

Selected solutions to exercises from Pavel
Grinfeld's *Introduction to Tensor Analysis and
the Calculus of Moving Surfaces*

David Sulon

9/14/14

Contents

I Part I	1
1 Chapter 1	3
2 Chapter 2	7
3 Chapter 3	13
4 Chapter 4	17
5 Chapter 5	33
6 Chapter 6	39
7 Chapter 7	47
8 Chapter 8	49
9 Chapter 9	51
II Part II	57
10 Chapter 10	59
11 Chapter 11	67
12 Chapter 12	77
III Part III	89
13 Chapter 16	101
14 Chapter 17	109

Introduction

Included in this text are solutions to various exercises from *Introduction to Tensor Analysis and the Calculus of Moving Surfaces*, by Dr. Pavel Grinfeld.

Part I

Part I

Chapter 1

Chapter 1

Ex. 1: We have $x = 2x'$, $y = 2y'$. Thus

$$\begin{aligned} F'(x', y') &= F(2x', 2y') \\ &= (2x')^2 e^{2y'} \\ &= 4(x')^2 e^{2y'}. \end{aligned}$$

Ex. 2: Note that the above implies $x' = \frac{1}{2}x$, $y' = \frac{1}{2}y$. We check

$$\begin{aligned} \frac{\partial F'}{\partial x'}(x', y') &= 8(x') e^{2y'} \\ &= 8\left(\frac{1}{2}x\right) e^{2\left(\frac{1}{2}y\right)} \\ &= 4xe^y \\ \frac{\partial F}{\partial x}(x, y) &= 2xe^y. \end{aligned}$$

Thus, $\frac{\partial F'}{\partial x'}(x', y') = 2\frac{\partial F}{\partial x}(x, y)$ as desired.

Ex. 3: Let $a, b \in \mathbb{R}$, $a, b \neq 0$, and consider the "re-scaled" coordinate basis

$$\begin{aligned} \mathbf{i}' &= \begin{pmatrix} a \\ 0 \end{pmatrix} \\ \mathbf{j}' &= \begin{pmatrix} 0 \\ b \end{pmatrix}, \end{aligned}$$

where each of the above vectors is taken to be with respect to the standard basis for \mathbb{R}^2 . Thus, given point (x, y) in standard coordinates, we have $x = ax'$, $y = by'$, where (x', y') is the same point in our new coordinate system. Now, let $T(x, y)$ be a differentiable function. Then,

$$\nabla T = \left(\frac{\partial T}{\partial x}(x, y), \frac{\partial T}{\partial y}(x, y) \right)$$

in standard coordinates

$$= \left(\frac{\partial F}{\partial x'}(x', y') \frac{\partial x'}{\partial x}(x, y), \frac{\partial F}{\partial y'}(x', y') \frac{\partial y'}{\partial y}(x, y) \right)$$

(think of x' as a function of x).

$$\begin{aligned} &= \left(\frac{\partial F}{\partial x'}(x', y') \frac{1}{a}, \frac{\partial F}{\partial y'}(x', y') \frac{1}{b} \right) \\ &= \left(\frac{1}{\sqrt{a^2 + 0}} \frac{\partial F}{\partial x'}, \frac{1}{b^2 + 0} \frac{\partial F}{\partial y'} \right) \\ &= \left(\frac{1}{\sqrt{\mathbf{i}' \cdot \mathbf{i}'} } \frac{\partial F}{\partial x'}, \frac{1}{\sqrt{\mathbf{j}' \cdot \mathbf{j}'}} \frac{\partial F}{\partial y'} \right) \end{aligned}$$

as desired.

Ex. 4: Assume

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix} + \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix}.$$

Then,

$$\begin{aligned} x' &= a + (\cos \alpha) x - (\sin \alpha) y \\ y' &= b + (\sin \alpha) x + (\cos \alpha) y \end{aligned}$$

Also,

$$\begin{aligned} \begin{pmatrix} x' - a \\ y' - b \end{pmatrix} &= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \\ \begin{pmatrix} x \\ y \end{pmatrix} &= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix}^{-1} \begin{pmatrix} x' - a \\ y' - b \end{pmatrix} \\ &= \begin{bmatrix} \frac{\cos \alpha}{\cos^2 \alpha + \sin^2 \alpha} & \frac{\sin \alpha}{\cos^2 \alpha + \sin^2 \alpha} \\ -\frac{\sin \alpha}{\cos^2 \alpha + \sin^2 \alpha} & \frac{\cos \alpha}{\cos^2 \alpha + \sin^2 \alpha} \end{bmatrix} \begin{pmatrix} x' - a \\ y' - b \end{pmatrix} \\ &= \begin{bmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{bmatrix} \begin{pmatrix} x' - a \\ y' - b \end{pmatrix} \end{aligned}$$

Thus,

$$\begin{aligned} x &= (\cos \alpha) (x' - a) + (\sin \alpha) (y' - b) \\ y &= -(\sin \alpha) (x' - a) + (\cos \alpha) (y' - b). \end{aligned}$$

Further notice that we obtain \mathbf{i}', \mathbf{j}' from the standard basis [Note: this "basis" would describe points be with respect to this point (a, b)]

$$\begin{aligned}\mathbf{i}' &= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \cos \alpha \mathbf{i} + \sin \alpha \mathbf{j} \\ \mathbf{j}' &= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ &= -\sin \alpha \mathbf{i} + \cos \alpha \mathbf{j}\end{aligned}$$

Now, we have, given a function F , we compute

$$\begin{aligned}\frac{\partial F}{\partial x}(x, y) \mathbf{i} + \frac{\partial F}{\partial y}(x, y) \mathbf{j} &= \left(\frac{\partial F}{\partial x'}(x', y') \frac{\partial x'}{\partial x}(x, y) + \frac{\partial F}{\partial y'}(x', y') \frac{\partial y'}{\partial x}(x, y) \right) \mathbf{i} + \left(\frac{\partial F}{\partial x'}(x', y') \frac{\partial x'}{\partial y}(x, y) + \frac{\partial F}{\partial y'}(x', y') \frac{\partial y'}{\partial y}(x, y) \right) \mathbf{j} \\ &= \left(\frac{\partial F}{\partial x'}(x', y') \cos \alpha + \frac{\partial F}{\partial y'}(x', y') \sin \alpha \right) \mathbf{i} + \left(-\frac{\partial F}{\partial x'}(x', y') \sin \alpha + \frac{\partial F}{\partial y'}(x', y') \cos \alpha \right) \mathbf{j} \\ &= \frac{\partial F}{\partial x'}(x', y') \cos \alpha \mathbf{i} - \frac{\partial F}{\partial x'}(x', y') \sin \alpha \mathbf{j} + \frac{\partial F}{\partial y'}(x', y') \sin \alpha \mathbf{i} + \frac{\partial F}{\partial y'}(x', y') \cos \alpha \mathbf{j} \\ &= \frac{\partial F}{\partial x'}(x', y') (\cos \alpha \mathbf{i} - \sin \alpha \mathbf{j}) + \frac{\partial F}{\partial y'}(x', y') (\sin \alpha \mathbf{i} + \cos \alpha \mathbf{j}) \\ &= \frac{\partial F}{\partial x'}(x', y') \begin{bmatrix} \mathbf{i} & \mathbf{j} \end{bmatrix} \begin{bmatrix} \cos \alpha \\ -\sin \alpha \end{bmatrix} + \frac{\partial F}{\partial y'}(x', y') \begin{bmatrix} \mathbf{i} & \mathbf{j} \end{bmatrix} \begin{bmatrix} \sin \alpha \\ \cos \alpha \end{bmatrix} \\ &= \frac{\partial F}{\partial x'}(x', y') \mathbf{i}' + \frac{\partial F}{\partial y'}(x', y') \mathbf{j}'\end{aligned}$$

[NOT SURE - I will ask about this one tomorrow]

(a, b) corresponds to a shifted "origin," α corresponds to angle for which the whole coordinate system is rotated.

Ex. 5: We may obtain any affine orthogonal coordinate system by rotating the "standard" Cartesian coordinates via (1.7) and then applying a rescaling.

Chapter 2

Chapter 2

Ex. 6: See diagram.

Note: Diagrams will be added later for Ex. 7-12

Note: For Ex 7-12, let h denote the distance from P^* to P , where P^* is a point arbitrarily close to P along the appropriate direction for which we are taking each directional derivative. Define $f(h) := F(P^*)$, i.e. parametrize along the unit vector emanating from P in the direction of l (note $f(0) = F(P)$). Also, for points A, B , AB indicates the (unsigned) length of the vector from A to B .

Ex. 7:

$$\begin{aligned}f(h) &= \sqrt{F(P)^2 + h^2} \\f'(h) &= \frac{h}{\sqrt{F(P)^2 + h^2}} \\ \frac{dF(p)}{dl} &= f'(0)\end{aligned}$$

Ex. 8: We have

$$\begin{aligned}f(h) &= \frac{1}{AP - h} \\f'(h) &= -\frac{-1}{(AP - h)^2} \\ &= \frac{1}{(AP - h)^2}\end{aligned}$$

so

$$\begin{aligned}\frac{dF(p)}{dl} &= f'(0) \\ &= \frac{1}{(AP)^2}\end{aligned}$$

Ex. 9: Let ϕ denote the measure of angle OP^*P . By the Law of Sines, we have

$$\begin{aligned} \frac{\sin(F(P^*))}{AP-h} &= \frac{\sin(\pi-\phi)}{OA} \\ &= \frac{\sin(\phi)}{OA} \\ \frac{\sin\phi}{OP} &= \frac{\sin(F(P)-F(P^*))}{h} \end{aligned}$$

From the second equation, we obtain

$$\begin{aligned} \sin\phi &= \frac{OP \sin(F(P)-F(P^*))}{h} \\ &= \frac{OP [\sin(F(P)) \cos(F(P^*)) - \cos(F(P)) \sin(F(P^*))]}{h} \end{aligned}$$

The, from the first equation, we have

$$\begin{aligned} \frac{\sin(F(P^*))}{AP-h} &= \frac{OP [\sin(F(P)) \cos(F(P^*)) - \cos(F(P)) \sin(F(P^*))]}{(OA)h} \\ (OA)h \sin(F(P^*)) &= (OP)(AP-h) [\sin(F(P)) \cos(F(P^*)) - \cos(F(P)) \sin(F(P^*))] \\ (OA)h \tan(F(P^*)) &= (OP)(AP-h) \sin(F(P)) - (OP)(AP-h) \cos(F(P)) \tan(F(P^*)) \\ ((OA)h + (OP)(AP-h) \cos(F(P))) \tan(F(P^*)) &= (OP)(AP-h) \sin(F(P)) \\ \tan(F(P^*)) &= \frac{(OP)(AP-h) \sin(F(P))}{(OA)h + (OP)(AP-h) \cos(F(P))} \\ F(P^*) &= \arctan \left[\frac{(OP)(AP-h) \sin(F(P))}{(OA)h + (OP)(AP-h) \cos(F(P))} \right] \end{aligned}$$

Thus,

$$\begin{aligned} f(h) &= \arctan \left[\frac{(OP)(AP-h) \sin(F(P))}{(OA)h + (OP)(AP-h) \cos(F(P))} \right] \\ f'(h) &= \frac{-(OP) \sin(F(P)) [(OA)h + (OP)(AP-h) \cos(F(P))] - (OP) \sin(F(P)) (AP-h) [(OA)h + (OP)(AP-h) \cos(F(P))]}{[(OA)h + (OP)(AP-h) \cos(F(P))]^2} \\ &= \frac{-(OP) \sin(F(P)) [(OA)h + (OP)(AP-h) \cos(F(P))] - (OP) \sin(F(P)) (AP-h) [(OA)h + (OP)(AP-h) \cos(F(P))]}{[(OA)h + (OP)(AP-h) \cos(F(P))]^2 + [(OP)(AP-h) \sin(F(P))]^2} \end{aligned}$$

$$\begin{aligned}
\frac{dF(p)}{dl} &= f'(0) \\
&= \frac{-(OP) \sin(F(P)) [(OP)(AP) \cos(F(P))] - (OP) \sin(F(P)) (AP) [(OA) - (OP)(AP) \cos(F(P))]}{[(OP)(AP) \cos(F(P))]^2 + [(OP)(AP) \sin(F(P))]^2} \\
&= \frac{-(OP) \sin(F(P)) (OP)(AP) \cos(F(P)) - (OP) \sin(F(P)) (AP)(OA) + (OP) \sin(F(P)) (AP)(OP)}{(OP)^2 (AP)^2 [\cos^2(F(P)) + \sin^2(F(P))]} \\
&= \frac{-(OP) \sin(F(P)) (AP)(OA)}{(OP)^2 (AP)^2} \\
&= \frac{-(OA)}{(OP)(AP)} \sin(F(P))
\end{aligned}$$

Ex. 10: Clearly $F(P^*) = F(P)$ for any choice P^* in such a direction. Thus, f is constant, and we have

$$\frac{dF(p)}{dl} = 0$$

Ex. 11: Put d as the distance between P and the line from A to B . As with the previous problem, the distance from P^* to line \overleftrightarrow{AB} is also d . Thus,

$$\begin{aligned}
F(P) &= \frac{1}{2} (AB) d \\
F(P^*) &= \frac{1}{2} (AB) d,
\end{aligned}$$

and we have $F(P^*) = F(P)$, so $\frac{dF(p)}{dl} = 0$ as before.

Ex. 12: Drop a perpendicular from P to \overleftrightarrow{AB} . Let K be this point of intersection. Note that the length $AK = F(P) + h$. Then,

$$\begin{aligned}
f(h) &= \frac{1}{2} (AB) (F(P) + h) \\
f'(h) &= \frac{1}{2} AB
\end{aligned}$$

$$\begin{aligned}
\frac{dF(p)}{dl} &= f'(0) \\
&= \frac{1}{2} AB
\end{aligned}$$

Ex. 13: (7) The gradient will point in direction \overrightarrow{AP} , and will have magnitude 1.

(8) [Not sure]

(9) The gradient will point in direction \overrightarrow{AP} (in the same direction as was asked for the directional derivative), and thus will have magnitude

$$\frac{(OA)}{(OP)(AP)} \sin(F(P))$$

(note $F(P)$ is assumed to satisfy $F(P) \leq \pi$)

(10) The gradient will point in direction perpendicular to \overleftrightarrow{AB} , and will have magnitude 1.

(11),(12) The gradient will point in the direction perpendicular to \overleftrightarrow{AB} (in the same direction as was asked for the directional derivative in Ex.12), and thus will have magnitude

$$\frac{1}{2}AB.$$

Ex. 14: The directional derivative in direction L would then correspond to the projection of ∇f onto L .

Ex. 15: [See diagram]

$$\|R(\alpha + h) - R(\alpha)\|^2 = 1 + 1 - 2 \cos(h)$$

by the Law of Cosines. So,

$$\begin{aligned} \|R(\alpha + h) - R(\alpha)\|^2 &= 2 - 2 \cos(h) \\ \|R(\alpha + h) - R(\alpha)\| &= \sqrt{2 - 2 \cos(h)} \\ &= \sqrt{2 - 2 \cos\left(2\frac{h}{2}\right)} \\ &= \sqrt{2 - 2\left(\sin^2 \frac{h}{2}\right)} \\ &= \sqrt{4 \sin^2 \frac{h}{2}} \\ &= 2 \sin \frac{h}{2}. \end{aligned}$$

Ex. 16:

$$\lim_{h \rightarrow 0} \frac{2 \sin \frac{h}{2}}{h} = \lim_{h \rightarrow 0} \frac{2\left(\frac{1}{2}\right) \cos \frac{h}{2}}{1},$$

by L'Hospital's rule,

$$\begin{aligned} &= \lim_{h \rightarrow 0} \cos \frac{h}{2} \\ &= 1. \end{aligned}$$

Ex. 17:

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{2 \sin \frac{h}{2}}{h} &= \lim_{h \rightarrow 0} \frac{\sin \frac{h}{2}}{\frac{h}{2}} \\ &= \lim_{h \rightarrow 0} \frac{\sin \left(0 + \frac{h}{2}\right) - \sin(0)}{\frac{h}{2}} \\ &= \sin'(0) \\ &= \cos(0) \\ &= 1. \end{aligned}$$

Ex. 18: We have

$$R(\alpha) \cdot R'(\alpha) = 0.$$

Differentiating both sides, we obtain

$$R'(\alpha) \cdot R'(\alpha) + R(\alpha) \cdot R''(\alpha) = 0.$$

But, $R'(\alpha)$ is of unit length, so we have

$$\begin{aligned} 1 + R(\alpha) \cdot R''(\alpha) &= 0 \\ R(\alpha) \cdot R''(\alpha) &= -1. \end{aligned}$$

Now, let θ be the angle between $R(\alpha)$, $R''(\alpha)$. We thus have

$$\begin{aligned} \|R(\alpha)\| \|R''(\alpha)\| \cos \theta &= -1 \\ \|R''(\alpha)\| \cos \theta &= -1, \end{aligned}$$

since $R(\alpha)$ is of unit length. Now, let h be arbitrarily small. Since $\|R(\alpha)\| = \|R(\alpha + h)\| = \|R'(\alpha + h)\| = \|R'(\alpha)\| = 1$, we have by congruent triangles that $\|R'(\alpha + h) - R'(\alpha)\| = \|R(\alpha + h) - R(\alpha)\|$. Thus,

$$\begin{aligned} \|R''(\alpha)\| &= \lim_{h \rightarrow 0} \frac{\|R'(\alpha + h) - R'(\alpha)\|}{h} \\ &= \lim_{h \rightarrow 0} \frac{\|R(\alpha + h) - R(\alpha)\|}{h} \\ &= \|R'(\alpha)\| \\ &= 1. \end{aligned}$$

Thus, $R''(\alpha)$ is of unit length. We then have

$$\cos \theta = -1,$$

which implies that $\theta = \pi$, or that $R''(\alpha)$ points in the opposite direction as $R(\alpha)$.

Chapter 3

Chapter 3

Ex. 19: We may construct a three-dimensional Cartesian coordinate system as follows: Fix an origin O , then pick three points A, B, C such that the vectors $\overrightarrow{OA}, \overrightarrow{OB}, \overrightarrow{OC}$ form an orthonormal system. Define $\mathbf{i} = \overrightarrow{OA}$, $\mathbf{j} = \overrightarrow{OB}$, $\mathbf{k} = \overrightarrow{OC}$. Note that in this coordinate system, A, B, C have coordinates

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

respectively, and a vector \mathbf{V} connecting the origin to a point with coordinates

$$\begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix}$$

can be expressed by the linear combination

$$\mathbf{V} = x_0\mathbf{i} + y_0\mathbf{j} + z_0\mathbf{k}.$$

Ex. 20: Since our space is three-dimensional, there are three continuous degrees of freedom associated with our choice of origin O . The choice of the direction of the " x "-axis yield another two continuous degrees of freedom (note the bijection between the direction of the x -axis and a point on the unit sphere centered at O). Finally, the " y "-axis may be chosen to lie along any line orthogonal to the x -axis; the set of all such lines lie in a plane, hence our choice of direction for the y -axis yields the sixth continuous degree of freedom (there is a bijection between the set of all such directions and points on the unit circle which lies in this plane orthogonal to the x -axis).

Ex. 21: Let P be an arbitrary point in a two-dimensional Euclidean space with polar coordinates r, θ . Assume P has cartesian coordinates (x, y) . Define P' to be the point along the pole that is distance x from the origin. Note that by the orthogonality of the x, y axes, we may form a right triangle with P , the origin O , and P' . Note that $OP' = x$ and $PP' = y$; hence by the properties of right triangles, we have

$$\begin{aligned}\frac{x}{r} &= \cos \theta \\ \frac{y}{r} &= \sin \theta,\end{aligned}$$

or

$$\begin{aligned}x &= r \cos \theta \\ y &= r \sin \theta.\end{aligned}$$

Ex. 22: We see from the above that

$$\begin{aligned}x^2 + y^2 &= r^2 \cos^2 \theta + r^2 \sin^2 \theta \\ &= r^2,\end{aligned}$$

hence we may solve for r (taken to be non-negative):

$$r = \sqrt{x^2 + y^2}.$$

Also,

$$\begin{aligned}\frac{y}{x} &= \frac{r \sin \theta}{r \cos \theta} \\ &= \tan \theta,\end{aligned}$$

so

$$\theta = \arctan \frac{y}{x}.$$

Ex. 23: Define the x and y coordinate of some arbitrary point P to be the Cartesian system of coordinates defined by applying Ex. 21 to the coordinate plane fixed in the definition of our cylindrical coordinates. Simply define the z (Cartesian) coordinate to be the signed distance from P to the coordinate plane

(note the orthogonality of x, y, z by the definition of distance to a plane - and also that x, y do not depend on z). The equations for x, y then follow from Ex. 21, and the z (Cartesian) coordinate is equal to the z (cylindrical) by definition.

Ex. 24: The inverse relationships for r, θ follow from Ex. 22, and the identity $z(x, y, z) = z$ follows trivially from 23.

Ex. 25: Let P be a point with spherical coordinates r, θ, ϕ . Let the x -axis be the polar axis, and the y -axis lie in the coordinate plane and point in the direction orthogonal to the polar axis (chosen in accordance to the right-hand rule). Finally, let the z -axis be the longitudinal axis. Since the z -coordinate length OP' , where P' is the orthogonal projection of P onto the longitudinal axis, we have by the properties of right triangles,

$$z = r \cos \theta.$$

Now, project P onto the coordinate plane, and denote this point P'' . We clearly have the length $OP'' = r \sin \theta$. Thus, by considering the right triangle determined by the points O, P'' , and the polar axis, we have

$$\begin{aligned} x &= (OP'') \cos \phi \\ &= r \sin \theta \cos \phi \\ y &= (OP'') \sin \phi \\ &= r \sin \theta \sin \phi. \end{aligned}$$

Ex. 26: From Ex. 25, we have

$$\begin{aligned} \sqrt{x^2 + y^2 + z^2} &= \sqrt{r^2 \sin^2 \theta \cos^2 \phi + r^2 \sin^2 \theta \sin^2 \phi + r^2 \cos^2 \theta} \\ &= r \sqrt{\sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi + \cos^2 \theta} \\ &= r \sqrt{\sin^2 \theta (\cos^2 \phi + \sin^2 \phi) + \cos^2 \theta} \\ &= r \sqrt{\sin^2 \theta + \cos^2 \theta} \\ &= r, \end{aligned}$$

so

$$r(x, y, z) = \sqrt{x^2 + y^2 + z^2}.$$

Also, $z/r = \cos \theta$, so

$$\begin{aligned} \theta(x, y, z) &= \arccos \frac{z}{r} \\ &= \arccos \frac{z}{\sqrt{x^2 + y^2 + z^2}}. \end{aligned}$$

Finally,

$$\begin{aligned}\frac{y}{x} &= \frac{r \sin \theta \sin \phi}{r \sin \theta \cos \phi} \\ &= \tan \phi,\end{aligned}$$

so

$$\phi(x, y, z) = \arctan \frac{y}{x}.$$

Chapter 4

Chapter 4

Ex. 27:

$$\begin{aligned}\det J &= \det \begin{bmatrix} \frac{x}{\sqrt{x^2+y^2}} & \frac{y}{\sqrt{x^2+y^2}} \\ \frac{-y}{x^2+y^2} & \frac{x}{x^2+y^2} \end{bmatrix} \\ &= \frac{x^2 + y^2}{(x^2 + y^2) \sqrt{x^2 + y^2}} \\ &= \frac{1}{\sqrt{x^2 + y^2}}.\end{aligned}$$

Ex. 28:

$$\begin{aligned}J(1,1) &= \begin{bmatrix} \frac{1}{\sqrt{1^2+1^2}} & \frac{1}{\sqrt{1^2+1^2}} \\ \frac{-1}{1^2+1^2} & \frac{1}{1^2+1^2} \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}.\end{aligned}$$

Ex. 29:

$$\begin{aligned}\det J' &= \det \begin{bmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{bmatrix} \\ &= r (\cos^2 \theta + \sin^2 \theta) \\ &= r,\end{aligned}$$

Using the relationship $r = \sqrt{x^2 + y^2}$, we have $\det J \det J' = 1$.

Ex. 30:

$$\begin{aligned} J' \left(\sqrt{2}, \frac{\pi}{4} \right) &= \begin{bmatrix} \cos \frac{\pi}{4} & -\sqrt{2} \sin \frac{\pi}{4} \\ \sin \frac{\pi}{4} & \sqrt{2} \cos \frac{\pi}{4} \end{bmatrix} \\ &= \begin{bmatrix} \frac{\sqrt{2}}{2} & -1 \\ \frac{\sqrt{2}}{2} & 1 \end{bmatrix}. \end{aligned}$$

Ex. 31: We evaluate the product

$$\begin{aligned} JJ' &= \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} \frac{\sqrt{2}}{2} & -1 \\ \frac{\sqrt{2}}{2} & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \end{aligned}$$

as desired.

Ex. 32:

$$\begin{aligned} J'(x, y) &= \begin{bmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{bmatrix} \\ &= \begin{bmatrix} \frac{x}{r} & -y \\ \frac{y}{r} & x \end{bmatrix} \\ &= \begin{bmatrix} \frac{x}{\sqrt{x^2+y^2}} & -y \\ \frac{y}{\sqrt{x^2+y^2}} & x \end{bmatrix}, \end{aligned}$$

so

$$\begin{aligned} JJ' &= \begin{bmatrix} \frac{x}{\sqrt{x^2+y^2}} & \frac{y}{\sqrt{x^2+y^2}} \\ \frac{-y}{x^2+y^2} & \frac{x}{x^2+y^2} \end{bmatrix} \begin{bmatrix} \frac{x}{\sqrt{x^2+y^2}} & -y \\ \frac{y}{\sqrt{x^2+y^2}} & x \end{bmatrix} \\ &= \begin{bmatrix} \frac{x^2}{x^2+y^2} + \frac{y^2}{x^2+y^2} & 0 \\ 0 & \frac{x^2}{x^2+y^2} + \frac{y^2}{x^2+y^2} \end{bmatrix} \\ &= I, \end{aligned}$$

similarly, $J'J = I$. Thus, J, J' are inverses of each other.

Ex. 33: We use

$$\begin{aligned} r(x, y, z) &= \sqrt{x^2 + y^2 + z^2} \\ \theta(x, y, z) &= \arccos \frac{z}{\sqrt{x^2 + y^2 + z^2}} \\ \phi(x, y, z) &= \arctan \frac{y}{x} \end{aligned}$$

Note from our computation of the Laplacian in spherical coordinates, we have (after substituting expressions for x, y, z to obtain these results in terms of r, θ, ϕ):

$$\begin{aligned}\frac{\partial r}{\partial x} &= \sin \theta \cos \phi \\ \frac{\partial r}{\partial y} &= \sin \theta \sin \phi \\ \frac{\partial r}{\partial z} &= \cos \theta\end{aligned}$$

$$\begin{aligned}\frac{\partial \theta}{\partial x} &= \frac{\cos \theta \cos \phi}{r} \\ \frac{\partial \theta}{\partial y} &= \frac{\cos \phi}{r \sin \theta} \\ \frac{\partial \theta}{\partial z} &= -\frac{\sin \theta}{r}\end{aligned}$$

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= -\frac{\sin \phi}{r \sin \theta} \\ \frac{\partial \phi}{\partial y} &= \cos \phi \sin \theta \\ \frac{\partial \phi}{\partial z} &= 0.\end{aligned}$$

Thus,

$$\begin{aligned}J(r, \theta, \phi) &= \begin{bmatrix} \frac{\partial r}{\partial x} & \frac{\partial r}{\partial y} & \frac{\partial r}{\partial z} \\ \frac{\partial \theta}{\partial x} & \frac{\partial \theta}{\partial y} & \frac{\partial \theta}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{bmatrix} \\ &= \begin{bmatrix} \sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \\ \frac{\cos \theta \cos \phi}{r} & \frac{\cos \phi}{r \sin \theta} & -\frac{\sin \theta}{r} \\ -\frac{\sin \phi}{r \sin \theta} & \cos \phi \sin \theta & 0 \end{bmatrix}.\end{aligned}$$

We then compute

$$\begin{aligned}J'(r, \theta, \phi) &= \begin{bmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \phi} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \phi} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \phi} \end{bmatrix} \\ &= \begin{bmatrix} \sin \theta \cos \phi & r \cos \theta \cos \phi & -r \sin \theta \sin \phi \\ \sin \theta \sin \phi & r \cos \theta \sin \phi & r \sin \theta \cos \phi \\ \cos \theta & -r \sin \theta & 0 \end{bmatrix},\end{aligned}$$

So

$$\begin{aligned}
JJ' &= \begin{bmatrix} \sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \\ \frac{\cos \theta \cos \phi}{r} & \frac{\cos \phi}{r \sin \theta} & -\frac{\sin \theta}{r} \\ -\frac{\sin \phi}{r \sin \theta} & \cos \phi \sin \phi & 0 \end{bmatrix} \begin{bmatrix} \sin \theta \cos \phi & r \cos \theta \cos \phi & -r \sin \theta \sin \phi \\ \sin \theta \sin \phi & r \cos \theta \sin \phi & r \sin \theta \cos \phi \\ \cos \theta & -r \sin \theta & 0 \end{bmatrix} \\
&= \begin{bmatrix} \cos^2 \theta + \cos^2 \phi \sin^2 \theta + \sin^2 \theta \sin^2 \phi & -r \cos \theta \sin \theta + r \cos \theta \cos^2 \phi \sin \theta + r \cos \theta \sin^2 \theta \cos \phi \\ -\frac{1}{r} \cos \theta \sin \theta + \frac{1}{r} \cos \phi \sin \phi + \frac{1}{r} \cos \theta \cos^2 \phi \sin \theta & \sin^2 \theta + (\cos \theta) \frac{\cos \phi}{\sin \theta} \sin \phi + \cos^2 \theta \cos \phi \\ -\frac{1}{r} \cos \phi \sin \phi + \cos \phi \sin \theta \sin^2 \phi & r \cos \theta \cos \phi \sin^2 \phi - (\cos \theta) \frac{\cos \phi}{\sin \theta} \sin \theta \end{bmatrix} \\
&= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
\end{aligned}$$

[Note: Something may be off with the computation of J]

Ex. 34: We compute

$$\begin{aligned}
\frac{\partial^2 f(\mu, \nu)}{\partial \mu^2} &= \frac{\partial}{\partial \mu} \left[\frac{\partial F}{\partial a} \frac{\partial A}{\partial \mu} + \frac{\partial F}{\partial b} \frac{\partial B}{\partial \mu} + \frac{\partial F}{\partial c} \frac{\partial C}{\partial \mu} \right] \\
&= \frac{\partial}{\partial \mu} \left[\frac{\partial F}{\partial a} \right] \frac{\partial A}{\partial \mu} + \frac{\partial F}{\partial a} \frac{\partial}{\partial \mu} \left[\frac{\partial A}{\partial \mu} \right] \\
&\quad + \frac{\partial}{\partial \mu} \left[\frac{\partial F}{\partial b} \right] \frac{\partial B}{\partial \mu} + \frac{\partial F}{\partial b} \frac{\partial}{\partial \mu} \left[\frac{\partial B}{\partial \mu} \right] \\
&\quad + \frac{\partial}{\partial \mu} \left[\frac{\partial F}{\partial c} \right] \frac{\partial C}{\partial \mu} + \frac{\partial F}{\partial c} \frac{\partial}{\partial \mu} \left[\frac{\partial C}{\partial \mu} \right]
\end{aligned}$$

by the product rule. We continue:

$$\begin{aligned}
\frac{\partial f(\mu, \nu)}{\partial \mu^2} &= \left[\frac{\partial^2 F}{\partial a^2} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial b} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial A}{\partial \mu} + \frac{\partial F}{\partial a} \frac{\partial^2 A}{\partial \mu^2} \\
&\quad + \left[\frac{\partial^2 F}{\partial a \partial b} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b^2} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial B}{\partial \mu} + \frac{\partial F}{\partial b} \frac{\partial^2 B}{\partial \mu^2} \\
&\quad + \left[\frac{\partial^2 F}{\partial a \partial c} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial c^2} \frac{\partial C}{\partial \mu} \right] \frac{\partial C}{\partial \mu} + \frac{\partial F}{\partial c} \frac{\partial^2 C}{\partial \mu^2}.
\end{aligned}$$

Ex. 36

$$\begin{aligned} \frac{\partial f(\mu, \nu)}{\partial \mu^2} &= \left[\frac{\partial^2 F}{\partial a^2} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial b} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial A}{\partial \mu} + \frac{\partial F}{\partial a} \frac{\partial^2 A}{\partial \mu^2} \\ &\quad + \left[\frac{\partial^2 F}{\partial a \partial b} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b^2} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial B}{\partial \mu} + \frac{\partial F}{\partial b} \frac{\partial^2 B}{\partial \mu^2} \\ &\quad + \left[\frac{\partial^2 F}{\partial a \partial c} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial c^2} \frac{\partial C}{\partial \mu} \right] \frac{\partial C}{\partial \mu} + \frac{\partial F}{\partial c} \frac{\partial^2 C}{\partial \mu^2} \\ &= \frac{\partial^2 F}{\partial a^i \partial a^j} \frac{\partial A^j}{\partial \mu} \frac{\partial A^i}{\partial \mu} + \frac{\partial F}{\partial a^i} \frac{\partial^2 A^i}{\partial \mu^2} \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 f(\mu, \nu)}{\partial \mu \partial \nu} &= \left[\frac{\partial^2 F}{\partial a^2} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial b} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial A}{\partial \nu} + \frac{\partial F}{\partial a} \frac{\partial^2 A}{\partial \mu \partial \nu} \\ &\quad + \left[\frac{\partial^2 F}{\partial a \partial b} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b^2} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial B}{\partial \nu} + \frac{\partial F}{\partial b} \frac{\partial^2 B}{\partial \mu \partial \nu} \\ &\quad + \left[\frac{\partial^2 F}{\partial a \partial c} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial c^2} \frac{\partial C}{\partial \mu} \right] \frac{\partial C}{\partial \nu} + \frac{\partial F}{\partial c} \frac{\partial^2 C}{\partial \mu \partial \nu} \\ &= \frac{\partial^2 F}{\partial a^i \partial a^j} \frac{\partial A^j}{\partial \mu} \frac{\partial A^i}{\partial \nu} + \frac{\partial F}{\partial a^i} \frac{\partial^2 A^i}{\partial \mu \partial \nu} \end{aligned}$$

$$\frac{\partial f(\mu, \nu)}{\partial \nu^2} = \frac{\partial^2 F}{\partial a^i \partial a^j} \frac{\partial A^j}{\partial \nu} \frac{\partial A^i}{\partial \nu} + \frac{\partial F}{\partial a^i} \frac{\partial^2 A^i}{\partial \nu^2}$$

Ex. 37 We may generalize the above three equations, setting $\mu^1 = \mu$, $\mu^2 = \nu$, to yield

$$\frac{\partial^2 f(\mu, \nu)}{\partial \mu^\alpha \partial \mu^\beta} = \frac{\partial^2 F}{\partial a^i \partial a^j} \frac{\partial A^j}{\partial \mu^\alpha} \frac{\partial A^i}{\partial \mu^\beta} + \frac{\partial F}{\partial a^i} \frac{\partial^2 A^i}{\partial \mu^\alpha \partial \mu^\beta}.$$

This encompasses three separate identities, since we have been assuming that we may switch the order of partial differentiation throughout.

Ex. 38 [Not finished]

Ex. 39 Begin with

$$\cos \arccos x = x$$

and differentiate both sides:

$$\begin{aligned} \frac{d}{dx} [\cos \arccos x] &= 1 \\ -(\sin \arccos x) \frac{d}{dx} [\arccos x] &= 1 \\ \frac{d}{dx} [\arccos x] &= \frac{-1}{(\sin \arccos x)} \end{aligned}$$

By examining triangles with unit hypotenuse, we obtain

$$\sin \arccos x = \pm \sqrt{1 - x^2},$$

so

$$\frac{d}{dx} [\arccos x] = \pm \frac{1}{\sqrt{1 - x^2}}$$

Ex. 40: We know that f, g satisfy

$$g'(f(x)) f'(x) = 1.$$

Differentiating both sides, we obtain

$$\begin{aligned} \frac{d}{dx} [g'(f(x))] f'(x) + g'(f(x)) \frac{d}{dx} [f'(x)] &= 0 \\ g''(f(x)) f'(x) f'(x) + g'(f(x)) f''(x) &= 0 \end{aligned}$$

$$g''(f(x)) [f'(x)]^2 + g'(f(x)) f''(x) = 0 \quad (4.1)$$

as desired.

Ex. 41: We compute

$$\begin{aligned} f'(x) &= e^x \\ f''(x) &= e^x \\ g'(x) &= \frac{1}{x} \\ g''(x) &= -\frac{1}{x^2}, \end{aligned}$$

So

$$\begin{aligned} g''(f(x)) [f'(x)]^2 + g'(f(x)) f''(x) &= -\frac{1}{e^{2x}} e^{2x} + \frac{1}{e^x} e^x \\ &= -1 + 1 \\ &= 0, \end{aligned}$$

as desired.

Ex. 42: We compute

$$\begin{aligned} f'(x) &= \frac{1}{\sqrt{1-x^2}} \\ f''(x) &= -2x \frac{1}{2} (1-x^2)^{-3/2} \\ &= -x (1-x^2)^{-3/2} \\ g'(x) &= -\sin(x) \\ g''(x) &= -\cos(x), \end{aligned}$$

So

$$\begin{aligned} g''(f(x)) [f'(x)]^2 + g'(f(x)) f''(x) &= -\cos(\arccos x) \frac{1}{1-x^2} - \sin(\arccos(x)) \left(-x (1-x^2)^{-3/2}\right) \\ &= -\frac{x}{1-x^2} + \frac{x\sqrt{1-x^2}}{\sqrt{1-x^2}^3} \\ &= -\frac{x}{1-x^2} + \frac{x}{1-x^2} \\ &= 0, \end{aligned}$$

as desired.

Ex. 43: We differentiate both sides of the second-order relationship to obtain

$$\begin{aligned} \frac{d}{dx} \left(g''(f(x)) [f'(x)]^2 + g'(f(x)) f''(x) \right) &= 0 \\ \frac{d}{dx} [g''(f(x)) [f'(x)]^2 + g''(f(x)) \frac{d}{dx} [f'(x)]^2] + \frac{d}{dx} [g'(f(x)) f''(x) + g'(f(x)) \frac{d}{dx} f''(x)] &= 0 \\ g^{(3)}(f(x)) [f'(x)]^3 + g''(f(x)) \cdot 2f'(x) f''(x) + g''(f(x)) f'(x) f''(x) + g'(f(x)) f^{(3)}(x) &= 0 \\ g^{(3)}(f(x)) [f'(x)]^3 + 3g''(f(x)) f'(x) f''(x) + g'(f(x)) f^{(3)}(x) &= 0 \end{aligned}$$

Ex. 44:

Ex. 45:

Ex. 46:

Ex. 47:

Ex. 48: We begin with the identity (note the top indices should be considered "first")

$$J_{i'}^i J_j^{i'} = \delta_j^i,$$

and write out the dependences on unprimed coordinates:

$$J_{i'}^i(Z'(Z)) J_j^{i'}(Z) = \delta_j^i(Z) \quad (4.2)$$

(note, however, that the Krönicker delta is constant with respect to the unprimed coordinates Z). We differentiate both sides of (4.2) with respect to Z^k :

$$\begin{aligned}\frac{\partial}{\partial Z^k} \left[J_{i'}^i(Z'(Z)) J_j^{i'}(Z) \right] &= \frac{\partial}{\partial Z^k} [\delta_j^i(Z)] \\ \frac{\partial}{\partial Z^k} \left[J_{i'}^i(Z'(Z)) J_j^{i'}(Z) \right] &= 0 \\ \frac{\partial}{\partial Z^k} \left[J_{i'}^i(Z'(Z)) \right] J_j^{i'}(Z) + J_{i'}^i(Z'(Z)) \frac{\partial}{\partial Z^k} \left[J_j^{i'}(Z) \right] &= 0,\end{aligned}$$

since differentiation passes through the implied summation over i' . Then, using the definition of the Jacobian,

$$\frac{\partial}{\partial Z^k} \left[\frac{\partial Z^i}{\partial Z^{i'}}(Z'(Z)) \right] \frac{\partial Z^{i'}}{\partial Z^j}(Z) + \frac{\partial Z^i}{\partial Z^{i'}}(Z'(Z)) \frac{\partial}{\partial Z^k} \left[\frac{\partial Z^{i'}}{\partial Z^j}(Z) \right] = \mathbf{(4.3)}$$

$$\frac{\partial^2 Z^i}{\partial Z^{k'} \partial Z^{i'}}(Z'(Z)) \frac{\partial Z^{k'}}{\partial Z^k}(Z) \frac{\partial Z^{i'}}{\partial Z^j}(Z) + \frac{\partial Z^i}{\partial Z^{i'}}(Z'(Z)) \frac{\partial^2 Z^{i'}}{\partial Z^k \partial Z^j}(Z) = \mathbf{(4.4)}$$

applying the chain rule to the first term, and implying summation over new index k' . Then, if we define the "Hessian" object

$$J_{k',i'}^i := \frac{\partial^2 Z^i}{\partial Z^{k'} \partial Z^{i'}}(Z')$$

with an analogous definition for $J_{k,i}^{i'}$, we write (4.3) concisely:

$$J_{k',i'}^i J_k^{k'} J_j^{i'} + J_{i'}^i J_{k,j}^{i'} = 0,$$

or, using a renaming of dummy indicex k' to j' and a reversing of the order of partial derivatives,

$$J_{i',j'}^i J_j^{i'} J_k^{j'} + J_{i'}^i J_{j,k}^{i'} = 0.$$

This above tensor relationship represents n^3 identities.

Ex. 49: Since each $J_{i'}^i$ is constant for a transformation from one affine coordinate system to another, each second derivative vanishes, and hence each $J_{i',j'}^i = 0$.

Ex. 50: Begin with the identity derived in Ex. 48:

$$J_{i',j'}^i J_j^{i'} J_k^{j'} + J_{i'}^i J_{j,k}^{i'} = 0,$$

Then, letting k' be arbitrary, we multiply both sides by $J_{k'}^k$, implying summation over k :

$$\begin{aligned} \left[J_{i'j'}^i J_j^{j'} J_k^k + J_{i'j}^i J_{jk}^{j'} \right] J_{k'}^k &= 0 \\ J_{i'j'}^i J_j^{j'} J_k^k J_{k'}^k + J_{i'j}^i J_{jk}^{j'} J_{k'}^k &= 0 \end{aligned}$$

but, $J_k^{j'} J_{k'}^k = \delta_{k'}^{j'}$, so

$$J_{i'j'}^i J_j^{j'} \delta_{k'}^{j'} + J_{i'j}^i J_{jk}^{j'} J_{k'}^k = 0.$$

Note that we have $\delta_{k'}^{j'} = 1$ if and only if $j' = k'$, so the first term is equal to $J_{i'k'}^i J_j^{j'}$. After re-naming $k' = j'$, we obtain

$$J_{i'j'}^i J_j^{j'} + J_{i'j}^i J_{jk}^{j'} J_{j'}^k = 0. \quad (4.5)$$

Ex. 51: Let k' be arbitrary, and multiply both sides of (4.5) by $J_{k'}^j$, implying summation over j :

$$\begin{aligned} \left[J_{i'j'}^i J_j^{j'} + J_{i'j}^i J_{jk}^{j'} J_{j'}^k \right] J_{k'}^j &= 0 \\ J_{i'j'}^i J_j^{j'} J_{k'}^j + J_{i'j}^i J_{jk}^{j'} J_{j'}^k J_{k'}^j &= 0 \\ J_{i'j'}^i \delta_{k'}^{j'} + J_{i'j}^i J_{jk}^{j'} J_{j'}^k J_{k'}^j &= 0 \\ J_{i'j'}^i \delta_{k'}^{j'} + J_{jk}^{j'} J_{i'j}^i J_{j'}^k J_{k'}^j &= 0. \end{aligned}$$

Rename the dummy index in the second term $i' = h'$. Then,

$$J_{i'j'}^i \delta_{k'}^{j'} + J_{jk}^{h'} J_{h'}^i J_{j'}^k J_{k'}^j = 0.$$

Noting that the first term is zero for all $i' \neq k'$, and setting $k' = i'$:

$$J_{i'j'}^i + J_{jk}^{h'} J_{h'}^i J_{j'}^k J_{i'}^j = 0.$$

We then may re-introduce k' as a dummy index:

$$J_{i'j'}^i + J_{jk}^{k'} J_{k'}^i J_{j'}^k J_{i'}^j = 0.$$

Then, switch the roles of j, k as dummy indices:

$$J_{i'j'}^i + J_{kj}^{k'} J_{k'}^i J_{j'}^j J_{i'}^k = 0$$

Ex. 52: Return to

$$J_{i'j'}^i J_j^{i'} J_k^{j'} + J_{i'}^i J_{jk}^{i'} = 0,$$

and write out the dependences

$$\begin{aligned} J_{i'j'}^i (Z'(Z)) J_j^{i'} (Z) J_k^{j'} (Z) + J_{i'}^i (Z'(Z)) J_{jk}^{i'} (Z) &= 0 \\ \frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{j'}} (Z'(Z)) \frac{\partial Z^{i'}}{\partial Z^j} (Z) \frac{\partial Z^{j'}}{\partial Z^k} (Z) + \frac{\partial Z^i}{\partial Z^{i'}} (Z'(Z)) \frac{\partial^2 Z^{i'}}{\partial Z^j \partial Z^k} (Z) &= 0 \end{aligned}$$

Then, differentiate both sides with respect to Z^m :

$$\begin{aligned} 0 &= \frac{\partial}{\partial Z^m} \left[\frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{j'}} (Z'(Z)) \frac{\partial Z^{i'}}{\partial Z^j} (Z) \frac{\partial Z^{j'}}{\partial Z^k} (Z) + \frac{\partial Z^i}{\partial Z^{i'}} (Z'(Z)) \frac{\partial^2 Z^{i'}}{\partial Z^j \partial Z^k} (Z) \right] \\ &= \frac{\partial}{\partial Z^m} \left[\frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{j'}} (Z'(Z)) \right] \frac{\partial Z^{i'}}{\partial Z^j} (Z) \frac{\partial Z^{j'}}{\partial Z^k} (Z) + \frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{j'}} (Z'(Z)) \frac{\partial}{\partial Z^m} \left[\frac{\partial Z^{i'}}{\partial Z^j} (Z) \right] \frac{\partial Z^{j'}}{\partial Z^k} (Z) + \\ &\quad + \frac{\partial}{\partial Z^m} \left[\frac{\partial Z^i}{\partial Z^{i'}} (Z'(Z)) \right] \frac{\partial^2 Z^{i'}}{\partial Z^j \partial Z^k} (Z) + \frac{\partial Z^i}{\partial Z^{i'}} (Z'(Z)) \frac{\partial}{\partial Z^m} \left[\frac{\partial^2 Z^{i'}}{\partial Z^j \partial Z^k} (Z) \right] \\ &= \left[\frac{\partial^3 Z^i}{\partial Z^{i'} \partial Z^{j'} \partial Z^{m'}} (Z'(Z)) \frac{\partial Z^{m'}}{\partial Z^m} (Z) \right] \frac{\partial Z^{i'}}{\partial Z^j} (Z) \frac{\partial Z^{j'}}{\partial Z^k} (Z) + \frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{j'}} (Z'(Z)) \frac{\partial^2 Z^{i'}}{\partial Z^m \partial Z^j} (Z) \frac{\partial Z^{j'}}{\partial Z^k} (Z) \\ &\quad + \left[\frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{m'}} (Z'(Z)) \frac{\partial Z^{m'}}{\partial Z^m} (Z) \right] \frac{\partial^2 Z^{i'}}{\partial Z^j \partial Z^k} (Z) + \frac{\partial Z^i}{\partial Z^{i'}} (Z'(Z)) \frac{\partial^3 Z^{i'}}{\partial Z^j \partial Z^k \partial Z^m} (Z) \\ &= J_{i'j'm'}^i J_m^{m'} J_j^{i'} J_k^{j'} + J_{i'j'}^i J_{jm}^{i'} J_k^{j'} + J_{i'j'}^i J_j^{i'} J_{km}^{j'} + J_{i'm'}^i J_m^{m'} J_{jk}^{i'} + J_{i'}^i J_{jkm}^{i'}, \end{aligned}$$

so, setting $k' = m'$ as a dummy index:

$$J_{i'j'k'}^i J_j^{i'} J_k^{j'} J_m^{k'} + J_{i'j'}^i J_k^{j'} J_{jm}^{i'} + J_{i'j'}^i J_j^{i'} J_{km}^{j'} + J_{i'k'}^i J_{jk}^{i'} J_m^{k'} + J_{i'}^i J_{jkm}^{i'} = 0. \quad (4.6)$$

Then, multiply both sides by $J_{m'}^m$, implying summation over m :

$$\begin{aligned} J_{i'j'k'}^i J_j^{i'} J_k^{j'} J_m^{k'} J_{m'}^m + J_{i'j'}^i J_k^{j'} J_{jm}^{i'} J_{m'}^m + J_{i'j'}^i J_j^{i'} J_{km}^{j'} J_{m'}^m + J_{i'k'}^i J_{jk}^{i'} J_m^{k'} J_{m'}^m + J_{i'}^i J_{jkm}^{i'} J_{m'}^m &= 0 \\ J_{i'j'k'}^i J_j^{i'} J_k^{j'} \delta_{m'}^{k'} + J_{i'j'}^i J_k^{j'} J_{jm}^{i'} J_{m'}^m + J_{i'j'}^i J_j^{i'} J_{km}^{j'} J_{m'}^m + J_{i'k'}^i J_{jk}^{i'} \delta_{m'}^{k'} + J_{i'}^i J_{jkm}^{i'} J_{m'}^m &= 0, \end{aligned}$$

This holds for all m' , so specifically for $m' = k'$, the above identity reads

$$J_{i'j'k'}^i J_j^{i'} J_k^{j'} + J_{i'j'}^i J_k^{j'} J_{jm}^{i'} J_{k'}^m + J_{i'j'}^i J_j^{i'} J_{km}^{j'} J_{k'}^m + J_{i'k'}^i J_{jk}^{i'} + J_{i'}^i J_{jkm}^{i'} J_{k'}^m = 0 \quad (4.7)$$

Next, in an analogous manner, multiply both sides by $J_{m'}^k$, for arbitrary m' :

$$\begin{aligned} J_{i'j'k'}^i J_j^{j'} J_k^k J_{m'}^k + J_{i'j'}^i J_k^{j'} J_{jm}^m J_{k'}^k J_{m'}^k + J_{i'j'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{m'}^k + J_{i'k'}^i J_{jk}^{j'} J_{m'}^k + J_{i'}^i J_{jkm}^{j'} J_{k'}^k J_{m'}^k &= 0 \\ J_{i'j'k'}^i J_j^{j'} \delta_{m'}^{j'} + J_{i'j'}^i J_k^{j'} J_{jm}^m J_{k'}^k J_{m'}^k + J_{i'j'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{m'}^k + J_{i'k'}^i J_{jk}^{j'} J_{m'}^k + J_{i'}^i J_{jkm}^{j'} J_{k'}^k J_{m'}^k &= 0, \end{aligned}$$

rename the dummy index $h' = j'$ in all but the first term:

$$J_{i'j'k'}^i J_j^{j'} \delta_{m'}^{j'} + J_{i'h'}^i J_k^{h'} J_{jm}^m J_{k'}^k J_{m'}^k + J_{i'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{m'}^k + J_{i'k'}^i J_{jk}^{j'} J_{m'}^k + J_{i'}^i J_{jkm}^{j'} J_{k'}^k J_{m'}^k = 0,$$

then, as in the previous exercises, set $m' = j'$:

$$J_{i'j'k'}^i J_j^{j'} + J_{i'h'}^i J_k^{h'} J_{jm}^m J_{k'}^k J_{j'}^j + J_{i'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{j'}^j + J_{i'k'}^i J_{jk}^{j'} J_{j'}^j + J_{i'}^i J_{jkm}^{j'} J_{k'}^k J_{j'}^j = 0, \quad (4.8)$$

Finally, multiply both sides by $J_{m'}^j$:

$$\begin{aligned} J_{i'j'k'}^i J_j^{j'} J_{m'}^j + J_{i'h'}^i J_k^{h'} J_{jm}^m J_{k'}^k J_{j'}^j J_{m'}^j + J_{i'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{j'}^j J_{m'}^j + J_{i'k'}^i J_{jk}^{j'} J_{j'}^j J_{m'}^j + J_{i'}^i J_{jkm}^{j'} J_{k'}^k J_{j'}^j J_{m'}^j &= 0 \\ J_{i'j'k'}^i \delta_{m'}^{j'} + J_{i'h'}^i J_k^{h'} J_{jm}^m J_{k'}^k J_{j'}^j J_{m'}^j + J_{i'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{j'}^j J_{m'}^j + J_{i'k'}^i J_{jk}^{j'} J_{j'}^j J_{m'}^j + J_{i'}^i J_{jkm}^{j'} J_{k'}^k J_{j'}^j J_{m'}^j &= 0, \end{aligned}$$

rename the dummy index i' to g' in all but the first term:

$$J_{i'j'k'}^i \delta_{m'}^{j'} + J_{g'h'}^i J_k^{h'} J_{jm}^m J_{k'}^k J_{j'}^j J_{m'}^j + J_{g'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{j'}^j J_{m'}^j + J_{g'k'}^i J_{jk}^{j'} J_{j'}^j J_{m'}^j + J_{g'}^i J_{jkm}^{j'} J_{k'}^k J_{j'}^j J_{m'}^j = 0.$$

Then, set $m' = i'$:

$$J_{i'j'k'}^i + J_{g'h'}^i J_k^{h'} J_{jm}^m J_{k'}^k J_{j'}^j J_{i'}^i + J_{g'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{j'}^j J_{i'}^i + J_{g'k'}^i J_{jk}^{j'} J_{j'}^j J_{i'}^i + J_{g'}^i J_{jkm}^{j'} J_{k'}^k J_{j'}^j J_{i'}^i = 0. \quad (4.9)$$

Ex. 53: We have the following relationship

$$Z \left(Z' \left(Z'' (Z) \right) \right) = Z,$$

or for each i ,

$$Z^i \left(Z' \left(Z'' (Z) \right) \right) = Z^i.$$

Differentiating both sides with respect to Z^j , we obtain

$$\frac{\partial}{\partial Z^j} [Z^i (Z' (Z'' (Z)))] = \delta_j^i.$$

Then, we apply the chain rule twice:

$$\begin{aligned}\frac{\partial Z^i}{\partial Z^{i'}} \frac{\partial}{\partial Z^j} [Z' (Z'') (Z)] &= \delta_j^i \\ \frac{\partial Z^i}{\partial Z^{i'}} \frac{\partial Z^{i'}}{\partial Z^{i''}} \frac{\partial}{\partial Z^j} [Z^{i''} (Z)] &= \delta_j^i \\ \frac{\partial Z^i}{\partial Z^{i'}} \frac{\partial Z^{i'}}{\partial Z^{i''}} \frac{\partial Z^{i''}}{\partial Z^j} &= \delta_j^i,\end{aligned}$$

or

$$J_{i'}^i J_{i''}^{i'} J_j^{i''} = \delta_j^i.$$

Chapter 5

Chapter 5

Ex. 61: δ_j^i .

Ex. 62: Assume U is an arbitrary nontrivial linear combination $U^i \mathbf{Z}_i$ of coordinate bases \mathbf{Z}_i . Since

$$U \cdot U > 0$$

and

$$U \cdot U = Z_{ij} U^i U^j,$$

or in matrix notation

$$U \cdot U = U^T Z U,$$

this condition implies $Z = Z_{ij}$ is positive definite.

Ex. 63:

$$\begin{aligned} \|V\| &= \sqrt{V \cdot V} \\ &= \sqrt{Z_{ij} V^i V^j} \end{aligned}$$

Ex. 64: Put $Z = Z_{ij}$. Thus, $Z^{-1} = Z^{ij}$ by definition. Let x be an arbitrary nontrivial vector. Then, define $y = Z^{-1}x$. We have

$$\begin{aligned} y^T &= (Z^{-1}x)^T \\ &= x^T (Z^{-1})^T \\ &= x^T Z^{-1}, \end{aligned}$$

since Z^{-1} is symmetric. Then, since Z is positive definite, note

$$\begin{aligned} 0 &< y^T Z y \\ &= x^T Z^{-1} Z Z^{-1} x \\ &= x^T Z^{-1} x. \end{aligned}$$

Since x was arbitrary, this implies that $Z = Z^{ij} > 0$.

Ex. 65:

$$\begin{aligned} \mathbf{Z}^i \cdot \mathbf{Z}_j &= Z^{ik} \mathbf{Z}_k \cdot \mathbf{Z}_j \\ &= Z^{ik} Z_{kj} \end{aligned}$$

by definition. But,

$$Z^{ik} Z_{kj} = \delta_j^i,$$

so we have

$$\mathbf{Z}^i \cdot \mathbf{Z}_j = \delta_j^i$$

Ex. 66, 67: [Not sure - which coordinate system are we in (if any?)]

Ex. 68: Use the definition

$$\begin{aligned} \mathbf{Z}^i &= Z^{ij} \mathbf{Z}_j \\ Z_{ik} \mathbf{Z}^i &= Z_{ik} Z^{ij} \mathbf{Z}_j \\ &= \delta_k^j \mathbf{Z}_j \\ &= \mathbf{Z}_k. \end{aligned}$$

Thus,

$$\begin{aligned} \mathbf{Z}_k &= Z_{ik} \mathbf{Z}^i \\ &= Z_{ki} \mathbf{Z}^i, \end{aligned}$$

since Z_{ik} is symmetric.

Ex. 69: Examine

$$\begin{aligned} Z_{ki} \mathbf{Z}^i \cdot \mathbf{Z}^j &= Z_{ki} Z^{in} \mathbf{Z}_n \cdot \mathbf{Z}^j \\ &= \delta_k^n \delta_n^j \\ &= \delta_k^j, \end{aligned}$$

since $\delta_k^n \delta_n^j = 1$ iff $k = n$ and $n = j$, or by transitivity, iff $k = j$. Thus, $\mathbf{Z}^i \cdot \mathbf{Z}^j$ determines the matrix inverse of Z_{ki} , which must be Z^{ij} by uniqueness of matrix inverse.

Ex. 70: Because the inverse of a matrix is uniquely determined, we have that \mathbf{Z}^i are uniquely determined.

Ex. 71:

$$\begin{aligned} Z^{ij} Z_{jk} &= \mathbf{Z}^i \cdot \mathbf{Z}^j Z_{jk} \\ &= \mathbf{Z}^i \cdot \mathbf{Z}_k, \end{aligned}$$

from 5.17

$$= \delta_k^i$$

from 5.16.

Ex. 72: We compute

$$\begin{aligned} \mathbf{Z}^1 \cdot \mathbf{Z}_2 &= \left(\frac{1}{3}\mathbf{i} - \frac{1}{3}\mathbf{j} \right) \cdot \mathbf{j} \\ &= \frac{1}{3}\mathbf{i} \cdot \mathbf{j} - \frac{1}{3}\mathbf{j} \cdot \mathbf{j} \\ &= \frac{1}{3} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} - \frac{1}{3} \|\mathbf{j}\|^2 \\ &= \frac{1}{3} (2) (1) \left(\frac{1}{2} \right) - \frac{1}{3} 1^2 \\ &= 0; \end{aligned}$$

thus, $\mathbf{Z}^1, \mathbf{Z}_2$ are orthogonal. We further compute

$$\begin{aligned} \mathbf{Z}^2 \cdot \mathbf{Z}_1 &= \left(-\frac{1}{3}\mathbf{i} + \frac{4}{3}\mathbf{j} \right) \cdot \mathbf{i} \\ &= -\frac{1}{3} \|\mathbf{i}\|^2 + \frac{4}{3} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} \\ &= -\frac{1}{3} (4) + \frac{4}{3} (2) (1) \left(\frac{1}{2} \right) \\ &= 0, \end{aligned}$$

so $\mathbf{Z}^2, \mathbf{Z}_1$ are orthogonal.

Ex. 73:

$$\begin{aligned}
\mathbf{Z}^1 \cdot \mathbf{Z}_1 &= \left(\frac{1}{3}\mathbf{i} - \frac{1}{3}\mathbf{j} \right) \cdot \mathbf{i} \\
&= \frac{1}{3} \|\mathbf{i}\|^2 - \frac{1}{3} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} \\
&= \frac{4}{3} - \frac{2}{3} \left(\frac{1}{2} \right) \\
&= 1. \\
\mathbf{Z}^2 \cdot \mathbf{Z}_2 &= \left(-\frac{1}{3}\mathbf{i} + \frac{4}{3}\mathbf{j} \right) \cdot \mathbf{j} \\
&= -\frac{1}{3} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} + \frac{4}{3} \|\mathbf{j}\|^2 \\
&= -\frac{2}{3} \left(\frac{1}{2} \right) + \frac{4}{3} \\
&= 1.
\end{aligned}$$

Ex. 74:

$$\begin{aligned}
\mathbf{Z}^1 \cdot \mathbf{Z}^2 &= \left(\frac{1}{3}\mathbf{i} - \frac{1}{3}\mathbf{j} \right) \cdot \left(-\frac{1}{3}\mathbf{i} + \frac{4}{3}\mathbf{j} \right) \\
&= -\frac{1}{9} \|\mathbf{i}\|^2 + \frac{4}{9} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} + \frac{1}{9} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} - \frac{4}{9} \|\mathbf{j}\|^2 \\
&= -\frac{4}{9} + \frac{4}{9} + \frac{1}{9} - \frac{4}{9} \\
&= -\frac{3}{9} \\
&= -\frac{1}{3}.
\end{aligned}$$

Ex. 75: Let \mathbf{R} denote the position vector. We compute

$$\begin{aligned}
\mathbf{Z}_3 &= \frac{\partial \mathbf{R}(\mathbf{Z})}{\mathbf{Z}_3} \\
&= \frac{\partial \mathbf{R}(r, \theta, z)}{\partial z}
\end{aligned}$$

for cylindrical coordinates

$$= \lim_{h \rightarrow 0} \frac{\mathbf{R}(r, \theta, z+h) - \mathbf{R}(r, \theta, z)}{h}.$$

But, $\mathbf{R}(r, \theta, z + h) - \mathbf{R}(r, \theta, z)$ is clearly a vector of length h pointing in the z direction; thus, for any h ,

$$\frac{\mathbf{R}(r, \theta, z + h) - \mathbf{R}(r, \theta, z)}{h}$$

is the unit vector pointing in the z direction. This implies \mathbf{Z}_3 is the unit vector pointing in the z direction.

Ex. 76: The computations of the diagonal elements Z_{11} and Z_{22} are the same as for polar coordinates; moreover the zero off-diagonal entries Z_{12} , Z_{21} follow from the orthogonality of \mathbf{Z}_1 , \mathbf{Z}_2 . By definition of cylindrical coordinates, the z axis is perpendicular to the coordinate plane (upon which \mathbf{Z}_1 , \mathbf{Z}_2 lie); thus, since \mathbf{Z}_3 points in the z direction, we have that \mathbf{Z}_3 is perpendicular to both \mathbf{Z}_1 , \mathbf{Z}_2 . This implies that the off-diagonal entries in row 3 and column 3 of Z_{ij} are zero. Moreover, since \mathbf{Z}_3 is of unit length; we have $Z_{33} = \mathbf{Z}_3 \cdot \mathbf{Z}_3 = 1$. Thus, we have

$$Z_{ij} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Now, since Z^{ij} is defined to be the inverse of Z_{ij} , we may easily compute

$$Z^{ij} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & r^{-2} & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

since the inverse of a diagonal matrix (with non-zero diagonal entries, of course) is the diagonal matrix with corresponding reciprocal diagonal entries.

Ex. 77: We have

$$\begin{aligned} \mathbf{Z}^3 &= Z^{3j} \mathbf{Z}_j \\ &= 0\mathbf{Z}_1 + 0\mathbf{Z}_2 + 1\mathbf{Z}_3 \\ &= \mathbf{Z}_3 \end{aligned}$$

Chapter 6

Chapter 6

Ex. 87: Look at

$$Z^{ij} J_i^{i'} J_j^{j'} Z_{j'k'} = Z^{ij} J_i^{i'} J_j^{j'} Z_{jk} J_{j'}^j J_{k'}^k$$

by the tensor property of Z_{jk}

$$\begin{aligned} &= Z^{ij} Z_{jk} J_i^{i'} J_{k'}^k \\ &= \delta_k^i J_i^{i'} J_{k'}^k \\ &= J_k^{i'} J_{k'}^k \\ &= \delta_{k'}^{i'}, \end{aligned}$$

so, in linear algebra terms, we have that $Z^{ij} J_i^{i'} J_j^{j'}$ is the matrix inverse of $Z_{j'k'}$. By uniqueness of matrix inverses, this forces $Z^{ij} J_i^{i'} J_j^{j'} = Z^{i'j'}$, as desired.

Ex. 88: Let Z, Z' be two coordinate systems. Write the unprimed coordinates in terms of the primed coordinates

$$Z = Z(Z').$$

Then,

$$\begin{aligned} \frac{\partial F(Z)}{\partial Z^{i'}} &= \frac{\partial F(Z(Z'))}{\partial Z^{i'}} \\ &= \frac{\partial F}{\partial Z^i} \frac{\partial Z^i}{\partial Z^{i'}} \\ &= \frac{\partial F}{\partial Z^i} J_{i'}^i, \end{aligned}$$

so $\frac{\partial F}{\partial Z^i}$ is a covariant tensor.

Ex. 89: We show the general case (since by the previous exercise, we know that the collection of first partial derivatives is a covariant tensor). Define, given a covariant tensor field T_i

$$\begin{aligned} S_{ij} &= \frac{\partial T_i}{Z^j} \\ S_{i'j'} &= \frac{\partial T_{i'}}{Z^{j'}} \end{aligned}$$

so

$$\begin{aligned} S_{i'j'} &= \frac{\partial T_{i'}}{\partial Z^{j'}} \\ &= \frac{\partial}{\partial Z^{j'}} [T_i J_{i'}^i], \end{aligned}$$

since T is a covariant tensor,

$$\begin{aligned} &= \frac{\partial}{\partial Z^{j'}} [T_i(Z'(Z)) J_{i'}^i(Z')] \\ &= \frac{\partial T_i}{\partial Z^j} \frac{\partial Z^j}{\partial Z^{j'}} J_{i'}^i + T_i J_{i'j'}^i \\ &= S_{ij} J_{j'}^j J_{i'}^i + T_i J_{i'j'}^i \\ &\neq S_{ij} J_{j'}^j J_{i'}^i \end{aligned}$$

(except in the trivial case where $T_i = 0$). Thus, in general, the collection

$$\frac{\partial T_i}{Z^j}$$

is not a covariant tensor.

Ex. 90: Compute

$$\begin{aligned} S_{i'j'} &= \frac{\partial T_{i'}}{\partial Z^{j'}} - \frac{\partial T_{j'}}{\partial Z^{i'}} \\ &= \frac{\partial T_i}{\partial Z^j} J_{j'}^j J_{i'}^i + T_i J_{i'j'}^i - \left[\frac{\partial T_j}{\partial Z^i} J_{i'}^i J_{j'}^j + T_i J_{j'i'}^i \right] \end{aligned}$$

by the above, interchanging the rolls of i', j' for the second term:

$$= \frac{\partial T_i}{\partial Z^j} J_{j'}^j J_{i'}^i + T_i J_{i'j'}^i - \left[\frac{\partial T_j}{\partial Z^i} J_{j'}^j J_{i'}^i + T_i J_{i'j'}^i \right],$$

since $J_{j'i'}^i = J_{i'j'}^i$,

$$\begin{aligned}
&= \frac{\partial T_i}{\partial Z^j} J_{j'}^j J_{i'}^i + T_i J_{i'j'}^i - \frac{\partial T_j}{\partial Z^i} J_{j'}^j J_{i'}^i - T_i J_{i'j'}^i \\
&= \left(\frac{\partial T_i}{\partial Z^j} - \frac{\partial T_j}{\partial Z^i} \right) J_{j'}^j J_{i'}^i \\
&= S_{ij} J_{i'}^i J_{j'}^j,
\end{aligned}$$

so this skew-symmetric part S_{ij} is indeed a covariant tensor.

Ex. 91: Put

$$S^{ij} = \frac{\partial T^i}{\partial Z^j},$$

so

$$\begin{aligned}
S^{i'j'} &= \frac{\partial T^{i'}}{\partial Z^{j'}} \\
&= \frac{\partial}{\partial Z^{j'}} \left[T^i J_i^{i'} \right],
\end{aligned}$$

since T is a contravariant tensor,

$$\begin{aligned}
&= \frac{\partial}{\partial Z^{j'}} \left[T^i (Z'(Z)) \right] J_i^{i'} + T^i \frac{\partial}{\partial Z^{j'}} \left[J_i^{i'} (Z(Z')) \right] \\
&= \frac{\partial T^i}{\partial Z^j} J_j^{j'} J_i^{i'} + T^i \frac{\partial J_i^{i'}}{\partial Z^j} \frac{\partial Z^j}{\partial Z^{j'}} \\
&= S^{ij} J_i^{i'} J_j^{j'} + T^i J_{ij}^{i'} J_{j'}^j \\
&\neq S^{i'j'} J_i^{i'} J_j^{j'}
\end{aligned}$$

except in the trivial case.

Ex. 92: We have

$$\Gamma_{ij}^k = \mathbf{Z}^k \cdot \frac{\partial \mathbf{Z}_i}{\partial Z^j},$$

so in primed coordinates,

$$\begin{aligned}
\Gamma_{i'j'}^{k'} &= \mathbf{Z}^{k'} \cdot \frac{\partial \mathbf{Z}_{i'}}{\partial Z^{j'}} \\
&= \mathbf{Z}^{k'} \cdot \left(\frac{\partial \mathbf{Z}_i}{\partial Z^j} J_{i'}^i J_{j'}^j + \mathbf{Z}_i J_{i'j'}^i \right)
\end{aligned}$$

by our work done earlier (note that \mathbf{Z}_i is a covariant tensor)

$$\left(\mathbf{Z}^k J_k^{k'}\right) \cdot \left(\frac{\partial \mathbf{Z}_i}{\partial Z^j} J_{i'}^i J_{j'}^j + \mathbf{Z}_i J_{i'j'}^i\right)$$

since Z^k is a contravariant tensor,

$$\begin{aligned} &= \left(\mathbf{Z}^k \cdot \frac{\partial \mathbf{Z}_i}{\partial Z^j}\right) J_k^{k'} J_{i'}^i J_{j'}^j + (\mathbf{Z}^k \cdot \mathbf{Z}_i) J_k^{k'} J_{i'j'}^i \\ &= \left(\mathbf{Z}^k \cdot \frac{\partial \mathbf{Z}_i}{\partial Z^j}\right) J_k^{k'} J_{i'}^i J_{j'}^j + \delta_i^k J_k^{k'} J_{i'j'}^i \\ &= \left(\mathbf{Z}^k \cdot \frac{\partial \mathbf{Z}_i}{\partial Z^j}\right) J_k^{k'} J_{i'}^i J_{j'}^j + J_i^{k'} J_{i'j'}^i \\ &\neq \left(\mathbf{Z}^k \cdot \frac{\partial \mathbf{Z}_i}{\partial Z^j}\right) J_k^{k'} J_{i'}^i J_{j'}^j = \Gamma_{ij}^k J_k^{k'} J_{i'}^i J_{j'}^j \end{aligned}$$

except in the trivial case.

Ex. 93: Compute

$$\begin{aligned} \frac{\partial T_{i'j'}}{\partial Z^{k'}} &= \frac{\partial}{\partial Z^{k'}} [T_{ij} J_{i'}^i J_{j'}^j] \\ &= \frac{\partial}{\partial Z^{k'}} [T_{ij}] J_{i'}^i J_{j'}^j + T_{ij} \frac{\partial}{\partial Z^{k'}} [J_{i'}^i] J_{j'}^j + T_{ij} J_{i'}^i \frac{\partial}{\partial Z^{k'}} [J_{j'}^j] \\ &= \frac{\partial}{\partial Z^{k'}} [T_{ij}] J_{i'}^i J_{j'}^j + T_{ij} J_{i'k'}^i J_{j'}^j + T_{ij} J_{i'}^i J_{j'k'}^j \\ &= \frac{\partial}{\partial Z^{k'}} [T_{ij}(Z(Z'))] J_{i'}^i J_{j'}^j + T_{ij} J_{i'k'}^i J_{j'}^j + T_{ij} J_{i'}^i J_{j'k'}^j \\ &= \frac{\partial T_{ij}}{\partial Z^k} \frac{\partial Z^k}{\partial Z^{k'}} J_{i'}^i J_{j'}^j + T_{ij} J_{i'k'}^i J_{j'}^j + T_{ij} J_{i'}^i J_{j'k'}^j \\ &= \frac{\partial T_{ij}}{\partial Z^k} J_k^k J_{i'}^i J_{j'}^j + T_{ij} J_{i'k'}^i J_{j'}^j + T_{ij} J_{i'}^i J_{j'k'}^j. \end{aligned}$$

Thus, from 5.66,

$$\begin{aligned}
\Gamma_{i'j'}^{k'} &= \frac{1}{2} Z^{k'm'} \left(\frac{\partial Z_{m'i'}}{\partial Z^{j'}} + \frac{\partial Z_{m'j'}}{\partial Z^{i'}} - \frac{\partial Z_{i'j'}}{\partial Z^{m'}} \right) \\
&= \frac{1}{2} Z^{km} J_k^{k'} J_{m'}^{m'} \left(\frac{\partial Z_{m'i'}}{\partial Z^{j'}} + \frac{\partial Z_{m'j'}}{\partial Z^{i'}} - \frac{\partial Z_{i'j'}}{\partial Z^{m'}} \right) \\
&= \frac{1}{2} Z^{km} J_k^{k'} J_{m'}^{m'} \left(\frac{\partial Z_{mi}}{\partial Z^j} J_{j'}^j J_{m'}^m J_{i'}^i + Z_{mi} J_{m'j'}^m J_{i'}^i + Z_{mi} J_{m'}^m J_{i'j'}^i \right. \\
&\quad \left. + \frac{\partial Z_{mj}}{\partial Z^i} J_{i'}^i J_{m'}^m J_{j'}^j + Z_{mj} J_{m'i'}^m J_{j'}^j + Z_{mj} J_{m'}^m J_{i'j'}^j \right. \\
&\quad \left. - \frac{\partial Z_{ij}}{\partial Z^m} J_{m'}^m J_{i'}^i J_{j'}^j - Z_{ij} J_{i'm'}^i J_{j'}^j - Z_{ij} J_{i'}^i J_{j'm'}^j \right) \\
&= \frac{1}{2} Z^{km} J_k^{k'} J_{m'}^{m'} \left(\frac{\partial Z_{mi}}{\partial Z^j} J_{j'}^j J_{m'}^m J_{i'}^i + \frac{\partial Z_{mj}}{\partial Z^i} J_{i'}^i J_{m'}^m J_{j'}^j - \frac{\partial Z_{ij}}{\partial Z^m} J_{m'}^m J_{i'}^i J_{j'}^j \right) \\
&\quad + \frac{1}{2} Z^{km} J_k^{k'} J_{m'}^{m'} \left(Z_{mi} J_{m'j'}^m J_{i'}^i + Z_{mi} J_{m'}^m J_{i'j'}^i \right) \\
&\quad + \frac{1}{2} Z^{km} J_k^{k'} J_{m'}^{m'} \left(Z_{mj} J_{m'i'}^m J_{j'}^j + Z_{mj} J_{m'}^m J_{i'j'}^j \right) \\
&\quad - \frac{1}{2} Z^{km} J_k^{k'} J_{m'}^{m'} \left(Z_{ij} J_{i'm'}^i J_{j'}^j + Z_{ij} J_{i'}^i J_{j'm'}^j \right) \\
&= \frac{1}{2} Z^{km} J_k^{k'} J_{j'}^j J_{i'}^i \left(\frac{\partial Z_{mi}}{\partial Z^j} + \frac{\partial Z_{mj}}{\partial Z^i} - \frac{\partial Z_{ij}}{\partial Z^m} \right) \\
&\quad + \frac{1}{2} Z^{km} J_k^{k'} J_{m'}^{m'} \left(Z_{mi} J_{m'j'}^m J_{i'}^i + Z_{mi} J_{m'}^m J_{i'j'}^i \right) \\
&\quad + \frac{1}{2} Z^{km} J_k^{k'} J_{m'}^{m'} \left(Z_{mj} J_{m'i'}^m J_{j'}^j + Z_{mj} J_{m'}^m J_{i'j'}^j \right) \\
&\quad - \frac{1}{2} Z^{km} J_k^{k'} J_{m'}^{m'} \left(Z_{ij} J_{i'm'}^i J_{j'}^j + Z_{ij} J_{i'}^i J_{j'm'}^j \right) \\
&= \Gamma_{ij}^k J_k^{k'} J_{j'}^j J_{i'}^i \\
&\quad + \frac{1}{2} Z^{km} Z_{mi} J_k^{k'} J_{m'}^{m'} \left(J_{m'j'}^m J_{i'}^i + J_{m'}^m J_{i'j'}^i \right) \\
&\quad + \frac{1}{2} Z^{km} Z_{mj} J_k^{k'} J_{m'}^{m'} \left(J_{m'i'}^m J_{j'}^j + J_{m'}^m J_{i'j'}^j \right) \\
&\quad - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_{m'}^{m'} \left(J_{i'm'}^i J_{j'}^j + J_{i'}^i J_{j'm'}^j \right) \\
&= \Gamma_{ij}^k J_k^{k'} J_{j'}^j J_{i'}^i \\
&\quad + \frac{1}{2} \delta_i^k J_k^{k'} J_{m'}^{m'} \left(J_{m'j'}^m J_{i'}^i + J_{m'}^m J_{i'j'}^i \right) \\
&\quad + \frac{1}{2} \delta_j^k J_k^{k'} J_{m'}^{m'} \left(J_{m'i'}^m J_{j'}^j + J_{m'}^m J_{i'j'}^j \right) \\
&\quad - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_{m'}^{m'} \left(J_{i'm'}^i J_{j'}^j + J_{i'}^i J_{j'm'}^j \right) \\
&= \Gamma_{ij}^k J_k^{k'} J_{j'}^j J_{i'}^i \\
&\quad + \frac{1}{2} J_i^{k'} J_{m'}^{m'} \left(J_{m'j'}^m J_{i'}^i + J_{m'}^m J_{i'j'}^i \right) \\
&\quad + \frac{1}{2} J_j^{k'} J_{m'}^{m'} \left(J_{m'i'}^m J_{j'}^j + J_{m'}^m J_{i'j'}^j \right) \\
&\quad - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_{m'}^{m'} \left(J_{i'm'}^i J_{j'}^j + J_{i'}^i J_{j'm'}^j \right) \\
&= \Gamma_{ij}^k J_k^{k'} J_{j'}^j J_{i'}^i \\
&\quad + \frac{1}{2} J_i^{k'} J_{m'}^{m'} J_{m'j'}^m J_{i'}^i + \frac{1}{2} J_i^{k'} J_{m'}^{m'} J_{m'}^m J_{i'j'}^i \\
&\quad + \frac{1}{2} J_j^{k'} J_{m'}^{m'} J_{m'i'}^m J_{j'}^j + \frac{1}{2} J_j^{k'} J_{m'}^{m'} J_{m'}^m J_{i'j'}^j \\
&\quad - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_{m'}^{m'} \left(J_{i'm'}^i J_{j'}^j + J_{i'}^i J_{j'm'}^j \right)
\end{aligned}$$

$$\begin{aligned}
&= \Gamma_{ij}^k J_k^{k'} J_j^j J_{i'}^i \\
&\quad + \frac{1}{2} J_i^{k'} J_{i'}^i J_m^{m'} J_{m'j'}^m + \frac{1}{2} J_i^{k'} J_{i'j'}^i \\
&\quad + \frac{1}{2} J_j^{k'} J_j^j J_m^{m'} J_{m'i'}^m + \frac{1}{2} J_j^{k'} J_{i'j'}^j \\
&\quad - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_m^{m'} J_{i'm'}^i J_{j'}^j - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_m^{m'} J_{i'}^i J_{j'm'}^j \\
&= \Gamma_{ij}^k J_k^{k'} J_j^j J_{i'}^i + J_i^{k'} J_{i'j'}^i + \frac{1}{2} \delta_j^{k'} J_m^{m'} J_{m'j'}^m + \frac{1}{2} \delta_j^{k'} J_m^{m'} J_{m'i'}^m - \frac{1}{2} Z^{km} Z_{ij} J_j^j J_k^{k'} J_m^{m'} J_{i'm'}^i - \frac{1}{2} Z^{km} Z_{ij} J_{i'}^i J_{j'm'}^j \\
&= \Gamma_{ij}^k J_k^{k'} J_j^j J_{i'}^i + J_i^{k'} J_{i'j'}^i + 0.
\end{aligned}$$

Thus, we have

$$\Gamma_{i'j'}^{k'} = \Gamma_{ij}^k J_k^{k'} J_j^j J_{i'}^i + J_i^{k'} J_{i'j'}^i.$$

Ex. 94: We show the result for degree-one covariant tensors. The generalization to other tensors is then evident.

Assume $T_i = 0$. Then, since $T_{i'} = T_i J_i^{i'}$, we have $T_{i'} = 0$.

Ex. 95: Note that in such a coordinate change,

$$J_i^{i'} = A_i^{i'},$$

so the "Hessian" object

$$J_{ij}^{i'} = 0,$$

since $A_i^{i'}$ is assumed to be constant with respect to Z . This means that all but the first terms in the above computations of $\frac{\partial T_{i'}}{\partial Z^{j'}}$, $\frac{\partial T_{i'}}{\partial Z^{j'}}$, $\frac{\partial T_{i'j'}}{\partial Z^{k'}}$, and even $\Gamma_{i'j'}^{k'}$ are zero, and hence we have that each of these objects have this "tensor property" with respect to coordinate changes that are linear transformations.

Ex. 96: Since the sum of two tensors is a tensor, we may inductively show that the sum of finitely many tensors is a tensor. We must show that for any constant c ,

$$cA_{jk}^i$$

is a tensor. Compute

$$cA_{j'k'}^{i'} = cA_{jk}^i J_i^{i'} J_{j'}^j J_{k'}^k,$$

since A_{jk}^i is a tensor. Thus, by the above, we have if each $A(n)_{jk}^i$ is a tensor, then the sum

$$\sum_{n=1}^N c_n A(n)_{jk}^i$$

is a tensor. Thus, linear combinations of tensors are tensors.

Ex. 97: We have that

$$\begin{aligned} S_i T^{ij} &= S_i \delta_k^i T^{kj} \\ &= \delta_k^i S_i T^{kj}, \end{aligned}$$

which is a tensor, since both δ_k^i and $S_i T^{kj}$ are tensors by the previous section and by the fact that the product of two tensors is a tensor.

Ex. 98: $\delta_i^i = n$ by the summation convention. Thus, δ_i^i returns the dimension of the ambient space.

Ex. 99: We have

$$\mathbf{V}_{ij} = V_{ij}^k \mathbf{Z}_k,$$

so

$$\begin{aligned} \mathbf{V}_{ij} \cdot \mathbf{Z}^m &= V_{ij}^k \mathbf{Z}_k \cdot \mathbf{Z}^m \\ &= V_{ij}^k \delta_k^m \\ &= V_{ij}^m \end{aligned}$$

so substituting $m = k$, we have an expression for the components

$$V_{ij}^k = \mathbf{V}_{ij} \cdot \mathbf{Z}^k$$

So,

$$\begin{aligned} V_{i'j'}^{k'} &= \mathbf{V}_{i'j'} \cdot \mathbf{Z}^{k'} \\ &= \mathbf{V}_{ij} J_{i'}^i J_{j'}^j \cdot \mathbf{Z}^k J_k^{k'}, \end{aligned}$$

since both $\mathbf{V}_{ij}, \mathbf{Z}^k$ are tensors

$$= \mathbf{V}_{ij} \cdot \mathbf{Z}^k J_{i'}^i J_{j'}^j J_k^{k'}$$

by linearity

$$= V_{ij}^k J_i^i J_j^j J_k^{k'}$$

as desired.

Ex. 100: Fix a coordinate system $Z^{\bar{i}}$

$$T_k^{ij} = T_{\bar{k}}^{\bar{i}\bar{j}} J_{\bar{i}}^i J_{\bar{j}}^j J_{\bar{k}}^{\bar{k}},$$

so

$$\begin{aligned} T_k^{ij} J_i^{i'} J_j^{j'} J_{k'}^k &= T_{\bar{k}}^{\bar{i}\bar{j}} J_{\bar{i}}^i J_{\bar{j}}^j J_{\bar{k}}^{\bar{k}} J_{\bar{i}}^{i'} J_{\bar{j}}^{j'} J_{\bar{k}}^{\bar{k}} \\ &= T_{\bar{k}}^{\bar{i}\bar{j}} \delta_{\bar{i}}^{i'} \delta_{\bar{j}}^{j'} \delta_{\bar{k}}^{\bar{k}} \\ &= T_{\bar{k}'}^{i'j'}, \end{aligned}$$

as desired.

Chapter 7

Chapter 7

Chapter 8

Chapter 8

Chapter 9

Chapter 9

Ex. 183: Assume $n = 3$. Given a_{ij} , put A as the determinant. We define

$$A = e^{ijk} a_{i1} a_{j2} a_{k3}.$$

Note that switching the roles of 1, 2 in the above equation yields

$$\begin{aligned} e^{ijk} a_{i2} a_{j1} a_{k3} &= e^{ijk} a_{j1} a_{i2} a_{k3} \\ &= e^{jik} a_{i1} a_{j2} a_{k3} \\ &= -e^{ijk} a_{i1} a_{j2} a_{k3} \\ &= -A \end{aligned}$$

Generalizing, we let (r, s, t) be a permutation of $(1, 2, 3)$. We may then see that

$$A = e^{ijk} e^{rst} a_{ir} a_{js} a_{kt}$$

(note that the summation convention is not implied in the above line). Then, since there are $3!$ permutations of $(1, 2, 3)$, we may write

$$3!A = \sum_{\substack{\text{permutations} \\ (r,s,t)}} e^{ijk} e_{rst} a_{ir} a_{js} a_{kt}$$

But, $e^{rst} = 0$ for (r, s, t) that is not a permutation; hence we may sum over all $0 \leq r, s, t \leq 3$, and apply the Einstein summation convention:

$$3!A = e^{ijk} e_{rst} a_{ir} a_{js} a_{kt},$$

or

$$A = \frac{1}{3!} e^{ijk} e_{rst} a_{ir} a_{js} a_{kt}$$

We may similarly show that for a^{ij} , we have

$$A = \frac{1}{3!} e_{ijk} a^{i1} a^{j2} a^{k3}.$$

Ex. 184: We have

$$\delta_{rst}^{123} a_2^r a_2^s a_3^t = \delta_{srt}^{123} a_2^s a_2^r a_3^t$$

after index renaming

$$\begin{aligned} &= \delta_{srt}^{123} a_2^r a_2^s a_3^t \\ &= -\delta_{rst}^{123} a_2^r a_2^s a_3^t. \end{aligned}$$

Since

$$\delta_{rst}^{123} a_2^r a_2^s a_3^t = -\delta_{rst}^{123} a_2^r a_2^s a_3^t,$$

we need

$$\delta_{rst}^{123} a_2^r a_2^s a_3^t = 0.$$

The result for $\delta_{srt}^{132} a_2^s a_3^r a_2^t$ follows similarly.

Ex. 185: Note

$$\delta_{rst}^{123} = e^{123} e_{rst} = 1 \cdot e_{rst} = e_{rst},$$

so

$$\delta_{rst}^{123} a_1^r a_2^s a_3^t = e_{rst} a_1^r a_2^s a_3^t = A.$$

Also,

$$\begin{aligned} \delta_{rst}^{132} a_2^r a_3^s a_1^t &= \delta_{rst}^{132} a_1^t a_2^r a_3^s \\ &= \delta_{str}^{132} a_1^r a_2^s a_3^t \\ &= -\delta_{str}^{123} a_1^r a_2^s a_3^t \\ &= -e_{str} a_1^r a_2^s a_3^t \\ &= A. \end{aligned}$$

[Note: Is there an error somewhere - should this be $-A$?]

Ex. 186: Define

$$A^{ir} = \frac{1}{2!} e^{ijk} e^{rst} a_{js} a_{tk}.$$

We check that

$$\frac{\partial A}{\partial a_{ir}} = A^{ir}.$$

Check

$$\begin{aligned} \frac{\partial A}{\partial a_{lu}} &= \frac{1}{3!} e^{ijk} e^{rst} \frac{\partial (a_{ir} a_{js} a_{kt})}{\partial a_{lu}} \\ &= \frac{1}{3!} e^{ijk} e^{rst} \left[\frac{\partial a_{ir}}{\partial a_{lu}} a_{js} a_{kt} + a_{ir} \frac{\partial a_{js}}{\partial a_{lu}} a_{kt} + a_{ir} a_{js} \frac{\partial a_{kt}}{\partial a_{lu}} \right] \\ &= \frac{1}{3!} e^{ijk} e^{rst} \left[\delta_i^l \delta_r^u a_{js} a_{kt} + a_{ir} \delta_j^l \delta_s^u a_{kt} + a_{ir} a_{js} \delta_k^l \delta_t^u \right] \\ &= \frac{1}{3!} \left[e^{ijk} \delta_i^l e^{rst} \delta_r^u a_{js} a_{kt} + a_{ir} e^{ijk} \delta_j^l e^{rst} \delta_s^u a_{kt} + a_{ir} a_{js} e^{ijk} \delta_k^l e^{rst} \delta_t^u \right] \\ &= \frac{1}{3!} \left[e^{ljk} e^{ust} a_{js} a_{kt} + a_{ir} e^{ilk} e^{rut} a_{kt} + a_{ir} a_{js} e^{ijl} e^{rsu} \right] \\ &= \frac{1}{3!} \left[e^{ljk} e^{ust} a_{js} a_{kt} + e^{ilk} e^{rut} a_{ir} a_{kt} + e^{ijl} e^{rsu} a_{ir} a_{js} \right] \\ &= \frac{1}{3!} \left[3e^{ljk} e^{ust} a_{js} a_{kt} \right], \end{aligned}$$

after an index renaming,

$$\begin{aligned} &= \frac{1}{2!} e^{ljk} e^{ust} a_{js} a_{kt} \\ &= A^{lu} \end{aligned}$$

as desired. Similarly, if we define

$$A_{ir} = \frac{1}{2!} e_{ijk} e_{rst} a^{js} a^{tk},$$

we have

$$\frac{\partial A}{\partial a^{ir}} = A_{ir}$$

by a similar argument.

Ex. 187: In cartesian coordinates,

$$Z_{ij} = \delta_j^i,$$

so

$$\begin{aligned} Z &= |Z_{..}| \\ &= |I| \\ &= 1. \end{aligned}$$

Thus,

$$\sqrt{Z} = 1.$$

In polar coordinates,

$$[Z_{ij}] = \begin{bmatrix} 1 & 0 \\ 0 & r^2 \end{bmatrix},$$

so

$$\begin{aligned} Z &= \begin{vmatrix} 1 & 0 \\ 0 & r^2 \end{vmatrix} \\ &= r^2; \end{aligned}$$

hence

$$\sqrt{Z} = r.$$

In spherical coordinates,

$$[Z_{ij}] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{bmatrix},$$

so

$$\begin{aligned} Z &= \begin{vmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{vmatrix} \\ &= r^4 \sin^2 \theta; \end{aligned}$$

thus,

$$\sqrt{Z} = r^2 \sin \theta.$$

Ex. 188: We compute, using the Voss-Weyl formula,

$$\begin{aligned}
\nabla_i \nabla^i F &= \frac{1}{\sqrt{Z}} \frac{\partial}{\partial Z^i} \left(\sqrt{Z} Z^{ij} \frac{\partial F}{\partial Z^j} \right) \\
&= \frac{1}{r^2 \sin \theta} \left[\frac{\partial}{\partial r} \left(r^2 \sin \theta (1) \frac{\partial F}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(r^2 \sin \theta r^2 \frac{\partial F}{\partial \theta} \right) + \frac{\partial}{\partial \phi} \left(r^2 \sin \theta r^2 \sin^2 \theta \frac{\partial F}{\partial \phi} \right) \right] \\
&= \frac{1}{r^2 \sin \theta} \left[\frac{\partial}{\partial r} \left(r^2 \sin \theta \frac{\partial F}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(r^4 \sin \theta \frac{\partial F}{\partial \theta} \right) + \frac{\partial}{\partial \phi} \left(r^4 \sin^3 \theta \frac{\partial F}{\partial \phi} \right) \right] \\
&= \frac{1}{r^2 \sin \theta} \left[\sin \theta \frac{\partial}{\partial r} \left(r^2 \frac{\partial F}{\partial r} \right) + r^4 \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial F}{\partial \theta} \right) + r^4 \sin^3 \theta \frac{\partial}{\partial \phi} \left(\frac{\partial F}{\partial \phi} \right) \right] \\
&= \frac{1}{r^2 \sin \theta} \left[\sin \theta \left(2r \frac{\partial F}{\partial r} + r^2 \frac{\partial^2 F}{\partial r^2} \right) + r^4 \left(\cos \theta \frac{\partial F}{\partial \theta} + \sin \theta \frac{\partial^2 F}{\partial \theta^2} \right) + r^4 \sin^3 \theta \frac{\partial^2 F}{\partial \phi^2} \right] \\
&= \frac{1}{r^2} \left(2r \frac{\partial F}{\partial r} + r^2 \frac{\partial^2 F}{\partial r^2} \right) + \frac{r^2}{\sin \theta} \left(\cos \theta \frac{\partial F}{\partial \theta} + \sin \theta \frac{\partial^2 F}{\partial \theta^2} \right) + r^2 \sin^2 \theta \frac{\partial^2 F}{\partial \phi^2} \\
&= \frac{2}{r} \frac{\partial F}{\partial r} + \frac{\partial^2 F}{\partial r^2} + r^2 \cot \theta \frac{\partial F}{\partial \theta} + r^2 \frac{\partial^2 F}{\partial \theta^2} + r^2 \sin^2 \theta \frac{\partial^2 F}{\partial \phi^2} \\
&= \frac{\partial^2 F}{\partial r^2} + \frac{2}{r} \frac{\partial F}{\partial r} + r^2 \frac{\partial^2 F}{\partial \theta^2} + r^2 \cot \theta \frac{\partial F}{\partial \theta} + r^2 \sin^2 \theta \frac{\partial^2 F}{\partial \phi^2}
\end{aligned}$$

Ex. 189: We compute, for cylindrical coordinates

$$\begin{aligned}
\nabla_i \nabla^i F &= \frac{1}{\sqrt{Z}} \frac{\partial}{\partial Z^i} \left(\sqrt{Z} Z^{ij} \frac{\partial F}{\partial Z^j} \right) \\
&= \frac{1}{r} \left[\frac{\partial}{\partial r} \left(r (1) \frac{\partial F}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(r \cdot r^2 \frac{\partial F}{\partial \theta} \right) + \frac{\partial}{\partial z} \left(r (1) \frac{\partial F}{\partial z} \right) \right] \\
&= \frac{1}{r} \left[\frac{\partial}{\partial r} \left(r \frac{\partial F}{\partial r} \right) + r^3 \frac{\partial^2 F}{\partial \theta^2} + r \frac{\partial^2 F}{\partial z^2} \right] \\
&= \frac{1}{r} \left[\frac{\partial F}{\partial r} + r \frac{\partial^2 F}{\partial r^2} + r^3 \frac{\partial^2 F}{\partial \theta^2} + r \frac{\partial^2 F}{\partial z^2} \right] \\
&= \frac{\partial^2 F}{\partial r^2} + \frac{1}{r} \frac{\partial F}{\partial r} + r^2 \frac{\partial^2 F}{\partial \theta^2} + \frac{\partial^2 F}{\partial z^2}.
\end{aligned}$$

Part II

Part II

Chapter 10

Chapter 10

Ex. 213: Note that

$$\begin{aligned}Z_{\alpha}^i Z_j^{\alpha} &= (\mathbf{S}_{\alpha} \cdot \mathbf{Z}^i) (\mathbf{S}^{\alpha} \cdot \mathbf{Z}_j) \\&= (\mathbf{S}_{\alpha} (\mathbf{S}^{\alpha} \cdot \mathbf{Z}_j) \cdot \mathbf{Z}^i) \\&= (\mathbf{S}^{\alpha} \cdot \mathbf{Z}_j) \mathbf{S}_{\alpha} \cdot \mathbf{Z}^i \\&\neq \delta_j^i,\end{aligned}$$

since

$$(\mathbf{S}^{\alpha} \cdot \mathbf{Z}_j) \mathbf{S}_{\alpha}$$

is merely the projection of \mathbf{Z}_j onto the tangent space. [ASK]

EARLIER ATTEMPT:

$$\begin{aligned}Z_{\alpha}^i Z_j^{\alpha} &= \delta_j^i \\(\mathbf{S}_{\alpha} \cdot \mathbf{Z}^i) Z_{j\beta} S^{\alpha\beta} &= \delta_j^i \\ \mathbf{S}_{\alpha} S^{\alpha\beta} \cdot \mathbf{Z}^i Z_{j\beta} &= \delta_j^i \\ \mathbf{S}^{\beta} Z_{j\beta} \cdot \mathbf{Z}^i &= \delta_j^i \\ \mathbf{S}^{\beta} Z_{j\beta} \cdot \mathbf{Z}^i &= \mathbf{Z}_j \cdot \mathbf{Z}^i,\end{aligned}$$

which forces

$$\mathbf{S}^{\beta} Z_{j\beta} = \mathbf{Z}_j$$

??? [Not sure - maybe a dimensional argument?]

Ex. 214: We have

$$T^i = T^\alpha Z_\alpha^i.$$

Now,

$$\begin{aligned} T^i Z_i^\alpha &= T^\beta Z_\beta^i Z_i^\alpha \\ &= T^\beta \delta_\beta^\alpha \\ &= T^\alpha, \end{aligned}$$

as desired.

Ex. 215: We show that $(\mathbf{V} - \mathbf{P}) \cdot \mathbf{N} = 0$. Compute

$$\begin{aligned} (\mathbf{V} - \mathbf{P}) \cdot \mathbf{N} &= (\mathbf{V} - (\mathbf{V} \cdot \mathbf{N}) \mathbf{N}) \cdot \mathbf{N} \\ &= \mathbf{V} \cdot \mathbf{N} - (\mathbf{V} \cdot \mathbf{N}) (\mathbf{N} \cdot \mathbf{N}) \\ &= \mathbf{V} \cdot \mathbf{N} - \mathbf{V} \cdot \mathbf{N} \\ &= 0, \end{aligned}$$

since

$$\mathbf{N} \cdot \mathbf{N} = 1.$$

Ex. 216: We compute

$$\begin{aligned} P_j^i P_k^j &= N^i N_j N^j N_k \\ &= N^i (1) N_k \\ &= P_k^i, \end{aligned}$$

as desired.

Ex. 217: We show that $\mathbf{V} - \mathbf{T}$ is orthogonal to the tangent plane. We compute

$$\begin{aligned} (\mathbf{V} - \mathbf{T}) \cdot \mathbf{S}^\beta &= (\mathbf{V} - (\mathbf{V} \cdot \mathbf{S}^\alpha) \mathbf{S}_\alpha) \cdot \mathbf{S}^\beta \\ &= \mathbf{V} \cdot \mathbf{S}^\beta - (\mathbf{V} \cdot \mathbf{S}^\alpha) \mathbf{S}_\alpha \cdot \mathbf{S}^\beta \\ &= \mathbf{V} \cdot \mathbf{S}^\beta - (\mathbf{V} \cdot \mathbf{S}^\alpha) \delta_\alpha^\beta \\ &= \mathbf{V} \cdot \mathbf{S}^\beta - \mathbf{V} \cdot \mathbf{S}^\beta \\ &= 0. \end{aligned}$$

Ex. 218: Similarly to 216, we have, given definition $T_j^i = N^i N_j$

$$\begin{aligned} T_j^i T_k^j &= N^i N_j N^j N_k \\ &= N^i N_k \\ &= T_k^i. \end{aligned}$$

[Note: This seems like the exact same problem - do we mean to define $T_j^i = T^i T_j$?]

Ex. 219: We have [Note that this implies 213 additionally]

$$N^i N_j + Z_\alpha^i Z_j^\alpha = \delta_j^i.$$

Contract both sides with N_i :

$$\begin{aligned} N^i N_j N_i + Z_\alpha^i Z_j^\alpha N_i &= \delta_j^i N_i \\ N_i N^i N_j + N_i Z_\alpha^i Z_j^\alpha &= N_j \\ N_i N^i N_j + 0 &= N_j \\ N_i N^i N_j &= N_j, \end{aligned}$$

where the third line follows from $N_i Z_\alpha^i = 0$. Now, this holds for all N_j , for which at least one is nonzero (we cannot have the normal vector be zero). Hence, we have

$$N_i N^i = 1,$$

as desired.

Ex. 220: Using similar manipulations of indices to the earlier discussion of the Levy-Civita symbols, we derive

$$\begin{aligned} -\frac{1}{4} \delta_{rst}^{ijk} T_j^t T_k^s &= -\frac{1}{4} \delta_{rts}^{ijk} T_j^s T_k^t \\ &= \frac{1}{4} \delta_{rst}^{ijk} T_j^s T_k^t, \end{aligned}$$

so

$$\begin{aligned} N^i N_r &= \frac{1}{4} \delta_{rst}^{ijk} T_j^s T_k^t - \frac{1}{4} \delta_{rst}^{ijk} T_j^t T_k^s \\ &= 2 \left(\frac{1}{4} \delta_{rst}^{ijk} T_j^s T_k^t \right) \\ &= \frac{1}{2} \delta_{rst}^{ijk} T_j^s T_k^t. \end{aligned}$$

Ex. 221: This result follows exactly as was done earlier, except we use the new definition of the Jacobian for surface coordinates

$$J_{\alpha}^{\alpha'} = \frac{\partial S^{\alpha'}}{\partial S^{\alpha}}.$$

Ex. 222: From before, we have

$$\frac{\partial Z_{ij}}{\partial Z^k} = Z_{li}\Gamma_{jk}^l + Z_{lj}\Gamma_{ik}^l.$$

From the analogous definitions of $S_{\alpha\beta}$, we have

$$\frac{\partial S_{\alpha\beta}}{\partial S^{\gamma}} = S_{\delta\alpha}\Gamma_{\beta\gamma}^{\delta} + S_{\delta\beta}\Gamma_{\alpha\gamma}^{\delta}$$

compute

$$\begin{aligned} & \frac{1}{2}S^{\alpha\omega} \left(\frac{\partial S_{\omega\beta}}{\partial S^{\gamma}} + \frac{\partial S_{\omega\gamma}}{\partial S^{\beta}} - \frac{\partial S_{\beta\gamma}}{\partial S^{\omega}} \right) \\ &= \frac{1}{2}S^{\alpha\omega} (S_{\delta\omega}\Gamma_{\beta\gamma}^{\delta} + S_{\delta\beta}\Gamma_{\omega\gamma}^{\delta} + S_{\delta\omega}\Gamma_{\beta\gamma}^{\delta} + S_{\delta\gamma}\Gamma_{\omega\beta}^{\delta} - (S_{\delta\beta}\Gamma_{\gamma\omega}^{\delta} + S_{\delta\gamma}\Gamma_{\beta\omega}^{\delta})) \\ &= \frac{1}{2}S^{\alpha\omega} (S_{\delta\omega}\Gamma_{\beta\gamma}^{\delta} + S_{\delta\beta}\Gamma_{\omega\gamma}^{\delta} + S_{\delta\omega}\Gamma_{\beta\gamma}^{\delta} + S_{\delta\gamma}\Gamma_{\omega\beta}^{\delta} - S_{\delta\beta}\Gamma_{\gamma\omega}^{\delta} - S_{\delta\gamma}\Gamma_{\beta\omega}^{\delta}) \\ &= \frac{1}{2}(\delta_{\delta}^{\alpha}\Gamma_{\beta\gamma}^{\delta} + S^{\alpha\omega}S_{\delta\beta}\Gamma_{\alpha\gamma}^{\delta} + \delta_{\delta}^{\alpha}\Gamma_{\beta\gamma}^{\delta} + S^{\alpha\omega}S_{\delta\gamma}\Gamma_{\omega\beta}^{\delta} - S^{\alpha\omega}S_{\delta\beta}\Gamma_{\gamma\omega}^{\delta} - S^{\alpha\omega}S_{\delta\gamma}\Gamma_{\beta\omega}^{\delta}) \\ &= \frac{1}{2}(2\delta_{\delta}^{\alpha}\Gamma_{\beta\gamma}^{\delta}) \\ &= \Gamma_{\beta\gamma}^{\alpha}, \end{aligned}$$

as desired.

Ex. 223: Assume the ambient space is referred to affine coordinates. We have

$$\begin{aligned} \Gamma_{\beta\gamma}^{\alpha} &= Z_i^{\alpha} \frac{\partial Z_{\beta}^i}{\partial S^{\gamma}} + \Gamma_{jk}^i Z_i^{\alpha} Z_{\beta}^j Z_{\gamma}^k \\ &= Z_i^{\alpha} \frac{\partial Z_{\beta}^i}{\partial S^{\gamma}} + 0, \end{aligned}$$

since $\Gamma_{jk}^i = 0$ in affine coordinates.

Ex. 224 [Still Working]

Ex. 225 We compute, given

$$\begin{aligned} Z^1(\theta, \phi) &= R \\ Z^2(\theta, \phi) &= \theta \\ Z^3(\theta, \phi) &= \phi \end{aligned}$$

$$\begin{aligned} Z_\alpha^i &= \frac{\partial Z^i}{\partial S^\alpha} \\ &= \begin{bmatrix} \frac{\partial Z^1}{\partial S^1} & \frac{\partial Z^1}{\partial S^2} \\ \frac{\partial Z^2}{\partial S^1} & \frac{\partial Z^2}{\partial S^2} \\ \frac{\partial Z^3}{\partial S^1} & \frac{\partial Z^3}{\partial S^2} \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}, \end{aligned}$$

then, note that since

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix},$$

we have

$$\begin{aligned} Z_i^\alpha &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\ N^i &= \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \times \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} \\ &= \mathbf{i} \\ &= \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \mathbf{S}_1 &= Z_1^i \mathbf{Z}_i \\ &= Z_1^2 \mathbf{Z}_2 \\ &= R \cos \theta \cos \phi \mathbf{i} + R \cos \theta \sin \phi \mathbf{j} - R \sin \theta \mathbf{k} \\ \mathbf{S}_2 &= Z_2^i \mathbf{Z}_i \\ &= Z_2^3 \mathbf{Z}_3 \\ &= -R \sin \theta \sin \phi \mathbf{i} + R \sin \theta \cos \phi \mathbf{j} \end{aligned}$$

$$\begin{aligned}
S_{\alpha\beta} &= \begin{bmatrix} R^2 \cos^2 \theta \cos^2 \phi + R^2 \cos^2 \theta \sin^2 \phi + R^2 \sin^2 \theta & -R^2 \cos \theta \cos \phi \sin \theta \sin \phi + R^2 \cos \theta \sin \phi \sin \theta \cos \phi \\ -R^2 \cos \theta \cos \phi \sin \theta \sin \phi + R^2 \cos \theta \sin \phi \sin \theta \cos \phi & R^2 \sin^2 \theta \sin^2 \phi + R^2 \sin^2 \theta \cos^2 \phi \end{bmatrix} \\
&= \begin{bmatrix} R^2 & 0 \\ 0 & R^2 \sin^2 \theta \end{bmatrix} \quad [\text{ASK - should this be the same as when the ambient coordinates are Cart.}] \\
S^{\alpha\beta} &= \begin{bmatrix} R^{-2} & 0 \\ 0 & R^{-2} \sin^{-2} \theta \end{bmatrix} \\
\sqrt{S} &= \sqrt{\begin{vmatrix} R^2 & 0 \\ 0 & R^2 \sin^2 \theta \end{vmatrix}} \\
&= R^2 \sin \theta.
\end{aligned}$$

Now, recall the Christoffel symbols for the ambient space (in spherical coords):

$$\begin{aligned}
\Gamma_{22}^1 &= -r \\
\Gamma_{33}^1 &= -r \sin^2 \theta \\
\Gamma_{12}^2 &= \Gamma_{21}^2 = \frac{1}{r} \\
\Gamma_{33}^2 &= -\sin \theta \cos \theta \\
\Gamma_{13}^3 &= \Gamma_{31}^3 = \frac{1}{r} \\
\Gamma_{23}^2 &= \Gamma_{32}^2 = \cot \theta.
\end{aligned}$$

Now, setting θ as coord. 1 and ϕ as coord. 2, and using

$$\Gamma_{\beta\gamma}^\alpha = Z_i^\alpha \frac{\partial Z_\beta^i}{\partial S^\gamma} + \Gamma_{jk}^i Z_l^\alpha Z_\beta^j Z_\gamma^k,$$

we compute

$$\begin{aligned}
\Gamma_{11}^1 &= Z_1^i \frac{\partial Z_1^i}{\partial S^1} + \Gamma_{jk}^i Z_\iota^1 Z_1^j Z_1^k \\
&= Z_2^1 \frac{\partial Z_1^2}{\partial S^1} + \Gamma_{jk}^2 Z_2^1 Z_1^j Z_1^k \\
&= Z_2^1 \frac{\partial Z_1^2}{\partial S^1} + \Gamma_{22}^2 Z_2^1 Z_1^2 Z_1^2 \\
&= \frac{\partial Z_1^2}{\partial S^1} \\
&= 0 \\
\Gamma_{21}^1 &= \Gamma_{12}^1 = 0 + \Gamma_{jk}^i Z_\iota^1 Z_2^j Z_1^k \\
&= \Gamma_{jk}^2 Z_2^1 Z_2^j Z_1^k \\
&= \Gamma_{32}^2 Z_2^1 Z_2^3 Z_1^2 \\
&= \cot \theta (1) (1) (1) \\
&= \cot \theta \\
\Gamma_{22}^1 &= \Gamma_{jk}^i Z_\iota^1 Z_2^j Z_2^k \\
&= \Gamma_{jk}^2 Z_2^1 Z_2^j Z_2^k \\
&= \Gamma_{33}^2 Z_2^1 Z_2^3 Z_2^3 \\
&= -\sin \theta \cos \theta
\end{aligned}$$

$$\begin{aligned}
\Gamma_{11}^2 &= \Gamma_{jk}^i Z_\iota^2 Z_1^j Z_1^k \\
&= \Gamma_{jk}^3 Z_3^2 Z_1^j Z_1^k \\
&= \Gamma_{22}^3 Z_3^2 Z_1^2 Z_1^2 \\
&= 0 \\
\Gamma_{21}^2 &= \Gamma_{12}^2 = \Gamma_{jk}^i Z_\iota^2 Z_2^j Z_1^k \\
&= \Gamma_{jk}^3 Z_3^2 Z_2^j Z_1^k \\
&= \Gamma_{32}^3 Z_3^2 Z_2^3 Z_1^2 \\
&= 0 \\
\Gamma_{22}^2 &= \Gamma_{jk}^i Z_\iota^2 Z_2^j Z_2^k \\
&= \Gamma_{33}^3 Z_3^2 Z_2^3 Z_2^3 \\
&= 0,
\end{aligned}$$

(note $\frac{\partial Z_\beta^i}{\partial S^\gamma}$ vanishes in each computation).

Ex. 226: We have

$$\sqrt{(x'(s))^2 + (y'(s))^2} = 1,$$

since this is an arc-length parametrization. Thus,

$$\begin{aligned} N^i &= \begin{bmatrix} y'(s) \\ -x'(s) \end{bmatrix} \\ S_{\alpha\beta} &= (x'(s))^2 + (y'(s))^2 \\ &= 1 \\ S^{\alpha\beta} &= 1 \\ \sqrt{S} &= 1 \end{aligned}$$

[ASK why $x'x'' + y'y'' = 0$].

Ex. 227: Simply denote $t = x$, and then we have the parametrization

$$\begin{aligned} x(t) &= t \\ y(t) &= y(t), \end{aligned}$$

and compute these objects in the preceding section, noting that $x'(t) = 1$. The, re-substitute $x = t$.

Ex. 228: Again, we have (in polar coordinates)

$$\sqrt{r'(s)^2 + r(s)^2 \theta'(s)^2} = 1,$$

so the results follow similarly to the above cases.

Chapter 11

Chapter 11

Ex. 229: This follows similarly as with the ambient covariant derivative, using the tensor properties of $T_\alpha^\beta(S)$ given in surface coordinates, and using the analogous Jacobians $J_\alpha^{\alpha'}$.

Ex. 230: The sum rule is clear from the sum rule of the partial derivative, and the properties of contraction. Also, the product rule follows as with the ambient case.

Ex. 231: We compute, using

$$\Gamma_{\beta\gamma}^\alpha = \frac{1}{2} S^{\alpha\omega} \left(\frac{\partial S_{\omega\beta}}{\partial S^\gamma} + \frac{\partial S_{\omega\gamma}}{\partial S^\beta} - \frac{\partial S_{\beta\gamma}}{\partial S^\omega} \right)$$

$$\begin{aligned} \nabla_\gamma S_{\alpha\beta} &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \Gamma_{\gamma\alpha}^\delta S_{\delta\beta} - \Gamma_{\gamma\beta}^\delta S_{\alpha\delta} \\ &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \Gamma_{\alpha\gamma}^\delta S_{\delta\beta} - \Gamma_{\beta\gamma}^\delta S_{\alpha\delta} \\ &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \frac{1}{2} S^{\delta\omega} \left(\frac{\partial S_{\omega\alpha}}{\partial S^\gamma} + \frac{\partial S_{\omega\gamma}}{\partial S^\alpha} - \frac{\partial S_{\alpha\gamma}}{\partial S^\omega} \right) S_{\delta\beta} - \frac{1}{2} S^{\delta\omega} \left(\frac{\partial S_{\omega\beta}}{\partial S^\gamma} + \frac{\partial S_{\omega\gamma}}{\partial S^\beta} - \frac{\partial S_{\beta\gamma}}{\partial S^\omega} \right) S_{\alpha\delta} \\ &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \frac{1}{2} \delta_\beta^\omega \left(\frac{\partial S_{\omega\alpha}}{\partial S^\gamma} + \frac{\partial S_{\omega\gamma}}{\partial S^\alpha} - \frac{\partial S_{\alpha\gamma}}{\partial S^\omega} \right) - \frac{1}{2} \delta_\alpha^\omega \left(\frac{\partial S_{\omega\beta}}{\partial S^\gamma} + \frac{\partial S_{\omega\gamma}}{\partial S^\beta} - \frac{\partial S_{\beta\gamma}}{\partial S^\omega} \right) \\ &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \frac{1}{2} \left(\frac{\partial S_{\beta\alpha}}{\partial S^\gamma} + \frac{\partial S_{\beta\gamma}}{\partial S^\alpha} - \frac{\partial S_{\alpha\gamma}}{\partial S^\beta} \right) - \frac{1}{2} \left(\frac{\partial S_{\alpha\beta}}{\partial S^\gamma} + \frac{\partial S_{\alpha\gamma}}{\partial S^\beta} - \frac{\partial S_{\beta\gamma}}{\partial S^\alpha} \right) \\ &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \frac{1}{2} \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \frac{1}{2} \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} \\ &= 0. \end{aligned}$$

Similarly, we may show that in the contravariant case,

$$\nabla_\gamma S^{\alpha\beta} = 0.$$

For the Levy-Civita symbols, note

$$\begin{aligned}\varepsilon_{\alpha\beta} &= \sqrt{S}e_{\alpha\beta} \\ \varepsilon^{\alpha\beta} &= \frac{1}{\sqrt{S}}e^{\alpha\beta}\end{aligned}$$

The result follows similarly to the ambient case, carefully noting that

$$\Gamma_{\beta\gamma}^{\alpha} = \mathbf{S}^{\alpha} \cdot \frac{\partial \mathbf{S}_{\beta}}{\partial S^{\gamma}}.$$

The delta systems follow from the product rule and the fact that $\nabla_{\gamma}S_{\alpha\beta} = \nabla_{\gamma}\varepsilon_{\alpha\beta} = \nabla_{\gamma}\varepsilon^{\alpha\beta} = 0$.

Ex. 232: Commutativity with contraction follows exactly as in the ambient case.

Ex. 233: We compute, using

$$S^{\alpha\beta} = \begin{bmatrix} R^{-2} & 0 \\ 0 & R^{-2} \sin^{-2} \theta \end{bmatrix},$$

the following:

$$\begin{aligned}\nabla_{\alpha}\nabla^{\alpha}F &= \frac{1}{\sqrt{S}}\frac{\partial}{\partial S^{\alpha}}\left(\sqrt{S}S^{\alpha\beta}\frac{\partial F}{\partial S^{\beta}}\right) \\ &= \frac{1}{R^2\sin\theta}\frac{\partial}{\partial\theta}\left(R^2\sin\theta S^{1\beta}\frac{\partial F}{\partial S^{\beta}}\right) + \frac{1}{R^2\sin\theta}\frac{\partial}{\partial\phi}\left(R^2\sin\theta S^{2\beta}\frac{\partial F}{\partial S^{\beta}}\right) \\ &= \frac{1}{R^2\sin\theta}\frac{\partial}{\partial\theta}\left(R^2\sin\theta S^{11}\frac{\partial F}{\partial\theta}\right) + \frac{1}{R^2\sin\theta}\frac{\partial}{\partial\phi}\left(R^2\sin\theta S^{22}\frac{\partial F}{\partial\phi}\right) \\ &= \frac{1}{R^2\sin\theta}\frac{\partial}{\partial\theta}\left(R^2\sin\theta R^{-2}\frac{\partial F}{\partial\theta}\right) + \frac{1}{R^2\sin\theta}\frac{\partial}{\partial\phi}\left(R^2\sin\theta R^{-2}\sin^{-2}\theta\frac{\partial F}{\partial\phi}\right) \\ &= \frac{1}{R^2\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial F}{\partial\theta}\right) + \frac{1}{R^2\sin\theta}\frac{\partial}{\partial\phi}\left(\frac{1}{\sin\theta}\frac{\partial F}{\partial\phi}\right) \\ &= \frac{1}{R^2\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial F}{\partial\theta}\right) + \frac{1}{R^2\sin^2\theta}\frac{\partial^2 F}{\partial\phi^2}.\end{aligned}$$

Ex. 234: For the surface of a cylinder, note

$$\begin{aligned}S^{\alpha\beta} &= \begin{bmatrix} R^{-2} & 0 \\ 0 & 1 \end{bmatrix} \\ \sqrt{S} &= R,\end{aligned}$$

so

$$\begin{aligned}
 \nabla_\alpha \nabla^\alpha F &= \frac{1}{\sqrt{S}} \frac{\partial}{\partial S^\alpha} \left(\sqrt{S} S^{\alpha\beta} \frac{\partial F}{\partial S^\beta} \right) \\
 &= \frac{1}{R} \frac{\partial}{\partial \theta} \left(R S^{11} \frac{\partial F}{\partial \theta} \right) + \frac{1}{R} \frac{\partial}{\partial z} \left(R S^{22} \frac{\partial F}{\partial z} \right) \\
 &= \frac{1}{R^2} \frac{\partial^2 F}{\partial \theta^2} + \frac{\partial^2 F}{\partial z^2}.
 \end{aligned}$$

Ex. 235: Note

$$\begin{aligned}
 S^{\alpha\beta} &= \begin{bmatrix} (R + r \cos \phi)^{-2} & 0 \\ 0 & r^{-2} \end{bmatrix} \\
 \sqrt{S} &= r (R + r \cos \phi),
 \end{aligned}$$

and compute

$$\begin{aligned}
 \nabla_\alpha \nabla^\alpha F &= \frac{1}{\sqrt{S}} \frac{\partial}{\partial S^\alpha} \left(\sqrt{S} S^{\alpha\beta} \frac{\partial F}{\partial S^\beta} \right) \\
 &= \frac{1}{r (R + r \cos \phi)} \frac{\partial}{\partial \theta} \left(r (R + r \cos \phi) S^{1\beta} \frac{\partial F}{\partial S^\beta} \right) \\
 &\quad + \frac{1}{r (R + r \cos \phi)} \frac{\partial}{\partial \phi} \left(r (R + r \cos \phi) S^{2\beta} \frac{\partial F}{\partial S^\beta} \right) \\
 &= \frac{1}{r (R + r \cos \phi)} \frac{\partial}{\partial \theta} \left(r (R + r \cos \phi) (R + r \cos \phi)^{-2} \frac{\partial F}{\partial \theta} \right) \\
 &\quad + \frac{1}{r (R + r \cos \phi)} \frac{\partial}{\partial \phi} \left(r (R + r \cos \phi) r^{-2} \frac{\partial F}{\partial \phi} \right) \\
 &= \frac{1}{(R + r \cos \phi)^2} \frac{\partial^2 F}{\partial \theta^2} + \frac{1}{r^2 (R + r \cos \phi)} \frac{\partial}{\partial \phi} \left((R + r \cos \phi) \frac{\partial F}{\partial \phi} \right).
 \end{aligned}$$

Ex. 236: We have

$$\begin{aligned}
 S^{\alpha\beta} &= \begin{bmatrix} r(z)^{-2} & 0 \\ 0 & \frac{1}{1+r'(z)^2} \end{bmatrix} \\
 \sqrt{S} &= r(z) \sqrt{1+r'(z)^2};
 \end{aligned}$$

Thus,

$$\begin{aligned}
\nabla_\alpha \nabla^\alpha F &= \frac{1}{\sqrt{S}} \frac{\partial}{\partial S^\alpha} \left(\sqrt{S} S^{\alpha\beta} \frac{\partial F}{\partial S^\beta} \right) \\
&= \frac{1}{r(z) \sqrt{1+r'(z)^2}} \frac{\partial}{\partial \theta} \left(\sqrt{S} S^{11} \frac{\partial F}{\partial \theta} \right) + \frac{1}{r(z) \sqrt{1+r'(z)^2}} \frac{\partial}{\partial z} \left(\sqrt{S} S^{22} \frac{\partial F}{\partial z} \right) \\
&= \frac{1}{r(z) \sqrt{1+r'(z)^2}} \frac{\partial}{\partial \theta} \left(r(z) \sqrt{1+r'(z)^2} r(z)^{-2} \frac{\partial F}{\partial \theta} \right) \\
&\quad + \frac{1}{r(z) \sqrt{1+r'(z)^2}} \frac{\partial}{\partial z} \left(r(z) \sqrt{1+r'(z)^2} \frac{1}{1+r'(z)^2} \frac{\partial F}{\partial z} \right) \\
&= \frac{1}{r(z) \sqrt{1+r'(z)^2}} \frac{\partial}{\partial z} \left(\frac{r(z)}{\sqrt{1+r'(z)^2}} \frac{\partial F}{\partial z} \right) + \frac{1}{r(z)^2} \frac{\partial^2 F}{\partial \theta^2}.
\end{aligned}$$

Ex. 237: These were computed earlier.

Ex. 238: We compute:

$$\begin{aligned}
\nabla_\gamma \mathbf{Z}_i &= \frac{\partial \mathbf{Z}_i}{\partial S^\gamma} - Z_\gamma^j \Gamma_{ij}^k \mathbf{Z}_k \\
&= \frac{\partial \mathbf{Z}_i}{\partial Z^m} \frac{\partial Z^m}{\partial S^\gamma} - Z_\gamma^j \Gamma_{ij}^k \mathbf{Z}_k \\
&= \frac{\partial \mathbf{Z}_i}{\partial Z^m} Z_\gamma^m - Z_\gamma^j \Gamma_{ij}^k \mathbf{Z}_k \\
&= \Gamma_{im}^k \mathbf{Z}_k Z_\gamma^m - Z_\gamma^j \Gamma_{ij}^k \mathbf{Z}_k \\
&= (Z_\gamma^m \Gamma_{im}^k - Z_\gamma^j \Gamma_{ij}^k) \mathbf{Z}_k \\
&= 0,
\end{aligned}$$

after index renaming. The contravariant case follows similarly. Also, since $Z_{ij} = \mathbf{Z}_i \cdot \mathbf{Z}_j$, we have

$$\nabla_\gamma Z_{ij} = 0$$

by the product rule. Similarly,

$$\nabla_\gamma Z^{ij} = 0.$$

[Levy-Civita Symbols to come]

Ex. 239: Begin with equation 10.41:

$$N_i N^i = 1,$$

and compute take the surface covariant derivative of both sides:

$$\begin{aligned} 0 &= \nabla_\alpha (N_i N^i) \\ &= \nabla_\alpha N_i N^i + N_i \nabla_\alpha N^i \\ &= \nabla_\alpha (N^j Z_{ij}) N_k Z^{ik} + N_i \nabla_\alpha N^i \\ &= (\nabla_\alpha N^j Z_{ij}) N_k Z^{ik} + N_i \nabla_\alpha N^i, \end{aligned}$$

by the metrinilic property,

$$\begin{aligned} &= \nabla_\alpha N^j N_k \delta_j^k + N_i \nabla_\alpha N^i \\ &= \nabla_\alpha N^k N_k + N_i \nabla_\alpha N^i \\ &= N_k \nabla_\alpha N^k + N_i \nabla_\alpha N^i \\ &= 2N_i \nabla_\alpha N^i, \end{aligned}$$

after index renaming. Thus,

$$N_i \nabla_\alpha N^i = 0.$$

Ex. 240: We compute

$$\begin{aligned}
\varepsilon^{ijk}\varepsilon_{\alpha\beta}Z_j^\beta N_k &= \varepsilon^{ijk}\varepsilon_{\alpha\beta}Z_j^\beta \left(\frac{1}{2}\varepsilon_{kmn}\varepsilon^{\gamma\delta}Z_\gamma^m Z_\delta^n \right) \\
&= \frac{1}{2}\varepsilon^{ijk}\varepsilon_{kmn}\varepsilon^{\gamma\delta}\varepsilon_{\alpha\beta}Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \frac{1}{2}\delta_{kmn}^{ijk}\delta_{\alpha\beta}^{\gamma\delta}Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= -\frac{1}{2}\delta_{mkn}^{ijk}\delta_{\alpha\beta}^{\gamma\delta}Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \frac{1}{2}\delta_{mnk}^{ijk}\delta_{\alpha\beta}^{\gamma\delta}Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \frac{1}{2}2\delta_{mn}^{ij}\delta_{\alpha\beta}^{\gamma\delta}Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \delta_{mn}^{ij}\delta_{\alpha\beta}^{\gamma\delta}Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= (\delta_m^i\delta_n^j - \delta_m^j\delta_n^i) (\delta_\alpha^\gamma\delta_\beta^\delta - \delta_\alpha^\delta\delta_\beta^\gamma) Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \delta_m^i\delta_n^j\delta_\alpha^\gamma\delta_\beta^\delta Z_j^\beta Z_\gamma^m Z_\delta^n - \delta_m^j\delta_n^i\delta_\alpha^\gamma\delta_\beta^\delta Z_j^\beta Z_\gamma^m Z_\delta^n - \delta_m^i\delta_n^j\delta_\alpha^\delta\delta_\beta^\gamma Z_j^\beta Z_\gamma^m Z_\delta^n + \delta_m^j\delta_n^i\delta_\alpha^\delta\delta_\beta^\gamma Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \delta_\alpha^\gamma\delta_\beta^\delta Z_j^\beta Z_\gamma^i Z_\delta^j - \delta_\alpha^\gamma\delta_\beta^\delta Z_j^\beta Z_\gamma^j Z_\delta^i - \delta_\alpha^\delta\delta_\beta^\gamma Z_j^\beta Z_\gamma^i Z_\delta^j + \delta_\alpha^\delta\delta_\beta^\gamma Z_j^\beta Z_\gamma^j Z_\delta^i \\
&= \delta_\alpha^\gamma\delta_\beta^\delta\delta_\delta^\beta Z_\gamma^i - \delta_\alpha^\gamma\delta_\beta^\delta\delta_\gamma^\beta Z_\delta^i - \delta_\alpha^\delta\delta_\beta^\gamma\delta_\delta^\beta Z_\gamma^i + \delta_\alpha^\delta\delta_\beta^\gamma\delta_\gamma^\beta Z_\delta^i \\
&= Z_\alpha^i - Z_\alpha^i - Z_\alpha^i + Z_\alpha^i
\end{aligned}$$

[Some factors of 2 needed?]

Ex. 241: Note that for a general covariant-contravariant tensor, we have

$$\nabla_\alpha T_j^i = Z_\alpha^k \nabla_k T_j^i.$$

Thus,

$$\nabla_\alpha u = Z_\alpha^k \nabla_k u$$

and

$$\nabla^\alpha u = Z^{\alpha k} \nabla_k u.$$

Thus,

$$\begin{aligned}
\nabla_\gamma \nabla^\alpha u &= \nabla_\gamma (Z^{\alpha k} \nabla_k u) \\
&= \nabla_\gamma Z^{\alpha k} \nabla_k u + Z^{\alpha k} \nabla_\gamma \nabla_k u \\
&= B_\gamma^\alpha N^k \nabla_k u + Z^{\alpha k} Z_\gamma^m \nabla_m \nabla_k u. \\
&= B_\gamma^\alpha N^k \nabla_k u + Z^{\alpha k} Z_{n\gamma} Z^{mn} \nabla_m \nabla_k u \\
&= B_\gamma^\alpha N^k \nabla_k u + Z^{\alpha k} Z_n^\delta S_{\delta\gamma} Z^{mn} \nabla_m \nabla_k u
\end{aligned}$$

Now, set $\gamma = \alpha$ and contract:

$$\begin{aligned}\nabla_\alpha \nabla^\alpha u &= B_\alpha^\alpha N^k \nabla_k u + Z^{\alpha k} Z_n^\delta S_{\delta\alpha} Z^{mn} \nabla_m \nabla_k u \\ &= B_\alpha^\alpha N^k \nabla_k u + \delta_\delta^\beta Z_\beta^k Z_n^\delta Z^{mn} \nabla_m \nabla_k u \\ &= B_\alpha^\alpha N^k \nabla_k u + Z_\beta^k Z_n^\beta Z^{mn} \nabla_m \nabla_k u.\end{aligned}$$

Now,

$$N^k N_n + Z_\beta^k Z_n^\beta = \delta_n^k,$$

so

$$Z_\beta^k Z_n^\beta = \delta_n^k - N^k N_n.$$

We substitute in the above:

$$\begin{aligned}\nabla_\alpha \nabla^\alpha u &= B_\alpha^\alpha N^k \nabla_k u + \left(\delta_n^k - N^k N_n \right) Z^{mn} \nabla_m \nabla_k u \\ &= B_\alpha^\alpha N^k \nabla_k u + Z^{km} \nabla_m \nabla_k u - N^k N_n Z^{mn} \nabla_m \nabla_k u \\ &= B_\alpha^\alpha N^k \nabla_k u + \nabla_m \nabla^m u - N^m N^k \nabla_m \nabla_k u,\end{aligned}$$

or after renaming dummy indices,

$$\nabla_\alpha \nabla^\alpha u = B_\alpha^\alpha N^i \nabla_i u + \nabla_i \nabla^i u - N^i N^j \nabla_i \nabla_j u,$$

or

$$N^i N^j \nabla_i \nabla_j u = \nabla_i \nabla^i u - \nabla_\alpha \nabla^\alpha u + B_\alpha^\alpha N^i \nabla_i u$$

Ex. 242: Let

$$Z^i(s)$$

be the parametrization of the line normal to the surface, emanating from point Z_0^i . Note that we have

$$\frac{dZ^i}{ds}(0) = \lim_{h \rightarrow 0} \frac{Z^i(h) - Z_0^i}{h} = N^i.$$

also, compute

$$\begin{aligned}\frac{d}{ds} \left[\frac{dZ^i}{ds} \mathbf{Z}_i \right] &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + \frac{dZ^i}{ds} \frac{d\mathbf{Z}_i}{ds} (Z(s)) \\ &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + \frac{dZ^i}{ds} \frac{\partial \mathbf{Z}_i}{\partial Z^k} \frac{dZ^k}{ds} \\ &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + \frac{dZ^i}{ds} \Gamma_{ik}^n \mathbf{Z}_n \frac{dZ^k}{ds},\end{aligned}$$

so at $s = 0$,

$$\begin{aligned}
 \frac{d}{ds} \left[\frac{dZ^i}{ds} \mathbf{Z}_i \right] \Big|_{s=0} &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + N^i \Gamma_{ik}^n \mathbf{Z}_n N^k \\
 &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + N^i N^k \Gamma_{ik}^n \mathbf{Z}_n \\
 &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + N^j N^k \Gamma_{jk}^i \mathbf{Z}_i \\
 &= \left(\frac{d^2 Z^i}{ds^2} + N^j N^k \Gamma_{jk}^i \right) \mathbf{Z}_i
 \end{aligned}$$

Now, examine the LHS of the above. Since

$$\frac{d}{ds} \left[\frac{dZ^i}{ds} \mathbf{Z}_i \right]$$

represents the second derivative of a line, the LHS vanishes. Thus,

$$\frac{d^2 Z^i}{ds^2} = -N^j N^k \Gamma_{jk}^i,$$

Then, define

$$F(s) = u(Z(s)),$$

so

$$\begin{aligned}
 F'(s) &= \frac{\partial u}{\partial Z^i}(Z(s)) \frac{dZ^i}{ds}(s) \\
 F''(s) &= \frac{d}{ds} \left[\frac{\partial u}{\partial Z^i}(Z(s)) \right] \frac{dZ^i}{ds}(s) + \frac{\partial u}{\partial Z^i}(Z(s)) \frac{d}{ds} \left[\frac{dZ^i}{ds}(s) \right] \\
 &= \frac{\partial^2 u}{\partial Z^i \partial Z^j}(Z(s)) \frac{dZ^i}{ds}(s) \frac{dZ^j}{ds}(s) + \frac{\partial u}{\partial Z^i}(Z(s)) \frac{d^2 Z^i}{ds^2}(s).
 \end{aligned}$$

at $s = 0$:

$$\begin{aligned}
 F''(0) &= \frac{\partial^2 u}{\partial Z^i \partial Z^j}(Z(0)) N^i N^j + \frac{\partial u}{\partial Z^i}(Z(0)) \frac{d^2 Z^i}{ds^2}(0) \\
 &= \frac{\partial}{\partial Z^j} [\nabla_i u] N^i N^j + \nabla_i u \frac{d^2 Z^i}{ds^2}(0)
 \end{aligned}$$

now, note

$$\begin{aligned}\nabla_j \nabla_i u &= \frac{\partial \nabla_i u}{\partial Z^j} - \Gamma_{ij}^k \nabla_k u \\ \frac{\partial \nabla_i u}{\partial Z^j} &= \nabla_j \nabla_i u + \Gamma_{ij}^k \nabla_k u,\end{aligned}$$

so

$$\begin{aligned}F''(0) &= (\nabla_j \nabla_i u + \Gamma_{ij}^k \nabla_k u) N^i N^j + \nabla_i u \frac{d^2 Z^i}{ds^2} (0) \\ &= \nabla_j \nabla_i u N^i N^j + \Gamma_{ij}^k \nabla_k u N^i N^j + \nabla_i u \frac{d^2 Z^i}{ds^2} (0) \\ &= N^i N^j \nabla_j \nabla_i u + N^i N^j \Gamma_{ij}^k \nabla_k u - N^j N^k \Gamma_{jk}^i \nabla_i u \\ &= N^i N^j \nabla_j \nabla_i u;\end{aligned}$$

thus

$$\frac{\partial^2 u}{\partial n^2} = F''(0) = N^i N^j \nabla_i \nabla_j u$$

after renaming indices.

Chapter 12

Chapter 12

Ex. 243: This follows from the definition and from lowering the index γ .

Ex. 244: We have

$$R^{\gamma}_{\delta\alpha\beta} = \frac{\partial\Gamma^{\gamma}_{\beta\delta}}{\partial S^{\alpha}} - \frac{\partial\Gamma^{\gamma}_{\alpha\delta}}{\partial S^{\beta}} + \Gamma^{\gamma}_{\alpha\omega}\Gamma^{\omega}_{\beta\delta} - \Gamma^{\gamma}_{\beta\omega}\Gamma^{\omega}_{\alpha\delta},$$

so

$$\begin{aligned} R^{\delta}_{\delta\alpha\beta} &= \frac{\partial\Gamma^{\delta}_{\beta\delta}}{\partial S^{\alpha}} - \frac{\partial\Gamma^{\delta}_{\alpha\delta}}{\partial S^{\beta}} + \Gamma^{\delta}_{\alpha\omega}\Gamma^{\omega}_{\beta\delta} - \Gamma^{\delta}_{\beta\omega}\Gamma^{\omega}_{\alpha\delta} \\ &= \frac{\partial\Gamma^{\delta}_{\beta\delta}}{\partial S^{\alpha}} - \frac{\partial\Gamma^{\delta}_{\alpha\delta}}{\partial S^{\beta}} + \Gamma^{\omega}_{\beta\delta}\Gamma^{\delta}_{\alpha\omega} - \Gamma^{\delta}_{\beta\omega}\Gamma^{\omega}_{\alpha\delta} \\ &= \frac{\partial\Gamma^{\delta}_{\beta\delta}}{\partial S^{\alpha}} - \frac{\partial\Gamma^{\delta}_{\alpha\delta}}{\partial S^{\beta}} \\ &= 0. \end{aligned}$$

Ex. 245: This was done for the final exam.

Ex. 246: Compute

$$\begin{aligned} R_{\delta\gamma\alpha\beta} &= R_{\alpha\beta\delta\gamma} \quad (12.5) \\ &= -R_{\alpha\beta\gamma\delta} \quad (12.3) \\ &= -R_{\gamma\delta\alpha\beta} \quad (12.5). \end{aligned}$$

Ex. 247: Examine

$$\begin{aligned}
 R_{\alpha\beta} &= R_{\cdot\alpha\gamma\beta}^{\gamma} \\
 &= S^{\delta\gamma} R_{\delta\alpha\gamma\beta} \\
 &= S^{\delta\gamma} R_{\gamma\beta\delta\alpha} \\
 &= S^{\gamma\delta} R_{\gamma\beta\delta\alpha} \\
 &= R_{\cdot\beta\delta\alpha}^{\delta} \\
 &= R_{\cdot\beta\gamma\alpha}^{\gamma} \\
 &= R_{\beta\alpha}.
 \end{aligned}$$

Ex. 248: We may easily see the symmetry of the Einstein tensor from the fact that both $R_{\alpha\beta}$ and $S_{\alpha\beta}$ are symmetric.

Ex. 249: Note

$$\begin{aligned}
 G_{\alpha}^{\beta} &= R_{\alpha\gamma} S^{\gamma\beta} - \frac{1}{2} R S_{\alpha\gamma} S^{\gamma\beta} \\
 &= R_{\alpha\gamma} S^{\gamma\beta} - \frac{1}{2} R \delta_{\alpha}^{\beta},
 \end{aligned}$$

so

$$\begin{aligned}
 G_{\alpha}^{\alpha} &= R_{\alpha\gamma} S^{\gamma\alpha} - R \\
 &= R_{\alpha}^{\alpha} - R \\
 &= R - R \\
 &= 0,
 \end{aligned}$$

since $R_{\alpha}^{\alpha} = R$ by definition.

Ex. 250: We compute

$$\begin{aligned}
 (\nabla_{\alpha} \nabla_{\beta} - \nabla_{\beta} \nabla_{\alpha}) T_{\gamma} &= (\nabla_{\alpha} \nabla_{\beta} - \nabla_{\beta} \nabla_{\alpha}) T^{\delta} S_{\delta\gamma} \\
 &= R_{\cdot\varepsilon\alpha\beta}^{\delta} T^{\varepsilon} S_{\delta\gamma} \\
 &= R_{\cdot\varepsilon\alpha\beta}^{\delta} S_{\delta\gamma} T^{\varepsilon} \\
 &= R_{\gamma\varepsilon\alpha\beta} T^{\varepsilon} \\
 &= R_{\gamma\varepsilon\alpha\beta} T_{\omega} S^{\varepsilon\omega} \\
 &= -R_{\varepsilon\gamma\alpha\beta} T_{\omega} S^{\varepsilon\omega} \\
 &= -R_{\varepsilon\gamma\alpha\beta} S^{\varepsilon\omega} T_{\omega} \\
 &= -R_{\cdot\gamma\alpha\beta}^{\omega} T_{\omega} \\
 &= -R_{\cdot\gamma\alpha\beta}^{\delta} T_{\delta},
 \end{aligned}$$

with index renaming at the last step.

Ex. 251: The invariant case follows from the commutativity of partial derivatives. Now, we consider the covariant case:

$$\begin{aligned}
(\nabla_\alpha \nabla_\beta - \nabla_\beta \nabla_\alpha) T^i &= \nabla_\alpha \nabla_\beta T^i - \nabla_\beta \nabla_\alpha T^i \\
&= \frac{\partial (\nabla_\beta T^i)}{\partial S^\alpha} - \Gamma_{\alpha\beta}^\gamma \nabla_\gamma T^i - \left(\frac{\partial (\nabla_\alpha T^i)}{\partial S^\beta} - \Gamma_{\beta\alpha}^\gamma \nabla_\gamma T^i \right) \\
&= \frac{\partial (\nabla_\beta T^i)}{\partial S^\alpha} - \frac{\partial (\nabla_\alpha T^i)}{\partial S^\beta} \\
&= \frac{\partial}{\partial S^\alpha} \left(\frac{\partial T^i}{\partial S^\beta} + Z_\beta^k \Gamma_{km}^i T^m \right) - \frac{\partial}{\partial S^\beta} \left(\frac{\partial T^i}{\partial S^\alpha} + Z_\alpha^k \Gamma_{km}^i T^m \right) \\
&= \frac{\partial^2 T^i}{\partial S^\alpha \partial S^\beta} + \frac{\partial}{\partial S^\alpha} (Z_\beta^k \Gamma_{km}^i T^m) - \frac{\partial^2 T^i}{\partial S^\alpha \partial S^\beta} - \frac{\partial}{\partial S^\beta} (Z_\alpha^k \Gamma_{km}^i T^m) \\
&= \frac{\partial}{\partial S^\alpha} (Z_\beta^k \Gamma_{km}^i T^m) - \frac{\partial}{\partial S^\beta} (Z_\alpha^k \Gamma_{km}^i T^m) \\
&= \frac{\partial Z_\beta^k}{\partial S^\alpha} \Gamma_{km}^i T^m + Z_\beta^k \frac{\partial \Gamma_{km}^i}{\partial S^\alpha} + Z_\beta^k \Gamma_{km}^i \frac{\partial T^m}{\partial S^\alpha} \\
&\quad - \frac{\partial Z_\alpha^k}{\partial S^\beta} \Gamma_{km}^i T^m - Z_\alpha^k \frac{\partial \Gamma_{km}^i}{\partial S^\beta} T^m - Z_\alpha^k \Gamma_{km}^i \frac{\partial T^m}{\partial S^\beta} \\
&= 0 \text{ [not sure yet]}
\end{aligned}$$

Ex. 252: Look at

$$\begin{aligned}
R_{\alpha\beta\gamma\delta} + R_{\alpha\gamma\delta\beta} + R_{\alpha\delta\beta\gamma} &= \frac{\partial\Gamma_{\alpha,\delta\beta}}{\partial S^\gamma} - \frac{\partial\Gamma_{\alpha,\gamma\beta}}{\partial S^\delta} + \Gamma_{\omega,\alpha\delta}\Gamma_{\gamma\beta}^\omega - \Gamma_{\omega,\beta\delta}\Gamma_{\gamma\alpha}^\omega \\
&+ \frac{\partial\Gamma_{\alpha,\beta\gamma}}{\partial S^\delta} - \frac{\partial\Gamma_{\alpha,\delta\gamma}}{\partial S^\beta} + \Gamma_{\omega,\alpha\beta}\Gamma_{\delta\gamma}^\omega - \Gamma_{\omega,\gamma\beta}\Gamma_{\delta\alpha}^\omega \\
&+ \frac{\partial\Gamma_{\alpha,\gamma\delta}}{\partial S^\beta} - \frac{\partial\Gamma_{\alpha,\beta\delta}}{\partial S^\gamma} + \Gamma_{\omega,\alpha\gamma}\Gamma_{\beta\delta}^\omega - \Gamma_{\omega,\delta\gamma}\Gamma_{\beta\alpha}^\omega \\
&= \frac{\partial\Gamma_{\alpha,\beta\delta}}{\partial S^\gamma} - \frac{\partial\Gamma_{\alpha,\beta\gamma}}{\partial S^\delta} + \Gamma_{\omega,\alpha\delta}\Gamma_{\beta\gamma}^\omega - \Gamma_{\omega,\beta\delta}\Gamma_{\alpha\gamma}^\omega \\
&+ \frac{\partial\Gamma_{\alpha,\beta\gamma}}{\partial S^\delta} - \frac{\partial\Gamma_{\alpha,\gamma\delta}}{\partial S^\beta} + \Gamma_{\omega,\alpha\beta}\Gamma_{\gamma\delta}^\omega - \Gamma_{\omega,\beta\gamma}\Gamma_{\alpha\delta}^\omega \\
&+ \frac{\partial\Gamma_{\alpha,\gamma\delta}}{\partial S^\beta} - \frac{\partial\Gamma_{\alpha,\beta\delta}}{\partial S^\gamma} + \Gamma_{\omega,\alpha\gamma}\Gamma_{\beta\delta}^\omega - \Gamma_{\omega,\gamma\delta}\Gamma_{\alpha\beta}^\omega \\
&= \Gamma_{\omega,\alpha\delta}\Gamma_{\beta\gamma}^\omega - \Gamma_{\omega,\beta\delta}\Gamma_{\alpha\gamma}^\omega \\
&+ \Gamma_{\omega,\alpha\beta}\Gamma_{\gamma\delta}^\omega - \Gamma_{\omega,\beta\gamma}\Gamma_{\alpha\delta}^\omega \\
&+ \Gamma_{\omega,\alpha\gamma}\Gamma_{\beta\delta}^\omega - \Gamma_{\omega,\gamma\delta}\Gamma_{\alpha\beta}^\omega \\
&= S_{\omega\varepsilon}\Gamma_{\alpha\delta}^\varepsilon\Gamma_{\beta\gamma}^\omega - S_{\omega\varepsilon}\Gamma_{\beta\delta}^\varepsilon\Gamma_{\alpha\gamma}^\omega \\
&+ S_{\omega\varepsilon}\Gamma_{\alpha\beta}^\varepsilon\Gamma_{\gamma\delta}^\omega - S_{\omega\varepsilon}\Gamma_{\beta\gamma}^\varepsilon\Gamma_{\alpha\delta}^\omega \\
&+ S_{\omega\varepsilon}\Gamma_{\alpha\gamma}^\varepsilon\Gamma_{\beta\delta}^\omega - S_{\omega\varepsilon}\Gamma_{\gamma\delta}^\varepsilon\Gamma_{\alpha\beta}^\omega \\
&= S_{\omega\varepsilon}\Gamma_{\alpha\delta}^\varepsilon\Gamma_{\beta\gamma}^\omega - S_{\varepsilon\omega}\Gamma_{\beta\delta}^\omega\Gamma_{\alpha\gamma}^\varepsilon \\
&+ S_{\omega\varepsilon}\Gamma_{\alpha\beta}^\varepsilon\Gamma_{\gamma\delta}^\omega - S_{\varepsilon\omega}\Gamma_{\beta\gamma}^\omega\Gamma_{\alpha\delta}^\varepsilon \\
&+ S_{\omega\varepsilon}\Gamma_{\alpha\gamma}^\varepsilon\Gamma_{\beta\delta}^\omega - S_{\varepsilon\omega}\Gamma_{\gamma\delta}^\omega\Gamma_{\alpha\beta}^\varepsilon \\
&= S_{\omega\varepsilon}\Gamma_{\alpha\delta}^\varepsilon\Gamma_{\beta\gamma}^\omega - S_{\omega\varepsilon}\Gamma_{\alpha\gamma}^\varepsilon\Gamma_{\beta\delta}^\omega \\
&+ S_{\omega\varepsilon}\Gamma_{\alpha\beta}^\varepsilon\Gamma_{\gamma\delta}^\omega - S_{\omega\varepsilon}\Gamma_{\alpha\delta}^\varepsilon\Gamma_{\beta\gamma}^\omega \\
&+ S_{\omega\varepsilon}\Gamma_{\alpha\gamma}^\varepsilon\Gamma_{\beta\delta}^\omega - S_{\omega\varepsilon}\Gamma_{\alpha\beta}^\varepsilon\Gamma_{\gamma\delta}^\omega \\
&= 0,
\end{aligned}$$

as desired.

Ex. 253: Compute

$$\begin{aligned}
\nabla_\varepsilon R_{\alpha\beta\gamma\delta} + \nabla_\gamma R_{\alpha\beta\delta\varepsilon} + \nabla_\delta R_{\alpha\beta\varepsilon\gamma} &= \frac{\partial R_{\alpha\beta\gamma\delta}}{\partial S^\varepsilon} - \Gamma_{\alpha\varepsilon}^\omega R_{\omega\beta\gamma\delta} - \Gamma_{\beta\varepsilon}^\omega R_{\alpha\omega\gamma\delta} - \Gamma_{\gamma\varepsilon}^\omega R_{\alpha\beta\omega\delta} - \Gamma_{\delta\varepsilon}^\omega R_{\alpha\beta\gamma\omega} \\
&+ \frac{\partial R_{\alpha\beta\delta\varepsilon}}{\partial S^\gamma} - \Gamma_{\alpha\gamma}^\omega R_{\omega\beta\delta\varepsilon} - \Gamma_{\beta\gamma}^\omega R_{\alpha\omega\delta\varepsilon} - \Gamma_{\delta\gamma}^\omega R_{\alpha\beta\omega\varepsilon} - \Gamma_{\varepsilon\gamma}^\omega R_{\alpha\beta\delta\omega} \\
&+ \frac{\partial R_{\alpha\beta\varepsilon\gamma}}{\partial S^\delta} - \Gamma_{\alpha\delta}^\omega R_{\omega\beta\varepsilon\gamma} - \Gamma_{\beta\delta}^\omega R_{\alpha\omega\varepsilon\gamma} - \Gamma_{\varepsilon\delta}^\omega R_{\alpha\beta\omega\gamma} - \Gamma_{\gamma\delta}^\omega R_{\alpha\beta\varepsilon\omega} \\
&= \frac{\partial R_{\alpha\beta\gamma\delta}}{\partial S^\varepsilon} - \Gamma_{\alpha\varepsilon}^\omega R_{\omega\beta\gamma\delta} - \Gamma_{\beta\varepsilon}^\omega R_{\alpha\omega\gamma\delta} - \Gamma_{\gamma\varepsilon}^\omega R_{\alpha\beta\omega\delta} - \Gamma_{\delta\varepsilon}^\omega R_{\alpha\beta\gamma\omega} \\
&+ \frac{\partial R_{\alpha\beta\delta\varepsilon}}{\partial S^\gamma} - \Gamma_{\alpha\gamma}^\omega R_{\omega\beta\delta\varepsilon} - \Gamma_{\beta\gamma}^\omega R_{\alpha\omega\delta\varepsilon} - \Gamma_{\delta\gamma}^\omega R_{\alpha\beta\omega\varepsilon} + \Gamma_{\varepsilon\gamma}^\omega R_{\alpha\beta\omega\delta} \\
&+ \frac{\partial R_{\alpha\beta\varepsilon\gamma}}{\partial S^\delta} - \Gamma_{\alpha\delta}^\omega R_{\omega\beta\varepsilon\gamma} - \Gamma_{\beta\delta}^\omega R_{\alpha\omega\varepsilon\gamma} + \Gamma_{\varepsilon\delta}^\omega R_{\alpha\beta\omega\gamma} + \Gamma_{\gamma\delta}^\omega R_{\alpha\beta\omega\varepsilon} \\
&= \frac{\partial R_{\alpha\beta\gamma\delta}}{\partial S^\varepsilon} - \Gamma_{\alpha\varepsilon}^\omega R_{\omega\beta\gamma\delta} - \Gamma_{\beta\varepsilon}^\omega R_{\alpha\omega\gamma\delta} \\
&+ \frac{\partial R_{\alpha\beta\delta\varepsilon}}{\partial S^\gamma} - \Gamma_{\alpha\gamma}^\omega R_{\omega\beta\delta\varepsilon} - \Gamma_{\beta\gamma}^\omega R_{\alpha\omega\delta\varepsilon} \\
&+ \frac{\partial R_{\alpha\beta\varepsilon\gamma}}{\partial S^\delta} - \Gamma_{\alpha\delta}^\omega R_{\omega\beta\varepsilon\gamma} - \Gamma_{\beta\delta}^\omega R_{\alpha\omega\varepsilon\gamma} \\
&= \frac{\partial R_{\alpha\beta\gamma\delta}}{\partial S^\varepsilon} - \Gamma_{\alpha\varepsilon}^\omega \left(\frac{\partial \Gamma_{\omega,\delta\beta}}{\partial S^\gamma} - \frac{\partial \Gamma_{\omega,\gamma\beta}}{\partial S^\delta} + \Gamma_{\phi,\omega\delta} \Gamma_{\gamma\beta}^\phi - \Gamma_{\phi,\beta\delta} \Gamma_{\gamma\omega}^\phi \right) - \Gamma_{\beta\varepsilon}^\omega \left(\frac{\partial \Gamma_{\alpha,\delta\omega}}{\partial S^\gamma} - \dots \right) \\
&+ \dots
\end{aligned}$$

Ex. 254: Compute

$$\begin{aligned}
\frac{1}{4} \varepsilon^{\gamma\delta} \varepsilon^{\alpha\beta} R_{\gamma\delta\alpha\beta} &= \frac{1}{4} \varepsilon^{\gamma\delta} \varepsilon^{\alpha\beta} \frac{R_{1212}}{S} \varepsilon_{\gamma\delta} \varepsilon_{\alpha\beta} \\
&= \frac{1}{4} (2)(2) \frac{R_{1212}}{S} \\
&= \frac{R_{1212}}{S} \\
&= K,
\end{aligned}$$

as desired.

Ex. 255: Compute

$$\begin{aligned}
 K(S_{\alpha\gamma}S_{\beta\delta} - S_{\alpha\delta}S_{\beta\gamma}) &= \frac{1}{4}\varepsilon^{\gamma\delta}\varepsilon^{\alpha\beta}R_{\gamma\delta\alpha\beta}(S_{\alpha\gamma}S_{\beta\delta} - S_{\alpha\delta}S_{\beta\gamma}) \\
 &= \frac{1}{4}\varepsilon^{\gamma\delta}\varepsilon^{\alpha\beta}S_{\alpha\gamma}S_{\beta\delta}R_{\gamma\delta\alpha\beta} - \frac{1}{4}\varepsilon^{\gamma\delta}\varepsilon^{\alpha\beta}S_{\alpha\delta}S_{\beta\gamma} \\
 &= \frac{1}{4}\varepsilon^{\gamma\delta}\varepsilon^{\alpha\beta}S_{\alpha\gamma}S_{\beta\delta}R_{\gamma\delta\alpha\beta} + \frac{1}{4}\varepsilon^{\gamma\delta}\varepsilon^{\beta\alpha}S_{\alpha\delta}S_{\beta\gamma} \\
 &= \frac{1}{4}\delta_\alpha^\delta\delta_\delta^\alpha R_{\gamma\delta\alpha\beta} + \frac{1}{4}\delta_\alpha^\gamma\delta_\gamma^\alpha R_{\gamma\delta\alpha\beta} \\
 &= \frac{1}{4}(2)R_{\gamma\delta\alpha\beta} + \frac{1}{4}(2)R_{\gamma\delta\alpha\beta} \\
 &= R_{\gamma\delta\alpha\beta}.
 \end{aligned}$$

Ex. 256: Note

$$\frac{1}{2}R_{\cdot\gamma\delta}^{\alpha\beta} = \frac{1}{2}R_{\omega\xi\gamma\delta}S^{\omega\alpha}S^{\xi\beta},$$

so

$$\begin{aligned}
 \frac{1}{2}R_{\cdot\alpha\beta}^{\alpha\beta} &= \frac{1}{2}R_{\omega\xi\alpha\beta}S^{\omega\alpha}S^{\xi\beta} \\
 &= \frac{1}{2}K\varepsilon_{\omega\xi}\varepsilon_{\alpha\beta}S^{\omega\alpha}S^{\xi\beta} \\
 &= \frac{1}{2}K\delta_\xi^\alpha\delta_\alpha^\xi \\
 &= K
 \end{aligned}$$

Ex. 257: This follows since

$$\nabla_\alpha \mathbf{S}_\beta = \nabla_\beta \mathbf{S}_\alpha,$$

hence

$$\mathbf{N}B_{\alpha\beta} = \mathbf{N}B_{\beta\alpha},$$

or

$$B_{\alpha\beta} = B_{\beta\alpha}.$$

Ex. 258: Note that since $B_\alpha^\alpha = 0$, we have that both eigenvalues of B are equal in absolute value and are negatives of each other; denote them $\lambda, -\lambda$. Thus,

$$|B| = -\lambda^2.$$

Now,

$$B_\beta^\alpha B_\gamma^\beta := C_\gamma^\alpha.$$

In linear algebra terms, we have

$$C = B^2$$

then,

$$\begin{aligned} B_\beta^\alpha B_\alpha^\beta &= \operatorname{tr} B^2 \\ &= \mu_1 + \mu_2, \end{aligned}$$

where μ_1, μ_2 are the eigenvalues of B^2 . But, since $\mu_1 = \lambda^2$ and $\mu_2 = (-\lambda)^2 = \lambda^2$ by the properties of eigenvalues, we have

$$\begin{aligned} B_\beta^\alpha B_\alpha^\beta &= 2\lambda^2 \\ &= -2|B| \end{aligned}$$

by the above.

Ex. 259: We compute, given

$$\begin{aligned} r(z) &= a \cosh\left(\frac{z-b}{a}\right) \\ &= a \left(\frac{e^{(z-b)/a} + e^{(b-z)/a}}{2} \right) \\ &= \frac{a}{2} e^{(z-b)/a} + \frac{a}{2} e^{(b-z)/a} \\ r'(z) &= \frac{1}{2} e^{(z-b)/a} - \frac{1}{2} e^{(b-z)/a} \\ r''(z) &= \frac{1}{2a} e^{(z-b)/a} + \frac{1}{2a} e^{(b-z)/a}. \end{aligned}$$

Compute

$$\begin{aligned}
 r''(z)r(z) - r'(z)^2 &= \left(\frac{1}{2a}e^{(z-b)/a} + \frac{1}{2a}e^{(b-z)/a} \right) \left(\frac{a}{2}e^{(z-b)/a} + \frac{a}{2}e^{(b-z)/a} \right) - \left(\frac{1}{2}e^{(z-b)/a} - \frac{1}{2}e^{(b-z)/a} \right)^2 \\
 &= \frac{1}{4}e^{2(z-b)/a} - \frac{1}{4}e^{2(b-z)/a} - \left[\frac{1}{4}e^{2(z-b)/a} - 1 + \frac{1}{4}e^{2(b-z)/a} \right] \\
 &= 1
 \end{aligned}$$

Thus,

$$r''(z)r(z) - r'(z)^2 - 1 = 0$$

$$\begin{aligned}
 B_\alpha^\alpha &= \frac{r''(z)r(z) - r'(z)^2 - 1}{r(z)\sqrt{1+r'(z)^2}} \\
 &= 0,
 \end{aligned}$$

as desired.

Ex. 260: We have

$$\begin{aligned}
 \mathbf{V} &= \frac{d\mathbf{R}}{dt}(S(t)) \\
 &= \frac{\partial \mathbf{R}}{\partial S^\alpha} \frac{dS^\alpha}{dt} \\
 &= \mathbf{S}_\alpha V^\alpha \\
 &= V^\alpha \mathbf{S}_\alpha
 \end{aligned}$$

as desired.

Ex. 261: Compute

$$\begin{aligned}
\mathbf{A} &= \frac{d\mathbf{V}}{dt} \\
&= \frac{d}{dt} [V^\alpha \mathbf{S}_\alpha] \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\alpha \frac{d\mathbf{S}_\alpha}{dt} (S(t)) \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\alpha \frac{\partial \mathbf{S}_\alpha}{\partial S^\beta} \frac{dS^\beta}{dt} \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\alpha V^\beta \frac{\partial \mathbf{S}_\alpha}{\partial S^\beta} \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\alpha V^\beta \left(\nabla_\beta \mathbf{S}_\alpha + \Gamma_{\alpha\beta}^\gamma \mathbf{S}_\gamma \right) \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\alpha V^\beta \Gamma_{\alpha\beta}^\gamma \mathbf{S}_\gamma + V^\alpha V^\beta \nabla_\beta \mathbf{S}_\alpha \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\beta V^\gamma \Gamma_{\beta\gamma}^\alpha \mathbf{S}_\alpha + V^\alpha V^\beta \nabla_\beta \mathbf{S}_\alpha \\
&= \frac{\delta V^\alpha}{\delta t} \mathbf{S}_\alpha + V^\alpha V^\beta \nabla_\beta \mathbf{S}_\alpha \\
&= \frac{\delta V^\alpha}{\delta t} \mathbf{S}_\alpha + \mathbf{N} V^\alpha V^\beta B_{\alpha\beta} \\
&= \frac{\delta V^\alpha}{\delta t} \mathbf{S}_\alpha + \mathbf{N} B_{\alpha\beta} V^\alpha V^\beta,
\end{aligned}$$

as desired.

Ex. 262: We define

$$\frac{\delta T_\beta^\alpha}{\delta t} = \frac{dT_\beta^\alpha}{dt} + V^\gamma \Gamma_{\gamma\omega}^\alpha T_\beta^\omega - V^\gamma \Gamma_{\gamma\beta}^\omega T_\omega^\alpha.$$

Ex. 263: Look at

$$\begin{aligned}
\frac{\delta T_{\beta'}^{\alpha'}}{\delta t} &= \frac{dT_{\beta'}^{\alpha'}}{dt} + V^\gamma \Gamma_{\gamma\omega}^{\alpha'} T_{\beta'}^\omega - V^\gamma \Gamma_{\gamma\beta'}^\omega T_\omega^{\alpha'} \\
&= \frac{d}{dt} \left(T_\beta^\alpha J_\alpha^{\alpha'} (S(t)) J_{\beta'}^\beta (S'(t)) \right) + V^\gamma \Gamma_{\gamma\omega}^{\alpha'} T_\beta^\omega J_{\beta'}^\beta - V^\gamma \Gamma_{\gamma\beta'}^\omega T_\omega^\alpha J_\alpha^{\alpha'} \\
&= \frac{dT_\beta^\alpha}{dt} J_\alpha^{\alpha'} J_{\beta'}^\beta + T_\beta^\alpha \frac{\partial J_\alpha^{\alpha'}}{\partial S^\gamma} \frac{dS^\gamma}{dt} J_{\beta'}^\beta + T_\beta^\alpha \frac{\partial J_{\beta'}^\beta}{\partial S^{\gamma'}} J_\alpha^{\alpha'} \frac{dS^{\gamma'}}{dt} + V^\gamma \Gamma_{\gamma\omega}^{\alpha'} T_\beta^\omega J_{\beta'}^\beta - V^\gamma \Gamma_{\gamma\beta'}^\omega T_\omega^\alpha J_\alpha^{\alpha'} \\
&= \frac{dT_\beta^\alpha}{dt} J_\alpha^{\alpha'} J_{\beta'}^\beta + T_\beta^\alpha J_{\gamma\alpha}^{\alpha'} V^\gamma J_{\beta'}^\beta + T_\beta^\alpha J_{\gamma'\beta'}^\beta V^{\gamma'} J_\alpha^{\alpha'} + V^\gamma \Gamma_{\gamma\omega}^{\alpha'} T_\beta^\omega J_{\beta'}^\beta - V^\gamma \Gamma_{\gamma\beta'}^\omega T_\omega^\alpha J_\alpha^{\alpha'} \\
&= \dots ??? \\
&= \frac{\delta T_\beta^\alpha}{\delta t} J_\alpha^{\alpha'} J_{\beta'}^\beta
\end{aligned}$$

Ex. 264: These follow from the properties of the standard derivative.

Ex. 265: This also follows from the properties of the standard derivative.

Ex. 266: Not sure - are we considering the surface metrics as functions of time? In that case, would this be a moving surface, and then we would require the derivative in Part III?

Ex. 267: Compute

$$\begin{aligned}
 \frac{\delta \mathbf{S}_\alpha}{\delta t} &= \frac{d\mathbf{S}_\alpha(S(t))}{dt} - V^\gamma \Gamma_{\gamma\beta}^\omega \mathbf{S}_\omega \\
 &= \frac{\partial \mathbf{S}_\alpha}{\partial S^\beta} \frac{dS^\beta}{dt} - V^\gamma \Gamma_{\gamma\beta}^\omega \mathbf{S}_\omega \\
 &= (\nabla_\beta \mathbf{S}_\alpha + \Gamma_{\alpha\beta}^\omega \mathbf{S}_\omega) V^\beta - V^\gamma \Gamma_{\gamma\beta}^\omega \mathbf{S}_\omega \\
 &= \nabla_\beta \mathbf{S}_\alpha V^\beta + V^\beta \Gamma_{\alpha\beta}^\omega \mathbf{S}_\omega - V^\gamma \Gamma_{\gamma\beta}^\omega \mathbf{S}_\omega \\
 &= \nabla_\beta \mathbf{S}_\alpha V^\beta \\
 &= \mathbf{N} B_{\alpha\beta} V^\beta \\
 &= \mathbf{N} V^\beta B_{\alpha\beta},
 \end{aligned}$$

as desired.

Ex. 268: This follows from the sum and product rules.

Ex. 269: [Not finished]

Ex. 270: For a cylinder, we have

$$B_\beta^\alpha = \begin{bmatrix} -\frac{1}{R} & 0 \\ 0 & 0 \end{bmatrix},$$

so

$$\begin{aligned}
 K &= |B| \\
 &= 0 \left(-\frac{1}{R} \right) \\
 &= 0.
 \end{aligned}$$

Ex. 271: For a cone, we have

$$B_{\beta}^{\alpha} = \begin{bmatrix} -\frac{\cot \Theta}{r} & 0 \\ 0 & 0 \end{bmatrix},$$

which has determinant zero. Thus,

$$K = 0.$$

Ex. 272: For a sphere, we have

$$B_{\beta}^{\alpha} = \begin{bmatrix} -\frac{1}{R} & 0 \\ 0 & -\frac{1}{R} \end{bmatrix},$$

so

$$\begin{aligned} K &= |B_{\beta}^{\alpha}| = \left(-\frac{1}{R}\right) \left(-\frac{1}{R}\right) \\ &= \frac{1}{R^2} \end{aligned}$$

Ex. 273: For a torus, we have

$$B_{\beta}^{\alpha} = \begin{bmatrix} -\frac{\cos \phi}{R+r \cos \phi} & 0 \\ 0 & -\frac{1}{r} \end{bmatrix},$$

so

$$K = \frac{\cos \phi}{r(R+r \cos \phi)}$$

Ex. 274: For a surface of revolution, we have

$$B_{\beta}^{\alpha} = \begin{bmatrix} -\frac{1}{r(z)\sqrt{1+r'(z)^2}} & 0 \\ 0 & \frac{r''(z)}{(1+r'(z)^2)^{3/2}} \end{bmatrix},$$

so

$$\begin{aligned} K &= -\frac{1}{r(z)\sqrt{1+r'(z)^2}} \frac{r''(z)}{(1+r'(z)^2)^{3/2}} \\ &= -\frac{r''(z)}{r(z)(1+r'(z)^2)^2} \end{aligned}$$

Ex. 275: We integrate

$$\begin{aligned}\int_S K dS &= \int_S \frac{1}{R^2} dS \\ &= \frac{1}{R^2} \int_S dS \\ &= \frac{1}{R^2} 4\pi R^2 \\ &= 4\pi\end{aligned}$$

Ex. 276: We integrate

$$\begin{aligned}\int_S \frac{\cos \phi}{r(R+r \cos \phi)} dS &= \int_0^{2\pi} \int_0^{2\pi} \frac{\cos \phi}{r(R+r \cos \phi)} \sqrt{S} d\phi d\theta \\ &= \int_0^{2\pi} \int_0^{2\pi} \frac{\cos \phi}{r(R+r \cos \phi)} r(R+r \cos \phi) d\phi d\theta \\ &= \int_0^{2\pi} \int_0^{2\pi} \cos \phi d\phi d\theta \\ &= 2\pi (\sin(2\pi) - \sin(0)) \\ &= 0.\end{aligned}$$

Part III

Part III

Ex. 291: We have

$$\theta(\alpha) = \operatorname{arccot}(At \cot \alpha),$$

so

$$\begin{aligned}\theta &= \operatorname{arccot}(At \cot \alpha) \\ \cot \theta &= At \cot \alpha \\ \frac{1}{At} \cot \theta &= \cot \alpha \\ \alpha(\theta) &= \operatorname{arccot}\left(\frac{1}{At} \cot \theta\right)\end{aligned}$$

$$\begin{aligned}J_t^\alpha &= \frac{\partial S^\alpha(t, S')}{\partial t} \\ &= \frac{\partial}{\partial t} \operatorname{arccot}\left(\frac{1}{At} \cot \theta\right) \\ &= -\frac{1}{1 + \frac{1}{A^2 t^2} \cot^2 \theta} \cdot -\frac{\cot \theta}{At^2} \\ &= \frac{\cot \theta}{At^2 + \frac{1}{A} \cot^2 \theta} \\ &= \frac{A \cot \theta}{A^2 t^2 + \cot^2 \theta}\end{aligned}$$

$$\begin{aligned}J_t^{\alpha'} &= \frac{\partial}{\partial t} \operatorname{arccot}(At \cot \alpha) \\ &= -\frac{A \cot \alpha}{1 + A^2 t^2 \cot^2 \alpha}\end{aligned}$$

Ex. 292:

$$V^\nu = \frac{\partial Z^i}{\partial t} = \begin{bmatrix} A \cos \alpha \\ 0 \end{bmatrix}$$

Ex. 293:

$$\begin{aligned}
 V^i &= \frac{\partial Z^i}{\partial t} = \left[\begin{array}{c} \frac{\partial}{\partial t} \left(\frac{A \cos \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \right) \\ \frac{\partial}{\partial t} \left(\frac{A \sin \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \right) \end{array} \right] \\
 &= \left[\begin{array}{c} -\frac{2A^2 t \sin^2 \theta \cdot A \cos \theta}{2\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}^3} \\ -\frac{2A^2 t \sin^2 \theta \cdot A \sin \theta}{2\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}^3} \end{array} \right] \\
 &= \left[\begin{array}{c} -\frac{A^3 t \sin^2 \theta \cos \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}^3} \\ -\frac{A^3 t \sin^3 \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}^3} \end{array} \right].
 \end{aligned}$$

Ex. 294: Clearly, the above expressions do not show the tensor property with respect to changes in surface coordinates.

Ex. 295: First, note our parametrization:

$$Z^i(\alpha) = \begin{bmatrix} At \cos \alpha \\ \sin \alpha \end{bmatrix}$$

Then, compute the shift tensors:

$$\begin{aligned}
 Z_{\alpha}^i &= \frac{\partial Z^i}{\partial S^{\alpha}} \\
 &= \begin{bmatrix} -At \sin \alpha \\ \cos \alpha \end{bmatrix},
 \end{aligned}$$

so

$$Z_i^{\alpha} = \left[-\frac{1}{At} \sin \alpha \quad \cos \alpha \right],$$

since we need

$$Z_i^{\alpha} Z_{\beta}^i = \delta_{\beta}^{\alpha}.$$

Thus,

$$\begin{aligned}
 V^{\alpha} &= V^i Z_i^{\alpha} \\
 &= \left[-\frac{1}{At} \sin \alpha \quad \cos \alpha \right] \begin{bmatrix} A \cos \alpha \\ 0 \end{bmatrix} \\
 &= \left[-\frac{1}{t} \sin \alpha \right].
 \end{aligned}$$

Ex. 296: Recall

$$Z^i(\theta) = \begin{bmatrix} \frac{A \cos \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \\ \frac{A \sin \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \end{bmatrix},$$

and note that

$$\begin{aligned} \frac{\partial}{\partial \theta} \sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta} &= \frac{-2 \cos \theta \sin \theta + 2A^2 t^2 \sin \theta \cos \theta}{2\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \\ &= \frac{A^2 t^2 \sin \theta \cos \theta - \cos \theta \sin \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \end{aligned}$$

so

$$\begin{aligned} Z_\alpha^i &= \frac{\partial Z^i}{\partial S^\alpha} \\ &= \frac{1}{\cos^2 \theta + A^2 t^2 \sin^2 \theta} \begin{bmatrix} \sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta} (-A \sin \theta) - A \cos \theta \frac{A^2 t^2 \sin \theta \cos \theta - \cos \theta \sin \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \\ \sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta} (A \cos \theta) - A \sin \theta \frac{A^2 t^2 \sin \theta \cos \theta - \cos \theta \sin \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \end{bmatrix}, \end{aligned}$$

The result is $V^\alpha = 0$, since the motion of a particle on the surface with constant θ is normal to tangent space; hence the projection $V^\alpha = V^i Z_i^\alpha = 0$.

Ex. 297: We see that V^α is not a tensor with respect to changes in ambient coordinates.

Ex. 298: We have

$$\mathbf{V} = V^i \mathbf{Z}_i,$$

so

$$\mathbf{V} \cdot \mathbf{Z}^j = V^j,$$

confirming that V^i is a tensor (\mathbf{V} is an invariant and \mathbf{Z}^j is a tensor).

Ex. 299: Both V^i and Z_i^α are tensors with regard to ambient coordinate changes; hence the contraction $V^\alpha = V^i Z_i^\alpha$ is a tensor with regard to ambient coordinate changes.

Ex. 300: This was done before.

Ex. 301: Both parametrizations use Cartesian ambient coordinates. Thus, the Jacobians $J_i^{i'}$ are the identity. We compute

$$\begin{aligned} V^i J_i^{j'} + Z_\alpha^i J_i^{j'} J_t^\alpha &= V^i + Z_\alpha^i J_t^\alpha \\ &= \begin{bmatrix} A \cos \alpha \\ 0 \end{bmatrix} + \frac{A \cot \theta}{A^2 t^2 + \cot^2 \theta} \begin{bmatrix} -\frac{1}{At} \sin \alpha \\ \cos \alpha \end{bmatrix}. \end{aligned}$$

[To be continued]

Ex. 302: Write

$$\begin{aligned}
 V^{\alpha'} &= V^{i'} Z_{i'}^{\alpha'} \\
 &= \left(V^i J_i^{i'} + Z_\alpha^i J_i^{i'} J_t^\alpha \right) Z_j^\beta J_{i'}^j J_\beta^{\alpha'} \\
 &= V^i J_i^{i'} Z_j^\beta J_{i'}^j J_\beta^{\alpha'} + Z_\alpha^i J_i^{i'} J_t^\alpha Z_j^\beta J_{i'}^j J_\beta^{\alpha'} \\
 &= V^i Z_j^\beta J_\beta^{\alpha'} \delta_i^j + Z_\alpha^i J_t^\alpha Z_j^\beta J_\beta^{\alpha'} \delta_i^j \\
 &= V^j Z_j^\beta J_\beta^{\alpha'} + Z_\alpha^j J_t^\alpha Z_j^\beta J_\beta^{\alpha'} \\
 &= V^\beta J_\beta^{\alpha'} + \delta_\beta^\alpha J_t^\alpha J_\beta^{\alpha'} \\
 &= V^\beta J_\beta^{\alpha'} + J_\beta^{\alpha'} J_t^\beta,
 \end{aligned}$$

as desired.

Ex. 303: Let the unprimed coordinates denote the first parametrization. Then, note

$$\begin{aligned}
 J_\beta^{\alpha'} &= \frac{d}{d\alpha} (\operatorname{arccot} (At \cot \alpha)) \\
 &= -\frac{1}{1 + A^2 t^2 \cot^2 \alpha} (-At \csc^2 \alpha) \\
 &= \frac{At \csc^2 \alpha}{1 + A^2 t^2 \cot^2 \alpha}
 \end{aligned}$$

$$\begin{aligned}
 V^\beta J_\beta^{\alpha'} + J_\beta^{\alpha'} J_t^\beta &= -\frac{1}{t} \sin \alpha \frac{At \csc^2 \alpha}{1 + A^2 t^2 \cot^2 \alpha} + \frac{A \cot \theta}{A^2 t^2 + \cot^2 \theta} \frac{At \csc^2 \alpha}{1 + A^2 t^2 \cot^2 \alpha} \\
 &=
 \end{aligned}$$

[perhaps I am using the wrong Jacobians]

Ex. 304: We have

$$Z^i = \begin{bmatrix} t \cos \alpha \\ \sin \alpha \end{bmatrix},$$

so

$$\mathbf{S}_\alpha = \frac{d}{d\alpha} (t \cos \alpha) \mathbf{i} + \frac{d}{d\alpha} (\sin \alpha) \mathbf{j},$$

since our ambient space is in Cartesian coordinates. So,

$$\mathbf{S}_\alpha = -t \sin \alpha \mathbf{i} + \cos \alpha \mathbf{j},$$

and choose the outward normal

$$\mathbf{N} = \cos \alpha \mathbf{i} + t \sin \alpha \mathbf{j},$$

and thus

$$N^i = \begin{bmatrix} \cos \alpha \\ t \sin \alpha \end{bmatrix},$$

and

$$N_i = [\cos \alpha \quad t \sin \alpha],$$

since our ambient space is in Cartesian coordinates. Thus,

$$\begin{aligned} C &= V^i N_i \\ &= [\cos \alpha \quad t \sin \alpha] \begin{bmatrix} \cos \alpha \\ 0 \end{bmatrix} \\ &= \cos^2 \alpha. \end{aligned}$$

Ex. 305: As before, compute

$$\begin{aligned} \mathbf{S}_\alpha &= \frac{d}{d\theta} \left(\frac{\cos \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} \right) \mathbf{i} + \frac{d}{d\theta} \left(\frac{\sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} \right) \mathbf{j} \\ &= \frac{1}{\cos^2 \theta + t^2 \sin^2 \theta} \left(\left(\sqrt{\cos^2 \theta + t^2 \sin^2 \theta} (-\sin \theta) - \cos \theta \frac{t^2 \sin \theta \cos \theta - \cos \theta \sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} \right) \mathbf{i} + \sqrt{\cos^2 \theta + t^2 \sin^2 \theta} (\cos \theta) \mathbf{j} \right) \\ &= \left(-\frac{\sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} - \frac{t^2 \sin \theta \cos^2 \theta - \cos^2 \theta \sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}^3} \right) \mathbf{i} + \left(\frac{\cos \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} - \frac{t^2 \sin^2 \theta \cos \theta - \cos \theta \sin^2 \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}^3} \right) \mathbf{j}, \end{aligned}$$

so

$$N_i = \left[\frac{\cos \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} - \frac{-\cos \theta \sin^2 \theta + t^2 \cos \theta \sin^2 \theta}{(\cos^2 \theta + t^2 \sin^2 \theta)^{\frac{3}{2}}}, \frac{\sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} + \frac{-\cos^2 \theta \sin \theta + t^2 \cos^2 \theta \sin \theta}{(\cos^2 \theta + t^2 \sin^2 \theta)^{\frac{3}{2}}} \right],$$

and

$$\begin{aligned} C &= V^i N_i \\ &= \left[\frac{\cos \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} - \frac{-\cos \theta \sin^2 \theta + t^2 \cos \theta \sin^2 \theta}{(\cos^2 \theta + t^2 \sin^2 \theta)^{\frac{3}{2}}}, \frac{\sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} + \frac{-\cos^2 \theta \sin \theta + t^2 \cos^2 \theta \sin \theta}{(\cos^2 \theta + t^2 \sin^2 \theta)^{\frac{3}{2}}} \right] \begin{bmatrix} -\frac{t \sin^2 \theta \cos \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}^3} \\ -\frac{t \sin^3 \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}^3} \end{bmatrix} \\ &= \end{aligned}$$

[Note: Shouldn't both be 1 by geometric considerations?]

Ex. 306: We have

$$\begin{aligned} V^{\alpha'} &= V^\alpha J_\alpha^{\alpha'} + J_\alpha^{\alpha'} J_t^\alpha \\ \frac{\partial T(t, S')}{\partial t} &= \frac{\partial T(t, S)}{\partial t} + J_t^\alpha \nabla_\alpha t, \end{aligned}$$

so compute

$$\begin{aligned} \dot{\nabla} T(t, S') &= \frac{\partial T(t, S')}{\partial t} - V^{\alpha'}(t, S') \nabla_{\alpha'} T \\ &= \frac{\partial T(t, S)}{\partial t} + J_t^\alpha \nabla_\alpha t - V^{\alpha'} \nabla_\beta T J_\beta^{\alpha'}, \end{aligned}$$

since $\nabla_{\alpha'} T$ has the tensor property. But,

$$V^{\alpha'} = V^\gamma J_\gamma^{\alpha'} + J_\gamma^{\alpha'} J_t^\gamma,$$

so

$$\begin{aligned} \dot{\nabla} T(t, S') &= \frac{\partial T(t, S)}{\partial t} + J_t^\alpha \nabla_\alpha t - \left(V^\gamma J_\gamma^{\alpha'} + J_\gamma^{\alpha'} J_t^\gamma \right) \nabla_\beta T J_\beta^{\alpha'} \\ &= \frac{\partial T(t, S)}{\partial t} + J_t^\alpha \nabla_\alpha t - \left(V^\gamma \delta_\gamma^\beta + J_t^\gamma \delta_\gamma^\beta \right) \nabla_\beta T \\ &= \frac{\partial T(t, S)}{\partial t} + J_t^\alpha \nabla_\alpha t - V^\beta \nabla_\beta T - J_t^\beta \nabla_\beta T \\ &= \frac{\partial T(t, S)}{\partial t} - V^\beta \nabla_\beta T \\ &= \frac{\partial T(t, S)}{\partial t} - V^\alpha \nabla_\alpha T, \end{aligned}$$

so $\dot{\nabla} T$ does not depend on changes in surface coordinates.

Ex. 307: This follows from the sum rule for partial derivatives and the covariant derivative

Ex. 308: This follows from the product rule for partial derivatives and the covariant derivative.

Ex. 309: Same as above

Ex. 310: This follows because the numerator of 15.33 would be zero.

Ex. 311: This follows from the definition of C , since we take our $\mathbf{R}(S_t + h)$ in the normal direction.

Ex. 312: We have

$$\mathbf{S}_\alpha = Z_\alpha^i \mathbf{Z}_i.$$

Ex. 313: Begin with

$$\dot{\nabla} \mathbf{R} = (V^i - V^\alpha Z_\alpha^i) \mathbf{Z}_i$$

and

$$V^\alpha = V^j Z_j^\alpha,$$

so

$$\begin{aligned} \dot{\nabla} \mathbf{R} &= (V^i - V^j Z_j^\alpha Z_\alpha^i) \mathbf{Z}_i \\ &= (V^i - V^j (\delta_j^i - N^i N_j)) \mathbf{Z}_i \\ &= (V^i - V^i + V^j N^i N_j) \mathbf{Z}_i \\ &= V^j N^i N_j \mathbf{Z}_i, \end{aligned}$$

as desired.

Ex. 314: Compute

$$\begin{aligned} \frac{d}{dt} \int_S \mathbf{N} B_\alpha^\alpha dS &= \frac{d}{dt} \int_S \nabla^\alpha \mathbf{S}_\alpha dS \\ &= \int_S \dot{\nabla} (\nabla^\alpha \mathbf{S}_\alpha) dS - \int_S C B_\alpha^\alpha \nabla^\beta \mathbf{S}_\beta dS \\ &= \int_S \frac{\partial (\nabla^\alpha \mathbf{S}_\alpha)}{\partial t} - V^\beta \nabla_\beta \nabla^\alpha \mathbf{S}_\alpha dS - \int_S C B_\alpha^\alpha \nabla^\beta \mathbf{S}_\beta dS \\ &= \int_S \frac{\partial (\nabla^\alpha \mathbf{S}_\alpha)}{\partial t} - V^i Z_i^\beta \nabla_\beta \nabla^\alpha \mathbf{S}_\alpha dS - \int_S C B_\alpha^\alpha \nabla^\beta \mathbf{S}_\beta dS \end{aligned}$$

[ask about integral problems]

Ex. 315: By the above,

$$\int_S \mathbf{N} B_\alpha^\alpha dS$$

is constant. Since our surface is of genus zero, we may smoothly append our surface evolution so that for all $t \geq T$ for some T , S is a sphere of constant

radius 1. Since the above quantity is constant for all t , then it must be equal to

$$-2 \int_S \mathbf{N} dS$$

for all t , since for a sphere,

$$B_\alpha^\alpha = \frac{-2}{R}.$$

But, $\int_S \mathbf{N} dS = 0$ (our surface is closed), so we have that $\int_S \mathbf{N} B_\alpha^\alpha dS$ vanishes.

Ex. 316: Need to show:

$$\frac{d}{dt} \int_\Omega F d\Omega = \int_\Omega \frac{\partial F}{\partial t} d\Omega + \int_S C F dS,$$

i.e.

$$\frac{d}{dt} \int_{A_1}^{A_2} \int_0^{b(t,x)} F(x,y) dy dx = \int_S C F dS,$$

since $\frac{\partial F}{\partial t} = 0$.

Clearly, C is zero on all of S except for the portion given by the graph of b . Let B denote the surface given by this graph. Then,:

$$\int_S C F dS = \int_B C F dB$$

Clearly, \mathbf{S}_α is the vector (given relative to the ambient Cartesian basis)

$$\mathbf{S}_\alpha = \mathbf{i} + b_x \mathbf{j},$$

so

$$\mathbf{N} = \frac{1}{\sqrt{1+b_x^2}} (-b_x \mathbf{i} + \mathbf{j}),$$

and

$$V^i = \begin{bmatrix} 0 \\ b_t \end{bmatrix},$$

so

$$\begin{aligned} C &= V^i N_i \\ &= \frac{b_t}{\sqrt{1+b_x^2}}. \end{aligned}$$

Now, at each t , our surface has line element $\sqrt{1 + b_x^2}$, so

$$\begin{aligned} \int_B CFdB &= \int_{A_1}^{A_2} b_t F(x, b(t, x)) dx \\ &= \int_{A_1}^{A_2} \frac{d}{dt} \int_0^{b(t, x)} F(x, y) dy dx, \end{aligned}$$

by FTC,

$$= \frac{d}{dt} \int_{A_1}^{A_2} \int_0^{b(t, x)} F(x, y) dy dx$$

Ex. 317: We have

$$\begin{aligned} U^{i'} &= \frac{\partial T^{i'}}{\partial t}(t, S') \\ &= \frac{\partial}{\partial t} \left(T^i(t, S) J_i^{i'}(Z(t, S)) \right) \\ &= \frac{\partial}{\partial t} T^i(t, S(t, S')) J_i^{i'} + T^i \frac{\partial}{\partial t} \left(J_i^{i'}(Z(t, S)) \right) \\ &= \left(\frac{\partial T^i}{\partial t} + \frac{\partial T^i}{\partial S^\alpha} \frac{\partial}{\partial t} S^\alpha \right) J_i^{i'} + T^i \frac{\partial J_i^{i'}}{\partial Z^j} \frac{\partial}{\partial t} Z(t, S) \\ &= \left(\frac{\partial T^i}{\partial t} + \frac{\partial T^i}{\partial S^\alpha} \frac{\partial S^\alpha}{\partial t} \right) J_i^{i'} + T^i J_{ji}^{i'} \left(\frac{\partial Z^j}{\partial t} + \frac{\partial Z^j}{\partial S^\alpha} \frac{\partial S^\alpha}{\partial t} \right) \\ &= \left(U^i + \frac{\partial T^i}{\partial S^\alpha} J_t^\alpha \right) J_i^{i'} + T^i J_{ji}^{i'} (V^j + Z_\alpha^j J_t^\alpha) \\ &= U^i J_i^{i'} + \frac{\partial T^i}{\partial S^\alpha} J_t^\alpha J_i^{i'} + T^i J_{ji}^{i'} V^j + T^i J_{ji}^{i'} Z_\alpha^j J_t^\alpha, \end{aligned}$$

which is the desired result.

Ex. 318: This follows similarly to the above.

Ex. 319: Write

$$\begin{aligned} U^{\alpha'} &= \frac{\partial T^{\alpha'}}{\partial t}(t, S') \\ &= \frac{\partial}{\partial t} \left(T^\alpha(t, S) J_\alpha^{\alpha'}(t, S) \right) \\ &= \frac{\partial}{\partial t} T^\alpha(t, S) J_\alpha^{\alpha'} + T^\alpha \frac{\partial}{\partial t} J_\alpha^{\alpha'}(t, S) \\ &= \left(\frac{\partial T^\alpha}{\partial t} + \frac{\partial T^\alpha}{\partial S^\beta} \frac{\partial S^\beta}{\partial t} \right) J_\alpha^{\alpha'} + T^\alpha \left(\frac{\partial J_\alpha^{\alpha'}}{\partial t} + \frac{\partial J_\alpha^{\alpha'}}{\partial S^\beta} \frac{\partial S^\beta}{\partial t} \right) \\ &= U^\alpha J_\alpha^{\alpha'} + \frac{\partial T^\alpha}{\partial S^\beta} J_t^\beta J_\alpha^{\alpha'} + T^\alpha J_{\alpha t}^{\alpha'} + T^\alpha J_{\beta \alpha}^{\alpha'} J_t^\beta. \end{aligned}$$

Ex. 320: The covariant case is analogous to the above.

Ex. 321: Note

$$\begin{aligned}
V^\alpha \nabla_\alpha T^{i'} &= V^\alpha \nabla_\alpha T^i J_i^{j'} \\
&= V^\alpha \left(\frac{\partial T^i}{\partial S^\alpha}(t, S) + \Gamma_{jk}^i T^j Z_\alpha^k \right) J_i^{j'} \\
&= V^{j'} Z_{j'}^\alpha \left(\frac{\partial T^i}{\partial S^\alpha}(t, S) + \Gamma_{jk}^i T^k Z_\alpha^j \right) J_i^{j'} \\
&= \left(V^j J_j^{j'} + Z_\beta^j J_j^{j'} J_t^\beta \right) \left(\frac{\partial T^i}{\partial S^\alpha}(t, S) + \Gamma_{jk}^i T^k Z_\alpha^j \right) J_i^{j'} \\
&= \left(V^j J_j^{j'} \frac{\partial T^i}{\partial S^\alpha} + V^j J_j^{j'} \Gamma_{jk}^i T^k Z_\alpha^j + Z_\beta^j J_j^{j'} J_t^\beta \frac{\partial T^i}{\partial S^\alpha} + Z_\beta^j J_j^{j'} J_t^\beta \Gamma_{jk}^i T^k Z_\alpha^j \right) J_i^{j'} \\
&= V^j J_j^{j'} \frac{\partial T^i}{\partial S^\alpha} J_i^{j'} + V^j J_j^{j'} \Gamma_{jk}^i T^k Z_\alpha^j J_i^{j'} + Z_\beta^j J_j^{j'} J_t^\beta \frac{\partial T^i}{\partial S^\alpha} J_i^{j'} + Z_\beta^j J_j^{j'} J_t^\beta \Gamma_{jk}^i T^k Z_\alpha^j J_i^{j'},
\end{aligned}$$

so given our work above,

$$\begin{aligned}
\frac{\partial T^{i'}}{\partial t} - V^\alpha \nabla_\alpha T^{i'} &= \frac{\partial T^i}{\partial t} J_i^{j'} + \frac{\partial T^i}{\partial S^\alpha} J_t^\alpha J_i^{j'} + T^i J_{ji}^{j'} V^j + T^i J_{ji}^{j'} Z_\alpha^j J_t^\alpha \\
&\quad - \left(V^j J_j^{j'} \frac{\partial T^i}{\partial S^\alpha} J_i^{j'} + V^j J_j^{j'} \Gamma_{jk}^i T^k Z_\alpha^j J_i^{j'} + Z_\beta^j J_j^{j'} J_t^\beta \frac{\partial T^i}{\partial S^\alpha} J_i^{j'} + Z_\beta^j J_j^{j'} J_t^\beta \Gamma_{jk}^i T^k Z_\alpha^j J_i^{j'} \right)
\end{aligned}$$

[not finished]

Chapter 13

Chapter 16

Ex. 325: Assume the sum, product rules hold, in addition to commutativity with contraction and the metrinilic property with respect to the ambient basis. Then, compute

$$\begin{aligned}\dot{\mathbf{T}} &= \dot{\nabla} (T^i \mathbf{Z}_i) \\ &= \dot{\nabla} T^i \mathbf{Z}_i + T^i \dot{\nabla} \mathbf{Z}_i,\end{aligned}$$

by commutativity with contraction and the product rule,

$$= T^i \mathbf{Z}_i,$$

since the second term would be zero by the metrinilic property.

Ex. 326: Compute

$$\begin{aligned}\frac{\partial \mathbf{Z}_i}{\partial t} &= \frac{\partial \mathbf{Z}_i(Z(t))}{\partial t} \\ &= \frac{\partial \mathbf{Z}_i}{\partial Z^j} \frac{\partial Z^j}{\partial t} \\ &= \Gamma_{ij}^k \mathbf{Z}_k V^j \\ &= V^j \Gamma_{ij}^k \mathbf{Z}_k,\end{aligned}$$

as desired.

Ex. 327: Write

$$\mathbf{T} = T_i \mathbf{Z}^i,$$

so

$$\dot{\nabla} T_i \mathbf{Z}^i = \dot{\nabla} \mathbf{T} = \frac{\partial T_i}{\partial t} \mathbf{Z}^i + T_i \frac{\partial \mathbf{Z}^i}{\partial t} - V^\gamma \nabla_\gamma T_i \mathbf{Z}^i,$$

but

$$\begin{aligned}\frac{\partial \mathbf{Z}^i}{\partial t} &= \frac{\partial \mathbf{Z}^i}{\partial Z^j} \frac{\partial Z^j}{\partial t} \\ &= -\Gamma_{jk}^i \mathbf{Z}^k V^j \\ &= -\Gamma_{jk}^i V^j \mathbf{Z}^k,\end{aligned}$$

so we have

$$\dot{\nabla} T_i = \frac{\partial T_i}{\partial t} - V^\gamma \nabla_\gamma T_i - V^j \Gamma_{ij}^k T_k,$$

after index renaming in the second term of the above expression.

Ex. 328: We know $\dot{\nabla} \mathbf{T}$ is invariant, and since $\dot{\nabla} \mathbf{T} = \dot{\nabla} T^i \mathbf{Z}_i$ and \mathbf{Z}_i is a tensor, by the quotient law, $\dot{\nabla} T^i$ must be a tensor. An argument using changes in coordinates would follow similarly to the covariant derivative computations.

Ex. 329: This also follows from the fact that $\dot{\nabla} \mathbf{T} = \dot{\nabla} T_i \mathbf{Z}^i$ and by the quotient law. An argument using changes in coordinates would also follow similarly.

Ex. 330: Put

$$\mathbf{S}_j = T_j^i \mathbf{Z}_i.$$

then, clearly,

$$\dot{\nabla} \mathbf{S}_j = \dot{\nabla} T_j^i \mathbf{Z}_i.$$

Dot both sides with \mathbf{Z}^k :

$$\begin{aligned}\dot{\nabla} \mathbf{S}_j \cdot \mathbf{Z}^k &= \dot{\nabla} T_j^i \mathbf{Z}_i \cdot \mathbf{Z}^k \\ \dot{\nabla} \mathbf{S}_j \cdot \mathbf{Z}^k &= \dot{\nabla} T_j^k.\end{aligned}$$

Since the LHS is clearly a tensor, the RHS is as well.

Ex. 331: We may use induction with a process similar to 330 to extend this result to arbitrary indices.

Ex. 332: Assume S^i, T_i^j are arbitrary tensors. Put

$$U^j = S^i T_i^j.$$

Now, compute

$$\begin{aligned}\dot{\nabla} \left(S^i T_i^j \right) &= \frac{\partial \left(S^i T_i^j \right)}{\partial t} - V^\gamma \nabla_\gamma \left(S^i T_i^j \right) + V^n \Gamma_{nk}^j S^i T_i^j \\ &= \frac{\partial U^j}{\partial t} - V^\gamma \nabla_\gamma U^j + V^n \Gamma_{nk}^j S^i T_i^j,\end{aligned}$$

since both the partial derivatives and the covariant surface derivatives commute with contraction.

Ex. 333: This follows from the sum and product rules for the partial derivatives and the covariant surface derivative.

Ex. 334: Note

$$\nabla_\gamma T_j^i = Z_\gamma^k \nabla_k T_j^i,$$

and compute

$$\begin{aligned}\dot{\nabla} T_j^i(t, S) &= \frac{\partial T_j^i(t, Z(t, S))}{\partial t} - V^\gamma \nabla_\gamma T_j^i(t, Z(t, S)) + V^k \Gamma_{km}^i T_j^m(t, Z(t, S)) - V^k \Gamma_{kj}^m T_m^i(t, Z(t, S)) \\ &= \frac{\partial T_j^i}{\partial t} + \frac{\partial T_j^i}{\partial Z^k} \frac{\partial Z^k}{\partial t} - V^\gamma Z_\gamma^k \nabla_k T_j^i + V^k \Gamma_{km}^i T_j^m - V^k \Gamma_{kj}^m T_m^i \\ &= \frac{\partial T_j^i}{\partial t} + \frac{\partial T_j^i}{\partial Z^k} V^k - V^\gamma Z_\gamma^k \nabla_k T_j^i + V^k \Gamma_{km}^i T_j^m - V^k \Gamma_{kj}^m T_m^i \\ &= \frac{\partial T_j^i}{\partial t} + \left(\frac{\partial T_j^i}{\partial Z^k} + \Gamma_{km}^i T_j^m - \Gamma_{kj}^m T_m^i \right) V^k - V^\gamma Z_\gamma^k \nabla_k T_j^i \\ &= \frac{\partial T_j^i}{\partial t} + \nabla_k T_j^i V^k - V^\gamma Z_\gamma^k \nabla_k T_j^i \\ &= \frac{\partial T_j^i}{\partial t} + (V^k - V^\gamma Z_\gamma^k) \nabla_k T_j^i \\ &= \frac{\partial T_j^i}{\partial t} + CN^k \nabla_k T_j^i,\end{aligned}$$

where the last step follows from the observation that $V^k - V^\gamma Z_\gamma^k$ is the normal component.

Ex. 335: Note that $\frac{\partial \mathbf{Z}_i}{\partial t} = 0$, and the second term of the above is also zero by the metrinilic property for covariant derivatives. Hence, $\dot{\nabla} \mathbf{Z}_i = 0$. the other results follow similarly.

Ex. 336: Compute

$$\begin{aligned}
\frac{\partial \mathbf{S}_\beta(Z(t, S))}{\partial t} &= \frac{\partial \mathbf{S}_\beta}{\partial Z^i} \frac{\partial Z^i}{\partial t} \\
&= \frac{\partial \mathbf{S}_\beta}{\partial Z^i} V^i \\
&= \frac{\partial \mathbf{S}_\beta}{\partial S^\alpha} \frac{\partial S^\alpha}{\partial Z^i} V^i \\
&= \frac{\partial^2 \mathbf{R}}{\partial S^\alpha \partial S^\beta} Z_i^\alpha V^i \\
&= \frac{\partial \mathbf{S}_\alpha}{\partial S^\beta} Z_i^\alpha V^i \\
&= [\text{not sure}]
\end{aligned}$$

Ex. 337: Simply decompose \mathbf{V} into its tangential and normal coordinates, to obtain the substitution used for the RHS.

Ex. 338: Compute

$$\begin{aligned}
\nabla_\beta (V^\alpha \mathbf{S}_\alpha + C\mathbf{N}) &= \nabla_\beta V^\alpha \mathbf{S}_\alpha + V^\alpha \nabla_\beta \mathbf{S}_\alpha + \nabla_\beta C\mathbf{N} + C\nabla_\beta \mathbf{N} \\
&= \nabla_\beta V^\alpha \mathbf{S}_\alpha + V^\alpha \mathbf{N} B_{\beta\alpha} + \mathbf{N} \nabla_\beta C + C(-B_\beta^\alpha \mathbf{S}_\alpha) \\
&= \nabla_\beta V^\alpha \mathbf{S}_\alpha + V^\alpha \mathbf{N} B_{\beta\alpha} + \mathbf{N} \nabla_\beta C - C B_\beta^\alpha \mathbf{S}_\alpha.
\end{aligned}$$

Ex. 339: Use

$$\begin{aligned}
\dot{\nabla} \mathbf{T} &= \frac{\partial T^\alpha}{\partial t} \mathbf{S}_\alpha + T^\beta \frac{\partial \mathbf{S}_\beta}{\partial t} - V^\beta \nabla_\beta T^\alpha \mathbf{S}_\alpha - V^\beta T^\alpha \mathbf{N} B_{\beta\alpha} \\
&= \frac{\partial T^\alpha}{\partial t} \mathbf{S}_\alpha + T^\beta (\nabla_\beta V^\alpha \mathbf{S}_\alpha + V^\alpha \mathbf{N} B_{\beta\alpha} + \mathbf{N} \nabla_\beta C - C B_\beta^\alpha \mathbf{S}_\alpha) - V^\beta \nabla_\beta T^\alpha \mathbf{S}_\alpha - V^\beta T^\alpha \mathbf{N} B_{\beta\alpha} \\
&= \frac{\partial T^\alpha}{\partial t} \mathbf{S}_\alpha + \nabla_\beta V^\alpha T^\beta \mathbf{S}_\alpha + V^\alpha T^\beta \mathbf{N} B_{\beta\alpha} + T^\beta \mathbf{N} \nabla_\beta C - C B_\beta^\alpha T^\beta \mathbf{S}_\alpha - V^\beta \nabla_\beta T^\alpha \mathbf{S}_\alpha - V^\beta T^\alpha \mathbf{N} B_{\beta\alpha} \\
&= \frac{\partial T^\alpha}{\partial t} \mathbf{S}_\alpha + T^\beta \nabla_\beta V^\alpha \mathbf{S}_\alpha + T^\beta \nabla_\beta C\mathbf{N} - T^\beta C B_\beta^\alpha \mathbf{S}_\alpha - V^\beta \nabla_\beta T^\alpha \mathbf{S}_\alpha \\
&= \frac{\partial T^\alpha}{\partial t} \mathbf{S}_\alpha + T^\beta \nabla_\beta V^\alpha \mathbf{S}_\alpha + T^\alpha \nabla_\alpha C\mathbf{N} - T^\beta C B_\beta^\alpha \mathbf{S}_\alpha - V^\beta \nabla_\beta T^\alpha \mathbf{S}_\alpha.
\end{aligned}$$

Ex. 340: Simply decompose \mathbf{T} with respect to the contravariant basis \mathbf{S}^α , and use the similar decomposition

$$\mathbf{V} = V^\alpha \mathbf{S}_\alpha + C\mathbf{N}.$$

Ex. 341: Note

$$\begin{aligned}
0 &= \dot{\nabla} S_{\alpha\beta} \\
&= \frac{\partial S_{\alpha\beta}}{\partial t} - V^\omega \nabla_\omega S_{\alpha\beta} - (\nabla_\alpha V^\omega - CB_\alpha^\omega) S_{\omega\beta} - (\nabla_\beta V^\omega - CB_\beta^\omega) S_{\alpha\omega} \\
&= \frac{\partial S_{\alpha\beta}}{\partial t} - \nabla_\alpha V^\omega S_{\omega\beta} + CB_\alpha^\omega S_{\omega\beta} - \nabla_\beta V^\omega S_{\alpha\omega} + CB_\beta^\omega S_{\alpha\omega} \\
&= \frac{\partial S_{\alpha\beta}}{\partial t} - \nabla_\alpha V_\beta - \nabla_\beta V_\alpha + CB_{\alpha\beta} + CB_{\beta\alpha} \\
&= \frac{\partial S_{\alpha\beta}}{\partial t} - \nabla_\alpha V_\beta - \nabla_\beta V_\alpha + 2CB_{\alpha\beta},
\end{aligned}$$

so

$$\frac{\partial S_{\alpha\beta}}{\partial t} = \nabla_\alpha V_\beta + \nabla_\beta V_\alpha - 2CB_{\alpha\beta}.$$

The contravariant case follows similarly.

Ex. 342: First, examine

$$\frac{\partial S}{\partial S^{\alpha\beta}} = S S^{\alpha\beta},$$

using the properties of the cofactor matrix. Then, compute

$$\begin{aligned}
\frac{\partial S}{\partial t} &= \frac{\partial S}{\partial S^{\alpha\beta}} \frac{\partial S^{\alpha\beta}}{\partial t} \\
&= S S^{\alpha\beta} (\nabla_\alpha V_\beta + \nabla_\beta V_\alpha - 2CB_{\alpha\beta}) \\
&= S (\nabla_\alpha V^\alpha + \nabla_\beta V^\beta - 2CB_\alpha^\alpha) \\
&= 2S (\nabla_\alpha V^\alpha - CB_\alpha^\alpha).
\end{aligned}$$

Then,

$$\begin{aligned}
\frac{\partial \sqrt{S}}{\partial t} &= \frac{1}{2\sqrt{S}} \frac{\partial S}{\partial t} \\
&= \sqrt{S} (\nabla_\alpha V^\alpha - CB_\alpha^\alpha),
\end{aligned}$$

and

$$\begin{aligned} \frac{\partial (\sqrt{S})^{-1}}{\partial t} &= -\frac{1}{(\sqrt{S})^2} \frac{\partial \sqrt{S}}{\partial t} \\ &= -\frac{1}{S} \sqrt{S} (\nabla_\alpha V^\alpha - CB_\alpha^\alpha) \\ &= -\frac{1}{\sqrt{S}} (\nabla_\alpha V^\alpha - CB_\alpha^\alpha). \end{aligned}$$

Ex. 343: Note

$$\varepsilon_{\alpha\beta} = \sqrt{S} e_{\alpha\beta},$$

so

$$\begin{aligned} \frac{\partial \varepsilon_{\alpha\beta}}{\partial t} &= \frac{\partial \sqrt{S}}{\partial t} e_{\alpha\beta} + \sqrt{S} \frac{\partial e_{\alpha\beta}}{\partial t} \\ &= \frac{\partial \sqrt{S}}{\partial t} e_{\alpha\beta}, \end{aligned}$$

since $e_{\alpha\beta}$ does not depend on t .

$$\begin{aligned} &= \sqrt{S} (\nabla_\gamma V^\gamma - CB_\gamma^\gamma) e_{\alpha\beta} \\ &= \varepsilon_{\alpha\beta} (\nabla_\gamma V^\gamma - CB_\gamma^\gamma). \end{aligned}$$

Ex. 344: Note

$$\varepsilon^{\alpha\beta} = (\sqrt{S})^{-1} e^{\alpha\beta},$$

so

$$\begin{aligned} \frac{\partial \varepsilon^{\alpha\beta}}{\partial t} &= \frac{\partial (\sqrt{S})^{-1}}{\partial t} e^{\alpha\beta} + \sqrt{S} \frac{\partial e^{\alpha\beta}}{\partial t} \\ &= \frac{\partial (\sqrt{S})^{-1}}{\partial t} e^{\alpha\beta} \\ &= -\frac{1}{\sqrt{S}} (\nabla_\gamma V^\gamma - CB_\gamma^\gamma) e^{\alpha\beta} \\ &= -\varepsilon^{\alpha\beta} (\nabla_\gamma V^\gamma - CB_\gamma^\gamma). \end{aligned}$$

Ex. 345: Simply write

$$\begin{aligned}\dot{\nabla}\varepsilon^{\alpha\beta} &= \dot{\nabla}(\varepsilon_{\gamma\delta}S^{\gamma\alpha}S^{\delta\beta}) \\ &= \dot{\nabla}\varepsilon_{\gamma\delta}S^{\gamma\alpha}S^{\delta\beta},\end{aligned}$$

by the metrinilic property,

$$= 0,$$

by the above.

Ex. 346: Use Gauss' Theorema Egregium:

$$\begin{aligned}K &= |B:| \\ &= \frac{1}{2}\varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}B_{\sigma}^{\beta},\end{aligned}$$

so

$$\begin{aligned}2\dot{\nabla}K &= \dot{\nabla}\varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}B_{\sigma}^{\beta} + \varepsilon^{\rho\sigma}\dot{\nabla}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}B_{\sigma}^{\beta} + \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}\dot{\nabla}B_{\rho}^{\alpha}B_{\sigma}^{\beta} + \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}\dot{\nabla}B_{\sigma}^{\beta} \\ &= \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}\dot{\nabla}B_{\rho}^{\alpha}B_{\sigma}^{\beta} + \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}\dot{\nabla}B_{\sigma}^{\beta},\end{aligned}$$

since the first two terms vanish,

$$\begin{aligned}&= \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}(\nabla^{\alpha}\nabla_{\rho}C + CB_{\gamma}^{\alpha}B_{\rho}^{\gamma})B_{\sigma}^{\beta} + \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}(\nabla^{\beta}\nabla_{\sigma}C + CB_{\gamma}^{\beta}B_{\sigma}^{\gamma}) \\ &= \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\rho}C + C\varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\rho}^{\gamma} + \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}\nabla^{\beta}\nabla_{\sigma}C + C\varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}B_{\gamma}^{\beta}B_{\sigma}^{\gamma} \\ &= \delta_{\alpha\beta}^{\rho\sigma}(B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\rho}C + B_{\rho}^{\alpha}\nabla^{\beta}\nabla_{\sigma}C + B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\rho}^{\gamma}C + B_{\rho}^{\alpha}B_{\gamma}^{\beta}B_{\sigma}^{\gamma}C) \\ &= (\delta_{\alpha}^{\rho}\delta_{\beta}^{\sigma} - \delta_{\beta}^{\rho}\delta_{\alpha}^{\sigma})B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\rho}C + B_{\rho}^{\alpha}\nabla^{\beta}\nabla_{\sigma}C + B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\rho}^{\gamma}C + B_{\rho}^{\alpha}B_{\gamma}^{\beta}B_{\sigma}^{\gamma}C \\ &= \delta_{\alpha}^{\rho}\delta_{\beta}^{\sigma}B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\rho}C + \delta_{\alpha}^{\rho}\delta_{\beta}^{\sigma}B_{\rho}^{\alpha}\nabla^{\beta}\nabla_{\sigma}C + \delta_{\alpha}^{\rho}\delta_{\beta}^{\sigma}B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\rho}^{\gamma}C + \delta_{\alpha}^{\rho}\delta_{\beta}^{\sigma}B_{\rho}^{\alpha}B_{\gamma}^{\beta}B_{\sigma}^{\gamma}C \\ &\quad - (\delta_{\beta}^{\rho}\delta_{\alpha}^{\sigma}B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\rho}C + \delta_{\beta}^{\rho}\delta_{\alpha}^{\sigma}B_{\rho}^{\alpha}\nabla^{\beta}\nabla_{\sigma}C + \delta_{\beta}^{\rho}\delta_{\alpha}^{\sigma}B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\rho}^{\gamma}C + \delta_{\beta}^{\rho}\delta_{\alpha}^{\sigma}B_{\rho}^{\alpha}B_{\gamma}^{\beta}B_{\sigma}^{\gamma}C) \\ &= B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\alpha}C + B_{\alpha}^{\alpha}\nabla^{\sigma}\nabla_{\sigma}C + B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\alpha}^{\gamma}C + B_{\alpha}^{\alpha}B_{\gamma}^{\sigma}B_{\sigma}^{\gamma}C \\ &\quad - (B_{\sigma}^{\rho}\nabla^{\sigma}\nabla_{\rho}C + B_{\rho}^{\rho}\nabla^{\rho}\nabla_{\sigma}C + B_{\sigma}^{\rho}B_{\gamma}^{\sigma}B_{\rho}^{\gamma}C + B_{\rho}^{\sigma}B_{\gamma}^{\rho}B_{\sigma}^{\gamma}C) \\ &= 2B_{\alpha}^{\alpha}\nabla^{\beta}\nabla_{\beta}C - 2B_{\beta}^{\beta}\nabla^{\alpha}\nabla_{\alpha}C + 2B_{\alpha}^{\alpha}B_{\gamma}^{\beta}B_{\beta}^{\gamma}C - 2B_{\beta}^{\beta}B_{\gamma}^{\alpha}B_{\alpha}^{\gamma}C \\ &= 2(B_{\alpha}^{\alpha}\nabla^{\beta}\nabla_{\beta}C - B_{\beta}^{\beta}\nabla^{\alpha}\nabla_{\alpha}C + (B_{\alpha}^{\alpha}B_{\gamma}^{\beta}B_{\beta}^{\gamma} - B_{\beta}^{\beta}B_{\gamma}^{\alpha}B_{\alpha}^{\gamma})C) \\ &= 2(B_{\alpha}^{\alpha}\nabla^{\beta}\nabla_{\beta}C - B_{\beta}^{\beta}\nabla^{\alpha}\nabla_{\alpha}C + B_{\alpha}^{\alpha}KC),\end{aligned}$$

which gives us the desired result [Note: I believe the last equality follows from Gauss' Theorema Egregium].

Chapter 14

Chapter 17

Ex. 347: Note that u is an invariant with respect to ambient indices, and thus $\nabla_i u = \frac{\partial u}{\partial Z^i}$. Write

$$\begin{aligned}\frac{\partial}{\partial t} \nabla_i u &= \frac{\partial}{\partial t} \frac{\partial u}{\partial Z^i} \\ &= \frac{\partial}{\partial Z^i} \frac{\partial u}{\partial t} \\ &= \nabla_i \frac{\partial u}{\partial t},\end{aligned}$$

under smoothness assumptions (hence the partials commute), and since $\frac{\partial u}{\partial t}$ is an invariant.

Ex. 348: First, compute, given polar coordinates

$$\begin{aligned}\nabla_i u &= \frac{\partial u}{\partial Z^i} \\ &= \begin{bmatrix} \frac{\partial}{\partial r} \left(\frac{J_0(\rho r)}{\sqrt{\pi} J_1(\rho)} \right) \\ \frac{\partial}{\partial \theta} \left(\frac{J_0(\rho r)}{\sqrt{\pi} J_1(\rho)} \right) \end{bmatrix} \\ &= \begin{bmatrix} \frac{-\rho J_1(\rho r)}{\sqrt{\pi} J_1(\rho)} \\ 0 \end{bmatrix}\end{aligned}$$

Now, since for polar coordinates,

$$Z^{ij} = \begin{bmatrix} 1 & 0 \\ 0 & r^{-2} \end{bmatrix},$$

so

$$\begin{aligned}\nabla^i u &= Z^{ij} \nabla_j u \\ &= \begin{bmatrix} 1 & 0 \\ 0 & r^{-2} \end{bmatrix} \begin{bmatrix} \frac{-\rho J_1(\rho r)}{\sqrt{\pi} J_1(\rho)} \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} \frac{-\rho J_1(\rho r)}{\sqrt{\pi} J_1(\rho)} \\ 0 \end{bmatrix}.\end{aligned}$$

thus,

$$\nabla_i u \nabla^i u = \frac{-\rho^2 J_1(\rho r)^2}{\pi J_1(\rho)^2}.$$

Now, at $t = 0$, our surface yields $r = 1$, so

$$\nabla_i u \nabla^i u = \frac{-\rho^2}{\pi}$$

Next, compute C for our surface evolution. Consider, in Cartesian coordinates,

$$\begin{aligned}V^i &= \begin{bmatrix} \frac{\partial x}{\partial t} \\ \frac{\partial y}{\partial t} \end{bmatrix} \\ &= \begin{bmatrix} a \cos \alpha \\ b \sin \alpha \end{bmatrix}\end{aligned}$$

With respect to the Cartesian basis,

$$\mathbf{S}_\alpha = -(1 + at) \sin \alpha \mathbf{i} + (1 + bt) \cos \alpha \mathbf{j}$$

$$N_i = \frac{1}{\sqrt{(1 + at)^2 \cos^2 \alpha + (1 + bt)^2 \sin^2 \alpha}} \begin{bmatrix} (1 + bt) \cos \alpha \\ (1 + at) \sin \alpha \end{bmatrix},$$

at $t = 0$,

$$N_i = \begin{bmatrix} \cos \alpha \\ \sin \alpha \end{bmatrix}$$

$$\begin{aligned}C &= V^i N_i \\ &= a \cos^2 \alpha + b \sin^2 \alpha;\end{aligned}$$

thus, by the Hadamard formula,

$$\begin{aligned}
 \lambda_1 &= \int_0^{2\pi} (a \cos^2 \alpha + b \sin^2 \alpha) \left(\frac{-\rho^2}{\pi} \right) d\alpha \\
 &= \frac{-\rho^2}{\pi} \int_0^{2\pi} a \cos^2 \alpha + b \sin^2 \alpha d\alpha \\
 &= \frac{-\rho^2}{\pi} \int_0^{2\pi} a (\cos^2 \alpha) + b (1 - \cos^2 \alpha) d\alpha \\
 &= \frac{-\rho^2}{\pi} \int_0^{2\pi} a \cos^2 \alpha + b \cos^2 \alpha d\alpha - 2b\rho^2 \\
 &= \frac{-\rho^2}{\pi} (a + b) \int_0^{2\pi} \cos^2 \alpha d\alpha - 2b\rho^2 \\
 &= \frac{-\rho^2}{\pi} (a + b) \left[\frac{\alpha}{2} + \frac{1}{4} \sin 2\alpha \right]_0^{2\pi} - 2b\rho^2 \\
 &= \frac{-\rho^2}{\pi} (a + b) \pi - 2b\rho^2 \\
 &= -\rho^2 (a + b) - 2b\rho^2 \\
 &= -\rho^2 (a + b).
 \end{aligned}$$

Since $\lambda = \rho^2$, we have the desired result.

Ex. 349: [Not sure]

Ex. 350: Want to show:

$$\lambda_1 = \int_S (u_1 N_i \nabla^i u - N_i \nabla^i u_1) dS.$$

Dirichlet:

$$\lambda_1 = - \int_S C \nabla_i u \nabla^i u dS$$

Neumann:

$$\lambda_1 =$$

Ex. 354: We have

$$\begin{aligned}
 \rho \left(\dot{\nabla} C + 2V^\alpha \nabla_\alpha C + B_{\alpha\beta} V^\alpha V^\beta \right) &= \sigma B_\alpha^\alpha \\
 \dot{\nabla} V^\alpha + V^\beta \nabla_\beta V^\alpha - C \nabla^\alpha C - C V^\beta B_\beta^\alpha &= 0.
 \end{aligned}$$

Write

$$V^\alpha = V^i Z_i^\alpha$$

and

$$C = V^i N_i,$$

Begin with the second, and contract with \mathbf{S}_α :

$$\begin{aligned} \dot{\nabla} V^\alpha \mathbf{S}_\alpha + V^\beta \nabla_\beta V^\alpha \mathbf{S}_\alpha - C \nabla^\alpha C \mathbf{S}_\alpha - C V^\beta B_\beta^\alpha \mathbf{S}_\alpha &= 0 \\ \dot{\nabla} (V^\alpha \mathbf{S}_\alpha) - V^\alpha \dot{\nabla} \mathbf{S}_\alpha + V^\beta \nabla_\beta (V^\alpha \mathbf{S}_\alpha) - V^\beta V^\alpha \nabla_\beta \mathbf{S}_\alpha - C \nabla^\alpha C \mathbf{S}_\alpha - C V^\beta B_\beta^\alpha \mathbf{S}_\alpha &= 0 \\ \dot{\nabla} (V^\alpha \mathbf{S}_\alpha) - V^\alpha \mathbf{N} \nabla_\alpha C + V^\beta \nabla_\beta (V^\alpha \mathbf{S}_\alpha) - V^\beta V^\alpha B_{\alpha\beta} \mathbf{N} - C \nabla^\alpha C \mathbf{S}_\alpha - C V^\beta B_\beta^\alpha \mathbf{S}_\alpha &= 0. \end{aligned}$$

Then, manipulate the first:

$$\dot{\nabla} C + 2V^\alpha \nabla_\alpha C + B_{\alpha\beta} V^\alpha V^\beta = \frac{\sigma}{\rho} B_\alpha^\alpha,$$

and multiply by \mathbf{N} :

$$\begin{aligned} \dot{\nabla} C \mathbf{N} + 2V^\alpha \nabla_\alpha C \mathbf{N} + B_{\alpha\beta} V^\alpha V^\beta \mathbf{N} &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\ \dot{\nabla} (C \mathbf{N}) - C \dot{\nabla} \mathbf{N} + 2V^\alpha \nabla_\alpha C \mathbf{N} + B_{\alpha\beta} V^\alpha V^\beta \mathbf{N} &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\ \dot{\nabla} (C \mathbf{N}) - C (-\mathbf{S}_\alpha \nabla^\alpha C) + 2V^\alpha \nabla_\alpha C \mathbf{N} + B_{\alpha\beta} V^\alpha V^\beta \mathbf{N} &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\ \dot{\nabla} (C \mathbf{N}) + C \mathbf{S}_\alpha \nabla^\alpha C + 2V^\alpha \nabla_\alpha C \mathbf{N} + B_{\alpha\beta} V^\alpha V^\beta \mathbf{N} &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\ \dot{\nabla} (C \mathbf{N}) + 2V^\alpha \nabla_\alpha C \mathbf{N} + V^\alpha V^\beta B_{\alpha\beta} \mathbf{N} + C \nabla^\alpha C \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N}. \end{aligned}$$

Now, add the results of both manipulations to each other:

$$\begin{aligned}
\dot{\nabla}(V^\alpha \mathbf{S}_\alpha) + \dot{\nabla}(C\mathbf{N}) + V^\alpha \nabla_\alpha C\mathbf{N} + V^\beta \nabla_\beta (V^\alpha \mathbf{S}_\alpha) - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha C\mathbf{N} + V^\beta \nabla_\beta (V^\alpha \mathbf{S}_\alpha) - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha (C\mathbf{N}) - V^\alpha C \nabla_\alpha \mathbf{N} + V^\beta \nabla_\beta (V^\alpha \mathbf{S}_\alpha) - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} - V^\alpha C \nabla_\alpha \mathbf{N} - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} - V^\alpha C \nabla_\alpha (N^i \mathbf{Z}_i) - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} - V^\alpha C \nabla_\alpha N^i \mathbf{Z}_i - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \quad [\text{note the metrinilic property}] \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} + V^\alpha C Z_\beta^i B_\alpha^\beta \mathbf{Z}_i - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} + V^\alpha C B_\alpha^\beta Z_\beta^i \mathbf{Z}_i - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} + CV^\alpha B_\alpha^\beta \mathbf{S}_\beta - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N}
\end{aligned}$$