s \ni u_0 \mapsto u(t) \) with \( s > 0 \) solves (1.1) for all \( t \in [0, T_{lwp}] \) then
\[
\left| \int_0^t \int_{*4} \left[ 1 - \frac{m_1}{m_2 m_3 m_4} \right] \left( \Delta \overline{I_{N_1}}(\xi_1) \overline{I_{N_2}}(\xi_2) \overline{I_{N_3}}(\xi_3) \overline{I_{N_4}}(\xi_4) \right) \right| \leq N^{-\alpha_4} \| I(D)u \|^4_{S^0_{2T_{lwp}} N_j=1 \prod} N_j^{0-}.
\]
(3.28)
with \( \alpha_4 = \frac{3}{2} \).

Proof. The analysis which follows will not rely upon the complex conjugate structure in the left-side of (3.28). Thus, there is symmetry under the interchange of the indices 2,3,4. We may therefore assume that \( N_2 \geq N_3 \geq N_4 \).

Case 1. \( N \gg N_2 \). On the convolution hypersurface \( *4 \), this forces \( N_1 \ll N \) as well, so the multiplier \( \left[ 1 - \frac{m_1}{m_2 m_3 m_4} \right] = 0 \) and the expression to be bounded vanishes.

Case 2. \( N_2 \gg N \gg N_3 \gg N_4 \). This forces \( N_1 \sim N_2 \) on \( *4 \). By the mean value theorem and simple algebra
\[
\left| 1 - \frac{m_1}{m_2 m_3 m_4} \right| = \left| \frac{m(\xi_2) - m(\xi_2 + \xi_3 + \xi_4)}{m(\xi_2)} \right| \leq \left| \nabla m(\xi_2) \cdot (\xi_3 + \xi_4) \right| \lesssim N_3 \frac{N_3}{N_2}.
\]
(3.29)

We use the frequency localization of the \( u_{N_j} \) to renormalize the derivatives and multipliers to arrange for the appearance of \( I(D)u_{N_j} \). In the case under consideration, using (3.29) and the frequency localizations, the left-side of (3.28) is controlled by
\[
\frac{N_3}{N_2} N_1(\langle N_3 \rangle \langle N_4 \rangle)^{-1} \left| \int_0^t \int_{*4} \prod_{j=1}^4 I(D)u_{N_j}(\xi_j) \right|.
\]

We apply Cauchy-Schwarz to obtain the bound
\[
\frac{N_3}{N_2} N_1(\langle N_3 \rangle \langle N_4 \rangle)^{-1} \| I(D)u_{N_1} \|_{L^2_{T_{lwp}}} \| I(D)u_{N_2} \|_{L^2_{T_{lwp}}} \| I(D)u_{N_3} \|_{L^2_{T_{lwp}}} \| I(D)u_{N_4} \|_{L^2_{T_{lwp}}}.
\]
By (3.23), we control by
\[
\frac{N_3}{N_2} N_1(\langle N_3 \rangle \langle N_4 \rangle)^{-1} \left( \frac{N_3 N_4}{N_1 N_2} \right)^{\frac{1}{2}} \| I(D)u \|^4_{S^0_{2T_{lwp}}},
\]
which simplifies to give the bound
\[
N^{-\frac{3}{2} + (N_1 N_2 \langle N_3 \rangle \langle N_4 \rangle)^{0-}} \| I(D)u \|^4_{S^0_{2T_{lwp}}}.
\]
(3.30)

Case 3. \( N_2 \geq N_3 \geq N \). In this case, we use the trivial multiplier bound
\[
\left| 1 - \frac{m_1}{m_2 m_3 m_4} \right| \leq \frac{m_1}{m_2 m_3 m_4}.
\]
(3.31)
Again, we pull the multiplier out and estimate the remaining integral using Lemma 3.3.

**Case 3a.** $N_1 \sim N_2 \geq N_3 \gtrsim N$. We bound $E_1$ here by renormalizing the derivatives and multiplier, then pairing $u_{N_1}u_{N_3}$ and $u_{N_2}u_{N_4}$ and using Lemma (3.3) again:

$$\frac{m_1}{m_2m_3m_4} \left( \frac{N_3N_4}{N_1N_2} \right)^{\frac{1}{2}} N_1(\langle N_2N_3 \rangle)^{-1} \|I(D)u\|_{S_0}^{\frac{1}{T_{lwp}}}.$$  

We reexpress this bound as

$$\frac{m_1}{m_2N_2^2m_3N_3^2m_4N_4^{1/2}N_1^{1/2}} \|I(D)u\|_{S_0}^{\frac{1}{T_{lwp}}}.$$  

Since $m(x)$ is bounded from above by 1 and $m(x)\langle x \rangle^{1/2}$ is nondecreasing and bounded from below by 1, this is bounded by

$$\frac{1}{NN_1^2} \|I(D)u\|_{S_0}^{\frac{1}{T_{lwp}}} \leq N^{-\frac{3}{4}}(\langle N_1N_2N_3 \rangle)^{0-} \|I(D)u\|_{S_0}^{\frac{1}{T_{lwp}}}.$$  

**Case 3b.** $N_2 \sim N_3 \geq N$. A similar analysis leads to the bound

$$\frac{m_1}{m_2m_3m_4} \left( \frac{N_1N_4}{N_3N_2} \right)^{\frac{1}{2}} N_1(\langle N_2N_3 \rangle)^{-1} \|I(D)u\|_{S_0}^{\frac{1}{T_{lwp}}} \leq \frac{1}{N_2^2} \|I(D)u_{N_j}\|_{S_0}^{\frac{1}{T_{lwp}}} \leq N^{-\frac{3}{4}}(\langle N_1N_2N_3 \rangle)^{0-} \|I(D)u_{N_j}\|_{S_0}^{\frac{1}{T_{lwp}}}.$$  

A related case-by-case analysis combined with a trilinear estimate establishes the required 6-linear estimate for (3.27). We write $m_{123}$ to denote $m(\xi_1 + \xi_2 + \xi_3)$ and use $N_{123}$ to denote the (dyadic) size of $\xi_1 + \xi_2 + \xi_3$. We will also use the similarly defined notation $m_{456}$. Note that $N_{123}$ could be much smaller than $N_1$, $N_2$, or $N_3$.

**Lemma 3.9.** If $H^s \ni u_0 \mapsto u(t)$ with $s > 0$ solves (1.1) for all $t \in [0, \tilde{T}_{lwp}]$ then

$$\int_0^t \int_{\mathbb{R}^d} \left[ 1 - \frac{m_{123}}{m_{456}} \right] m_{123} \left( \hat{u}_{N_1}(\xi_1) \hat{u}_{N_2}(\xi_2) \hat{u}_{N_3}(\xi_3) \right) \hat{I}u_{N_4}(\xi_4) \hat{I}u_{N_5}(\xi_5) \hat{I}u_{N_6}(\xi_6) \leq N^{-\alpha_6} \|I(D)u\|_{S_0}^6 \prod_{j=1}^6 N_j^{0^-}$$  

with $\alpha_6 = 2^-$. 

Proof. We carry out a case-by-case analysis. By symmetry (since we will not use the complex conjugate structure), we may assume $N_4 \geq N_5 \geq N_6$.

Case 1. $N \gg N_4$. On $*6$, this forces $N_{123} \sim N_4$ so $\left[1 - \frac{m_{123}}{m_4 m_5 m_6}\right]$ vanishes.

Case 2. $N_4 \geq N \geq N_5$. On $*6$, $N_{123} \sim N_4$ in this case. By the mean value theorem,

$$\left|1 - \frac{m_{123}}{m_4 m_5 m_6}\right| = \frac{|m_4 - m_{456}|}{m_4} \leq \frac{N_5}{N_4}.$$ 

Applying this multiplier bound and the Cauchy-Schwarz inequality to the integral in (3.33) gives the bound

$$(N_4 (N_5))^{-1} \frac{N_5}{N_4} \| \mathbb{P}_{N_{123}} I(\overline{\pi}_{N_1} u_{N_2} \overline{\pi}_{N_3}) I u_{N_6} \|_{L^2_{T_x}} \| I \langle D \rangle u_{N_4} I \langle D \rangle u_{N_6} \|_{L^2_{T_x}}.$$ 

By Hölder’s inequality and Lemma 3.3, we control the above expression by

$$(3.34) \quad \left(N_4 (N_5)\right)^{-1} \frac{N_5}{N_4} \| \mathbb{P}_{N_{123}} I(\overline{\pi}_{N_1} u_{N_2} \overline{\pi}_{N_3}) \|_{L^2_{T_x}} \| I u_{N_6} \|_{L^\infty_{T_x}} 
\times \left(\frac{N_5}{N_4}\right)^{\frac{3}{2}} \| I \langle D \rangle u \|_{S^0_{123}} \| I \langle D \rangle u \|_{S^0_{123}}.$$ 

By Sobolev’s inequality on functions with frequency support localized to a dyadic shell on $R^2_x$,

$$\| I u_{N_6} \|_{L^\infty_{T_x}} \leq \| I \langle D \rangle u_{N_6} \|_{L^2_{T_x}.}$$

In order to continue the proof of Lemma 3.9, we need an estimate of the term $\| \mathbb{P}_{N_{123}} I(\overline{\pi}_{N_1} u_{N_2} \overline{\pi}_{N_3}) \|_{L^2_{T_x}}$. This is the purpose of the next lemma. Let $N_1 \geq N_2 \geq N_3$ denote the decreasing rearrangement of $N_1, N_2, N_3$.

Lemma 3.10.

$$(3.36) \quad \| \mathbb{P}_{N_{123}} I(\overline{\pi}_{N_1} u_{N_2} \overline{\pi}_{N_3}) \|_{L^2_{T_x}} \leq \langle N_1 \rangle^{-\frac{3}{2}} \prod_{j=1}^{3} \| I \langle D \rangle u_{N_j} \|_{S^0_{123}}.$$ 

Proof. Again, we will not use the complex conjugate structure so we may assume that $N_1 \geq N_2 \geq N_3$. The projection $\mathbb{P}_{N_{123}}$ allows us to control the left-hand side of (3.36) by

$$m_{123} \| \overline{\pi}_{N_1} u_{N_2} \overline{\pi}_{N_3} \|_{L^2_{T_x}} \leq m_{123} \| u_{N_1} \|_{L^4_{T_x}} \| u_{N_2} \|_{L^4_{T_x}} \| u_{N_3} \|_{L^\infty_{T_x}}$$

where we used Hölder’s inequality.

We renormalize the derivatives and use a (dyadically localized) Sobolev inequality as in (3.35) to get the bound

$$\frac{m_{123}}{m_1 m_2 m_3} \langle N_1 \rangle^{-1} \langle N_2 \rangle^{-1} \| I \langle D \rangle u_{N_1} \|_{L^4_{T_x}} \| I \langle D \rangle u_{N_2} \|_{L^4_{T_x}} \| I \langle D \rangle u_{N_3} \|_{L^2_{T_x}}.$$
Since the norms appearing in the above expression are admissible we focus our attention upon the prefactor and bound with the expression

\[
\frac{m_{123}N_3^{\frac{1}{2}}}{\langle N_1 \rangle^{\frac{1}{2}}\langle N_2 \rangle^{\frac{1}{2}}m_1\langle N_1 \rangle^{\frac{1}{2}}m_2\langle N_2 \rangle^{\frac{1}{2}}m_3\langle N_3 \rangle^{\frac{1}{2}} \prod_{j=1}^{3} \|I(D)u_{N_j}\|_{S_{T_{1wp}}^0}^6}.
\]

Since \( m(x) \leq 1 \), \( m(x)\langle x \rangle^{\frac{1}{2}} \) is nondecreasing, and \( N_3 \leq N_2 \), this proves (3.36).

We use (3.36) and (3.35) on (3.34) to complete the Case 2 analysis. The left-hand side of (3.33) is bounded by

\[
(N_4\langle N_5 \rangle)^{-1} \left( \frac{N_4}{N_5} \right)^{\frac{1}{2}} \langle N_1 \rangle^{-\frac{1}{2}} \|I(D)u\|_{S_{T_{1wp}}^0}^6
\]

and

\[
\leq \frac{N_4^2}{N_5^2} \langle N_1 \rangle^{-\frac{1}{2}} \|I(D)u\|_{S_{T_{1wp}}^0}^6
\]

\[
\leq N^{-2+}(N_1 \ldots \langle N_5 \rangle \langle N_6 \rangle)^{0-} \prod_{j=1}^{6} \|I(D)u\|_{S_{T_{1wp}}^0}^6.
\]

**Case 3.** \( N_4 \geq N_5 \geq N \). We will use the trivial multiplier estimate

\[
\left| \left[ 1 - \frac{m_{123}}{m_4m_5m_6} \right] \right| \leq \frac{m_{123}}{m_4m_5m_6}.
\]

Familiar steps lead to the bound

\[
\frac{m_{123}}{m_4m_5m_6} \langle N_1 \rangle^{-\frac{1}{2}} \left( \frac{N_5}{N_4} \right)^{\frac{1}{2}} \langle N_4 \rangle^{-1} \langle N_5 \rangle^{-1} \|I(D)u\|_{S_{T_{1wp}}^0}^6
\]

which we recast as

\[
\frac{m_{123}}{m_4N_4^{\frac{1}{2}}m_5N_5^{\frac{1}{2}}m_6N_6^{\frac{1}{2}}\langle N_1 \rangle^{\frac{1}{2}}N_4} \|I(D)u\|_{S_{T_{1wp}}^0}^6.
\]

**Case 3a.** \( N_6 \geq N \). We express the prefactor in (3.40) as

\[
\frac{m_{123}N_6^{\frac{1}{2}}}{m_4N_4^{\frac{1}{2}}m_5N_5^{\frac{1}{2}}m_6N_6^{\frac{1}{2}}\langle N_1 \rangle^{\frac{1}{2}}N_4} \leq \frac{1}{N^{\frac{1}{2}}N_4^{\frac{1}{2}}} \leq N^{-2+}(N_1 \ldots N_6)^{0-}.
\]

**Case 3b.** \( N_6 \leq N \). Here we have \( m_6 = 1 \) so we can bound the prefactor in (3.40) by

\[
\frac{1}{N N_4} \leq N^{-2+}(N_1N_2N_3N_4)^{0-}.
\]

Since (3.26) and (3.27) control the increment in the modified energy, it suffices to prove appropriate bounds on these integrals to obtain (3.25). Lemmas (3.8), (3.9) provide estimates for dyadically localized contributions to the integrals (3.26), (3.27), respectively. Since the estimates (3.28) and (3.33) have the helpful
decay factors $\lambda_j^{0-}$, we can sum up the dyadic contributions, and apply Cauchy-Schwarz to complete the proof of (3.25).

4. Modified kinetic energy dominates modified total energy

In this section, we prove Proposition 2.1.

Proof of Proposition 2.1. When $s \geq 1$, we set $I_{N(T)} = \text{Identity}$ by choosing $N(T) = +\infty$. Since the (unmodified) energy is conserved while the kinetic energy blows up as time approaches $T^*$, the estimate (2.8) is obvious with $p(s) = 0$. We therefore restrict attention to $s \in (s_Q, 1)$, with $s_Q$ to be determined at the end of the proof.

Fix $s \in (s_Q, 1)$ and $T$ near $T^*$. Let $N = N(T)$ (to be chosen). Set $\delta = c_0 (\Sigma(T))^{-\frac{2}{s}} > 0$ with $c_0$ the small fixed constant in (3.19). Note that $\delta$ is the time of local well-posedness guaranteed by Proposition 3.4 for initial data of size $\Sigma(T)$, which is the largest value that the modified kinetic energy achieves up to time $T$. Thus the interval $[0, T]$ may be partitioned into $J = C \frac{T^*}{\delta}$-sized intervals on which the modified local well-posedness result uniformly applies. More precisely, $[0, T] = \bigcup_{j=1}^{J} I_j$, $I_j = [t_j, t_{j+1})$, $t_0 = 0$, $t_{j+1} = t_j + c\delta$, and we have at each $t_j$,

$$\|I_N(D)u(t_j)\|_{L^2} = \sigma(t_j) \leq \Sigma(T).$$

In addition, $\delta$ has been taken sufficiently small so that we can apply the almost conservation law Proposition 3.7 on each of the $I_j$. We now accumulate increments to the energy and have that

$$|E[I_N u(T)]| \leq |E[I_N u(0)]| + C \frac{T^*}{\delta} [N^{-\alpha_4} \Sigma^4(T) + N^{-\alpha_6} \Sigma^6(T)]$$

$$\leq N^{2(1-s)} \lambda(0) + C \frac{T^*}{\delta} N^{-\alpha_4} \Sigma^4(T) + C \frac{T^*}{\delta} N^{-\alpha_6} \Sigma^6(T).$$

By the choice of $\delta$ we see, dismissing irrelevant constants, that

$$|E[I_N u(T)]| \lesssim N^{2(1-s)} + N^{-\alpha_4} \Sigma^{4 + \frac{2}{s}}(T) + N^{-\alpha_6} \Sigma^{6 + \frac{2}{s}}(T).$$

Using (2.3), we can switch from $\Sigma$ to $\Lambda$:

(4.1)

$$|E[I_N u(T)]| \lesssim N^{2(1-s)} + N^{-\alpha_4 + (4 + \frac{2}{s})(1-s)} \Lambda^{4 + \frac{2}{s}}(T) + N^{-\alpha_6 + (6 + \frac{2}{s})(1-s)} \Lambda^{6 + \frac{2}{s}}(T).$$

We choose $N = N(\Lambda)$ so that the first and third terms in (4.1) give comparable contributions. A calculation reveals that the second term in (4.1) produces a smaller correction with $\alpha_2$ and $\alpha_4$ as given in Proposition 3.7. Thus, with the choice

(4.2)

$$N = \Lambda^{\frac{\alpha_2 + \frac{2}{s}}{\alpha_6 - (4 + \frac{2}{s})(1-s)}},$$
the Proposition 2.1 is established with
\[ p(s) = \frac{6 + \frac{2}{s}}{\alpha_6 - (4 + \frac{2}{s})(1 - s)} 2(1 - s). \]

Note that \( p(s) < 2 \) reduces to to a quadratic condition on \( s \). Specifically
\[ 10s^2 + (\alpha_6 - 6)s - 4 > 0. \]

For \( \alpha_6 = 2 \), this yields
\[ s > s_Q = \frac{1}{5} + \frac{1}{5} \sqrt{11} \sim 0.863. \]

\[ \square \]

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